# A Multi-Criteria Message Forwarding Architecture for Wireless Sensor Networks

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*Abstract*—Wireless Sensor Networks (WSN) comprise a fast-developing research area with a vast spectrum of applications. A WSN design is influenced by many factors such as transmission errors, network topology and power consumption. Consequently, developing a WSN application introduces several implementation challenges. In this paper, we describe a multi-criteria architecture in order to achieve energy-aware and consistent message forwarding over a WSN. Using the proposed architecture a directed acyclic graph (DAG) is formed throughout the WSN. Such DAG is used for multi-source data aggregation to a single sink. Intermediate nodes evaluate their energy reserve and induced error and decide whether message retransmission is needed. A sink is necessary in order to collect, process and probably forward these data to a more sophisticated system for further processing. The discussed architecture is developed using TinyOS, an operating system designed for WSN nodes, and nesC, an extension of C. Finally evaluation results are presented.

#### I. INTRODUCTION

The recent advances in highly integrated digital electronics and wireless communication technology have led to the development of low cost, large-scale and low power sensor networks. Such networks are composed by a large number of micro-sensor nodes, which are equipped with communication and minimal computation capabilities. Sensor nodes are able to monitor a wide variety of physical parameters such as temperature, humidity, light, radiation, noise, etc., and report them using ad hoc network protocols and algorithms. The capabilities of sensor networks have significant impact on numerous application areas with varying requirements and characteristics in our life such as military control and communications; environment forecast systems, forest fire detection, medical treatment, as well as, traffic control and security. In the future, sensors collecting data will become really ubiquitous i.e., be found everywhere; in machines, buildings, even on our clothes.

The constraints of sensor nodes render the design and management of a WSN very challenging. Firstly, sensors have limited resources such as battery lifetime (varying from hours to several years depending on the application), computational power, data storage and communication bandwidth. Hence, it is important for a WSN architecture to take into consideration the network topology, power consumption, data rate and fault tolerance in order to avoid significant energy consumption and improve bandwidth utilization [2].

## II. PRIOR AND RELATED WORK

In the recent years, numerous articles have been published describing new algorithms, routing protocols and architectures aiming at WSN lifetime maximization, through energy awareness.

Already proposed routing techniques ([1], [3]) for WSNs aiming at energy conservation, employ routing tactics such as data aggregation, in-network processing, clustering, different node role assignment and datacentric methods. There are several ways of categorizing these protocols and algorithms. For example, they can be discriminated depending on the network structure to Flat Networks Routing (Data-centric routing [1]), Hierarchical Networks Routing and Location-based Routing [3]. Intanagonwiwat et al. [9] proposed *Directed Diffusion* a data-centric (i.e. all communication is for named-data) and application-aware paradigm aiming at avoiding unnecessary operations of network layer routing in order to save energy by selecting empirically good paths and by caching and processing data within the network. Yao and Gehrke [17] proposed another data-centric protocol, namely, *COUGAR*, for an architecture which treats the network as a huge distributed database system. *Energy Aware Routing*, a protocol proposed by Shah and Rabaey [13], although similar to Directed Diffusion, it differs in the sense that it uses occasionally sub-optimal paths to obtain energy benefits. This protocol can achieve longer network lifetime as energy is dissipated more equally among all nodes. *TEEN and APTEEN*, two hierarchical routing protocols are proposed by Manjeshwar and Agarwal [12]. TEEN (Threshold-sensitive Energy Efficient sensor Network protocol) and APTEEN (Adaptive Periodic Threshold-sensitive Energy Efficient sensor Network protocol) are suitable for time-critical applications. In both protocols the key factor is the measured attribute's value. The additional feature of APTEEN is the capability of changing the periodicity and the parameters of TEEN according to user and application needs. The concept of generic, utility-based decision making in WSN is described in [5], where Byers and Nasser try to quantify the cost of each action performed by a sensor, by adopting heuristic assessments. Apart from routing protocols, PowerTOSSIM [14], a WSN simulation tool has been developed. PowerTOSSIM provides an accurate, per-node estimate of power consumption. PowerTOSSIM is an extension of TOSSIM ([10]-[11], [15]), the event-driven simulation for TinyOS [16] applications.

# **III. SYSTEM ARCHITECTURE**

The considered system architecture relies on three types/roles of sensor nodes:

- Sensing nodes (or sources) that sense certain physical parameters and transmit the relevant information towards other nodes in the infrastructure.
- Communication (or relay) nodes that, wirelessly, receive readings from sensing nodes (or other communication nodes) and relay them upstream towards the final recipient of such information. Communication nodes come into play whenever direct network connectivity is not feasible (due to limited resources such as power in the radio interface) and bridge the, otherwise inaccessible, nodes.
- Sink nodes that are the final recipients of the sensed information. Sink nodes are typically connected to conventional computing equipment for complex processing of the accumulated readings. Alternatively, sink nodes may be attached to another, more elaborate network topology (e.g., a WLAN or a fixed network) for further forwarding.

The aforementioned nodes form a directed acyclic graph, a rooted tree structure. The root of the tree is the sink node (exactly one node), all other nodes may assume the role of sensing nodes (at least one node is required), or communication nodes.



Through a sequence of nodes a data flow (DF) associating a certain leaf node with the root node is being served. For example, a data flow is SN4  $\rightarrow$  CN4  $\rightarrow$  CN1  $\rightarrow$  S. Every communication node reserves memory and communication resources for each DF, while sense nodes reserve resources only for their own DF. The architecture can be generalized in order to support a forest-like topology with multiple sinks. It is essential to maintain the concept of the DFs, that is, each node forwards all of its messages to the selected sink following an already established path. The core of the proposed architecture is an embedded control

mechanism (called Transmission Control Mechanism, TCM) which optimizes the energy consumption within the WSN. Every sensing and communication node uses TCM in order to determine the utility of each upstream transmission. The TCM takes certain criteria into account and may decide not to propagate the considered message upstream. The peer TCM (i.e., the TCM found in the next node upstream) should be able to conceive this situation and react accordingly. Below, we describe briefly the criteria considered by the TCM for assessing the utility of message transmission, as well as the main components of the mechanism.

The considered mechanism implements Heart-Beat (HB) messages in order to determine whether a node is alive. These messages contain also sensor readings and they are transmitted unconditionally from every sensing node. Communication nodes forward HB messages unconditionally. Each TCM implements an extrapolation scheme on the received sensor readings. The monitored physical parameter is assumed to vary smoothly over time (e.g., as a polynomial function of time). Whenever a new measurement is presented to the TCM, the latter entity determines whether the peer TCM (in the upstream path) can reproduce the new value without, explicitly, receiving it. To achieve this objective, an a-priori agreed extrapolation scheme<sup>1</sup> (common throughout the WSN) is engaged. The local TCM calculates an extrapolated value (EV) for the sensed physical variable using previous measurements. The EV is compared against the actual, new measurement and the relevant error is calculated. The estimated error level will contribute to the determination of the message transmission utility. If the message is not transmitted upstream, then the peer TCM will perform the same extrapolation calculation and consider the (locally estimated) EV as the new received measurement. The receiving end performs this calculation when a timeout event occurs. Each TCM has a timer, which is restarted upon reception of a message or a timeout event. A timeout period is application specific. The mandatory forwarding of HB messages avoids an unconstrained error increase spatially and temporally. This scheme is applied for all the DFs handled by the considered node.

Furthermore, data aggregation is performed when a communication node is required to propagate values from more than one DF. The new message consists of the values that TCM designated as necessary transmissions. Using this aggregation mechanism, the data received and/or extrapolated from a node N, form a single message which is forwarded upstream, towards the sink.

### A. Discussion on the Utility function design

Let  $U_k$  denote the utility of the sensor node k with respect to the transmission of a new (not HB) message upstream.  $U_k$  is a function of time, the current node energy reserve and the received measurement for a certain DF.  $U_k$  is calculated as follows:

$$U_{k} = w_{1} \cdot U_{energy}^{k} + w_{2} \cdot U_{error}^{k} + (1 - \sum_{i=1,2} w_{i}) \cdot U_{time}^{k}, \quad \sum_{i=1,2} w_{i} \le 1 \qquad \qquad U_{k} = 1, \text{ for all HB messages}$$

The weights  $w_i$  are application specific. The three utility components, for a given sensor node k, are calculated as follows:

<sup>1</sup> An appropriate extrapolation scheme is chosen according to the nature of the sensed data.

where *E* denotes the current energy reserve of the considered node,  $E_{max}$  is the maximum energy quantity that can be accumulated in the node, *err* denotes the error induced in the measurement sequence by the extrapolation scheme that is globally adopted throughout the WSN topology, *err<sub>threshold</sub>* is the maximum tolerable deviation that can be induced in the collected readings,  $\Delta T$  is the HB interval and  $\Delta t$  is the time that elapsed from the previous HB message transmission. The time component is mainly used in order to reduce the possibility of transmitting a message right after or right before the transmission of HB message.

The three utility components provide a full synopsis of the current status of the WSN, i.e., the energy component reflects the energy status of the node, the error component reflects the variance within a DF, and the time component reflects the clocking status of the entire topology.

Whenever the utility for a given sensor node k drops below an application specific threshold g, the sensor node halts upstream message re-transmission. Hence, the control condition for intelligent, energy aware message forwarding is:

$$U_k \ge g > 0$$

Threshold parameter g represents the trade-off between the two conflicting goals: energy conservation and quality of the gathered data. Taking into consideration the value of g, each node k achieves a balance between the energy cost of a message's forwarding and the utility of this transmission with respect to its usefulness to the specific application.

## B. Node Finite State Machine

An important aspect of the proposed architecture is the step-based network synchronization. Each node follows a predefined duty cycle. During each duty cycle, a node changes states according to the operation being performed. This scheme ensures that each node will be synchronized with its neighbors. Synchronization is crucial in order to achieve reliable message forwarding, as well as, energy conservation. Having knowledge of its neighbors' duty cycle, a node's state can be changed to sleep mode in order to reduce energy consumption. During sleep mode, the node stops any computation and communication with its neighbors.



Fig. 3. Node's duty cycle.

As shown in the Finite State Machine presented, a communication node firstly listens for incoming messages. After the reception of a message (or after a timeout), the node computes the utility of the transmission of the values received (or extrapolated). Based on this computation, TCM decides whether an upstream message is going to be forwarded. During the remaining period of the duty cycle, the node stands by (in sleep mode). It is estimated that a node remains in sleep mode for over 75% of its lifetime.

# **IV. PERFORMANCE ASSESSMENT**

TinyOS, an event-driven operating system specifically designed for sensor networks, has been used to develop several parts of the proposed multi-criteria message forwarding scheme. TinyOS has become a

popular environment for experimenting with and developing sensor network applications. A TinyOS program is a graph of components (independent entities). It is a component-based runtime environment which has been developed using the nesC language. NesC ([6]-[7], [18]) is an extension of C that provides support for the TinyOS component and concurrency model and all the low-level features necessary for accessing hardware.

We carried out several experiments using WSN topologies having several source nodes but a single sink node. Every source node initiates a data-flow towards the sink which is routed through the communication nodes. During the WSN initialization phase each node dynamically acquires an identifier (ID), knows its role (communication node/source node) and neighbors (children, parent). Each message comprises a 56-bit-header and a variable sized body, depending on the forwarding decisions. Based on the role assigned to each node, only the needed modules are enabled, following a duty cycle. The duty-cycle aids in synchronizing communication and organizes the sequence of scheduled events, in order to increase energy efficiency. The simulation results are based on 15-node and 31-node DAG network topologies (full binary trees).



Fig. 5. Node energy gain

Fig. 4. Data and approximations (DFs from numbered sensing nodes – evaluated at the sink)

Another very important design parameter is the node energy model. We adopted the Mica2 energy consumption model. Specifically, the execution of a single CPU instruction requires 4 nJ, the CPU while staying in idle mode consumes 9.6 mJ/s and in stand-by mode consumes 0.33 mJ/s. We also take into account the transition energy cost between different states. Finally, the energy cost of transmitting and receiving messages is measured per bit. Specifically, the transmission of a message costs 720 nJ/bit and the reception of a message 110 nJ/bit. These estimates are mean values of the lower and upper bound of transmission and reception costs.

### V. SIMULATION RESULTS

The conducted simulations show the effect of the proposed architecture. Numerous simulations using different parameter values, shows that effective energy conservation strongly depends on the succession of sensor states and WSN synchronization. Another very important issue when designing such a scheme is the fact that each node continuously consumes energy even in idle or in stand-by mode. As a result switching-off the radio component and limiting the listening period prolongs the lifetime of the WSN. Based on the simulation results the conditional forwarding of MCMFA eliminates unnecessary transmissions, thus reducing the transmitted messages for about 60% - 70%. The proposed scheme, by combining conditional transmission, data aggregation and network synchronization succeeds significant energy savings. The gain climbs up to 10%, which is lower than the percentage of the messages which were not transmitted. This can be explained by the fact that the CPU of a mote consumes energy in the idle and standby modes.

# **VI. CONCLUSIONS - FUTURE WORK**

In this paper we have presented a multi-criteria message forwarding architecture for WSN. The goal of the proposed architecture is to reduce energy consumption by avoiding unnecessary message transmissions. Energy awareness in WSNs is an emerging research area and the protocols presented in the relevant literature are focused on determining low-cost paths within the existing network. On the other hand, we try to avoid in-network transmissions if the induced error is acceptable. A combination of both techniques would lead to better results ensuring the prolongation of the lifetime of the WSN. Two protocols that could be combined with the proposed architecture are Energy Aware Routing and TEEN.

We believe that it is very important to evaluate the responsiveness of our architecture to increased node mobility. Node mobility is a prerequisite for some WSN applications, thus, resulting to even more demanding energy awareness and routing protocols. Moreover, we plan to implement intelligent data aggregation schemes to be embedded in the communication nodes. Such schemes may significantly reduce the upstream communication requirements by merging DF at a certain level within the WSN hierarchy. The applicability of the aggregation model is closely related to the nature of the monitored physical variables, the spatial WSN node distribution and temporal correlation of upstream messages. Finally, we intend to compare the presented scheme with already implemented protocols (i.e. Directed Diffusion).

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