

Pairwise Additive Spanners

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(Joint work with T. Kavitha)

TIFR Mumbai \rightarrow Penn State

Theory Seminar

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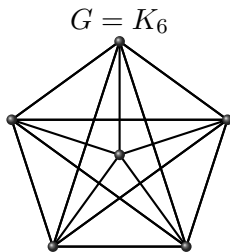
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Graph Spanners

Peleg and Schaffer 1989

$H = (V, E')$ is a spanner of $G = (V, E)$, an **undirected unweighted** graph, if

- H is a **subgraph** of G ($E' \subseteq E$)
- $d_H(u, v) \approx d_G(u, v)$ for all $u, v \in V(G)$

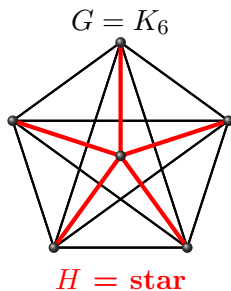


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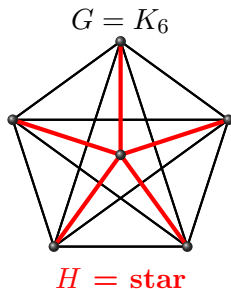


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For all $u, v \in V$

- $d_H(u, v) \leq 2 \cdot d_G(u, v)$
(multiplicative)

- $d_H(u, v) \leq d_G(u, v) + 1$
(additive)

Why Spanners?

- Fewer edges than the original graph, but roughly preserve shortest distances

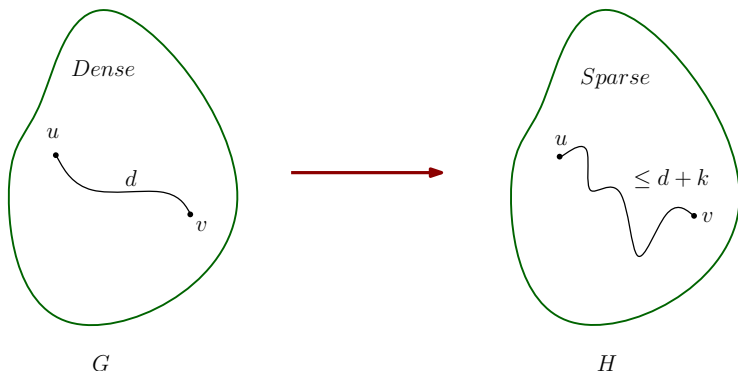
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- Space Efficient Routing Schemes
 - Thorup and Zwick (2001)
 - Near Shortest Path Algorithms
 - Elkin (2001)
 - Approximate Distance Oracles
 - Patrascu and Roditty (2010)

Additive Spanners



Liestman and Shermer (1991)

H is a $+k$ -spanner of G if $d_H(u, v) \leq d_G(u, v) + k$ for all $u, v \in V$.

Bounds for Additive Spanners

Upper Bounds

- **+2-spanner** with $O(n^{1.5})$ edges
 - Dor, Halperin and Zwick (2000, $\tilde{O}(n^{1.5})$ edges)
 - Elkin and Peleg (2001, $O(n^{1.5})$ edges)
- **+4-spanner** with $\tilde{O}(n^{1.4})$ edges
 - Chechik (2013)
- **+6-spanner** with $O(n^{1.33})$ edges
 - Baswana, Kavitha, Mehlhorn, Pettie (2005)
- **$+\tilde{O}(n^{\frac{1-3\delta}{2}})$ -spanner** with $\tilde{O}(n^{1+\delta})$ edges for $\delta \in [\frac{3}{17}, \frac{1}{3})$
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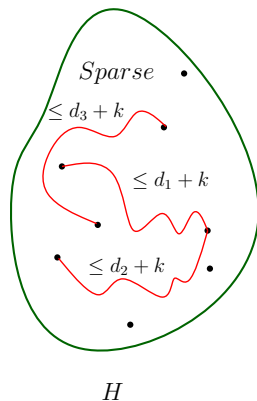
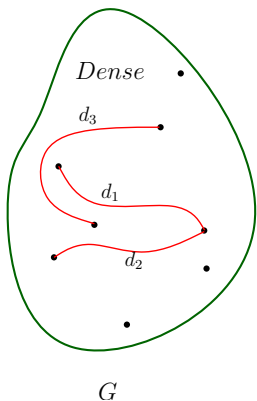
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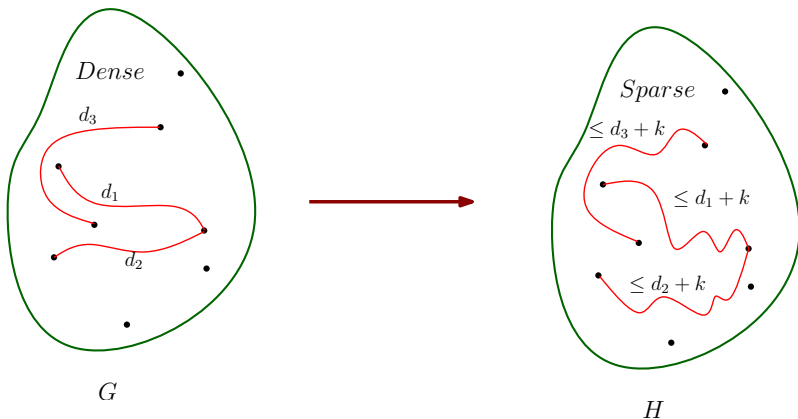
Lower Bounds

- $\Omega(n^{1+\frac{1}{k}})$ edges necessary, for **$+(2k - 1)$** -spanners
 - Woodruff (2006)

Our Focus: Pairwise Additive Spanners



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Cygan, Grandoni, Kavitha(2013)

A generalization of spanners: not all pairs in $V \times V$ are important here, only certain pairs are critical.

Pairwise Additive Spanners : Two Variants

\mathcal{P} -spanners[Cygan, Grandoni, Kavitha (2013)]

- Set of pairs explicitly given as $\mathcal{P} \subseteq V \times V$.

D -spanners[Kavitha, V. (2013)]

- Set of pairs specified implicitly using a number D
- $\mathcal{P} = \{(u, v) : d(u, v) \geq D\}$

Our Results [Kavitha, V. (2013)]

There exist deterministic polynomial time algorithms, which given any graph $G = (V, E)$ on n vertices, construct:

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- $+4k$ D -spanner with $\tilde{O}(n^{1.5}/D^{k/(2k+2)})$ edges for any integer $k \geq 1$

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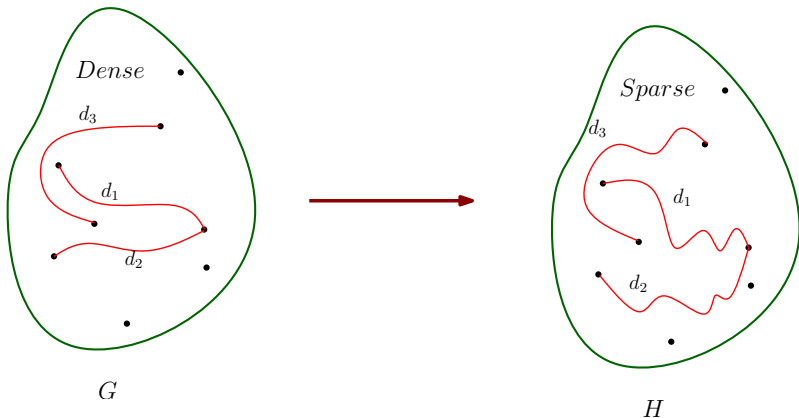
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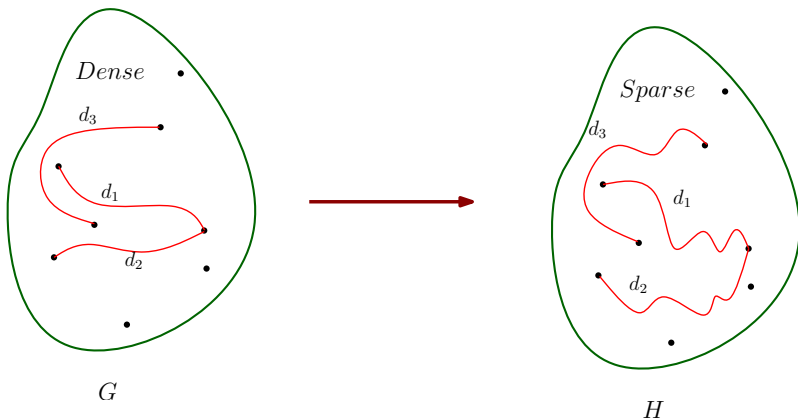
\mathcal{P} -preservers



Coppersmith and Elkin (2006)

H is a \mathcal{P} -preserver of G if $d_H(u, v) = d_G(u, v)$ whenever $(u, v) \in \mathcal{P}$, where $\mathcal{P} \subseteq V \times V$.

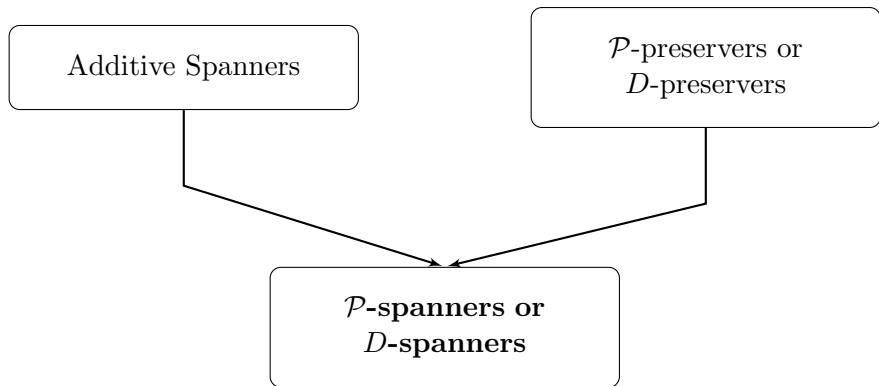
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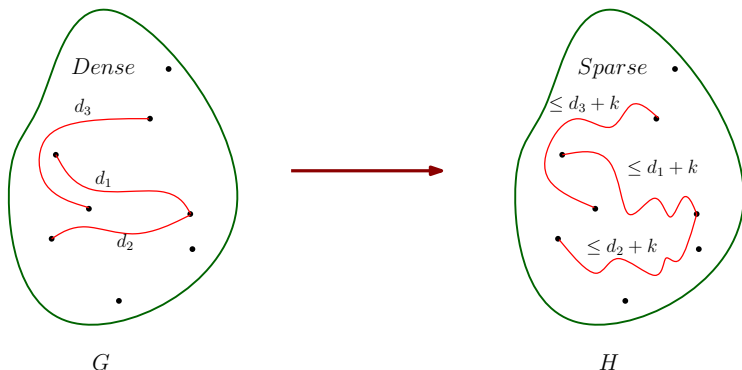
Bollobás, Coppersmith and Elkin (2005)

H is a D -preserver of G if $d_H(u, v) = d_G(u, v)$ whenever $d_G(u, v) \geq D$

- D -preserver with $O(n^2/D)$ edges (**This is tight.**)
 - Bollobás, Coppersmith and Elkin (2005)
- \mathcal{P} -preserver with $O(\min(n\sqrt{|\mathcal{P}|}, |\mathcal{P}|\sqrt{n}))$ edges
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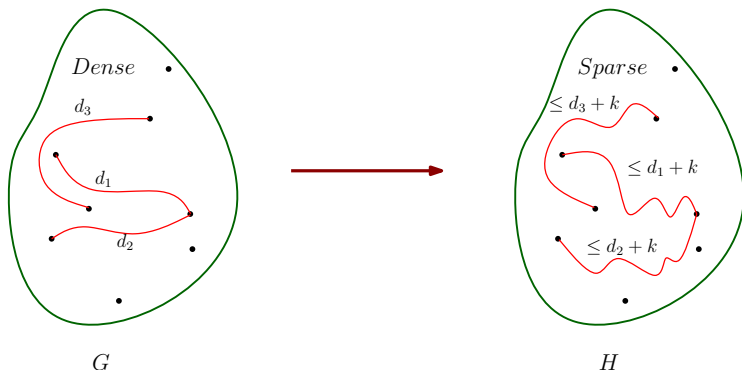
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 - **+4 log n** D -spanner with $\tilde{O}(n\sqrt{n/D})$ edges

What we are going to prove..

Theorem

There is a polynomial time algorithm which, given any graph $G = (V, E)$ on n nodes and any $\mathcal{P} \subseteq V \times V$, computes a $+2$ \mathcal{P} -spanner of G with $\tilde{O}(n|\mathcal{P}|^{1/3})$ edges.

+2 \mathcal{P} -spanner algorithm

Input

- Graph $G = (V, E)$ on n vertices
- Set $\mathcal{P} \subseteq V \times V$ of pairs to be approximated

Output

- $H = (V, E')$
- H is a +2 \mathcal{P} -spanner of G
- H has $\tilde{O}(n|\mathcal{P}|^{1/3})$ edges

Main Algorithmic Techniques Used

- **Clustering**
 - [EP01,BKMP05,C13,CGK13]

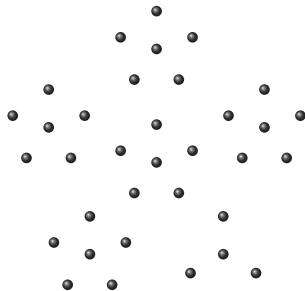
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- **Clustering**
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- **Shortest Paths Tree Addition**
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- **Path Buying**
 - [BKMP05,C13,CGK13]

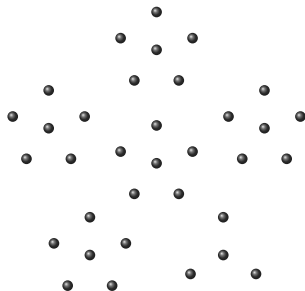
Construction : Initialization



- Initialize H to the empty graph.

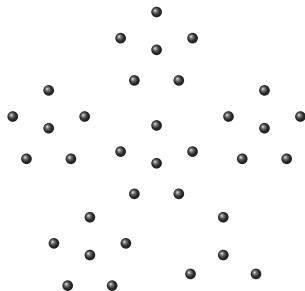
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- Mark all nodes as **unclustered**



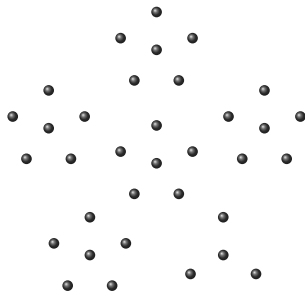
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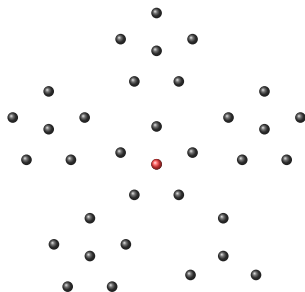
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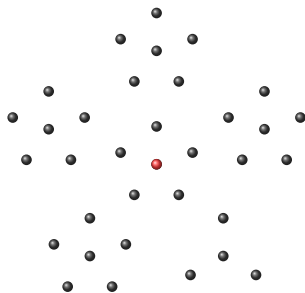


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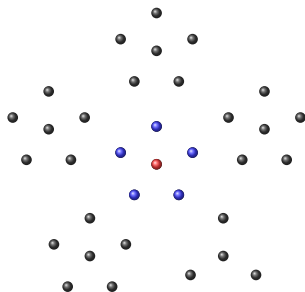


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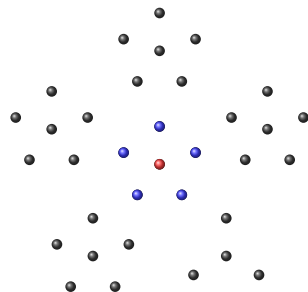


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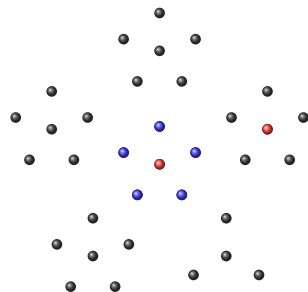


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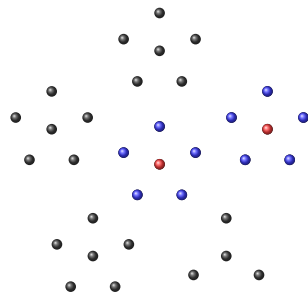
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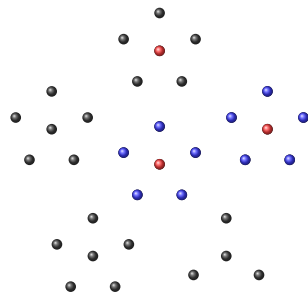
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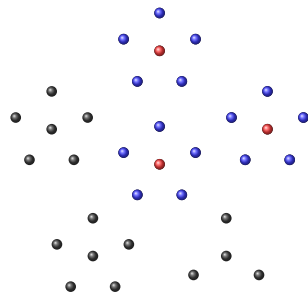
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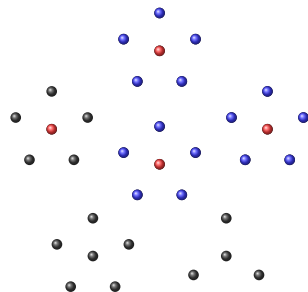
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Construction : Clustering



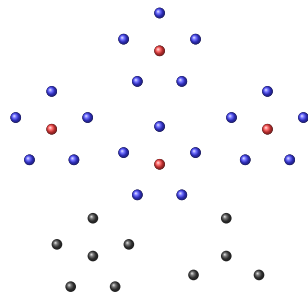
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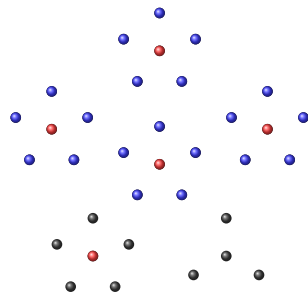
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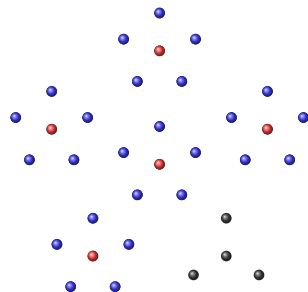
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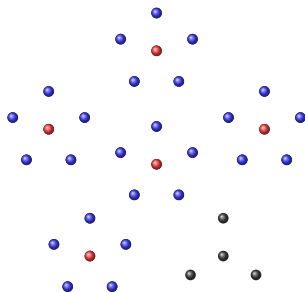
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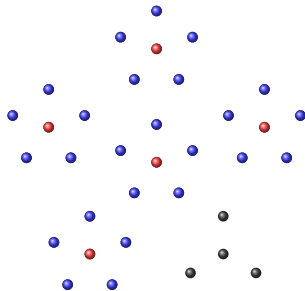
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- Stop when there are no potential **cluster centers**
- Some nodes remain **unclustered**.

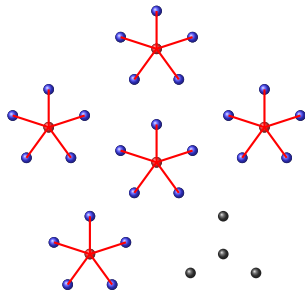
Construction : Clustering

Adding edges



Adding edges

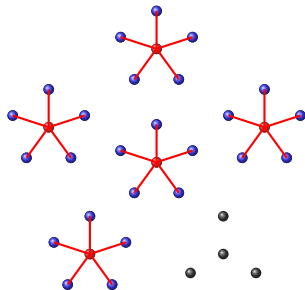
- Add the edges between **cluster centers** and nodes in their cluster to H .



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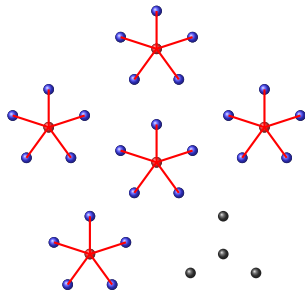
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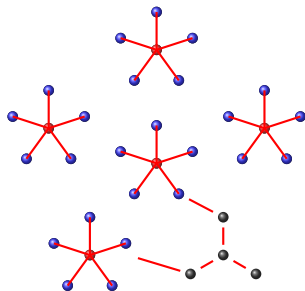
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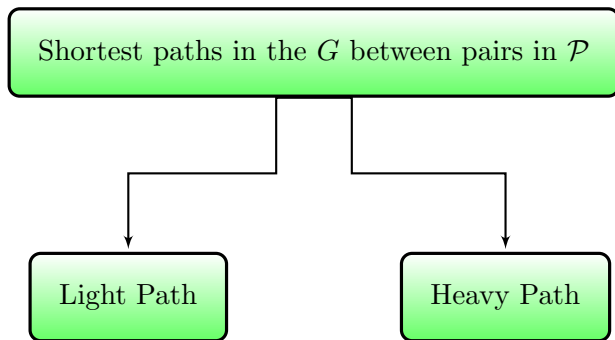
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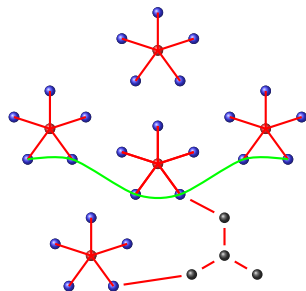
After Clustering



$< n \log n / h^2$
clustered nodes

$\geq n \log n / h^2$
clustered nodes

Construction : Shortest Paths Tree Addition

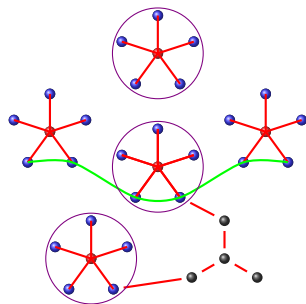


A heavy path intersects *many*
($\geq n \log n / 3h^2$) clusters



\exists a collection of $O(h)$ clusters \mathcal{C}
such that every heavy path
intersects some cluster in \mathcal{C} .

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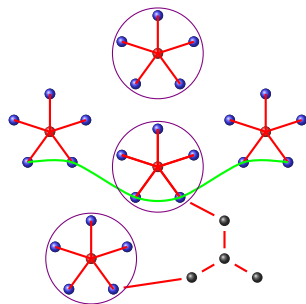


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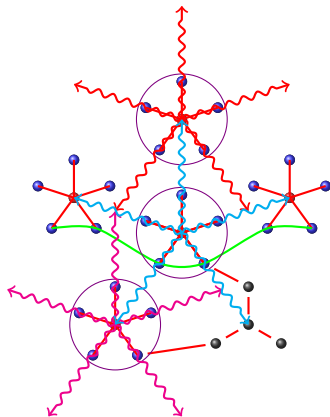
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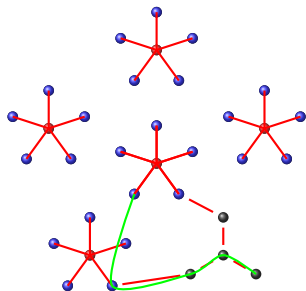
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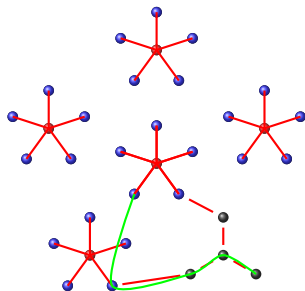
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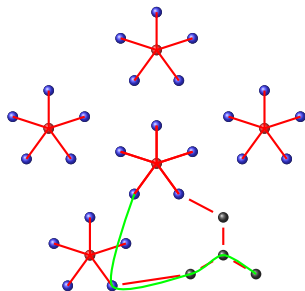


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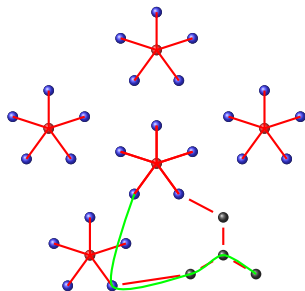


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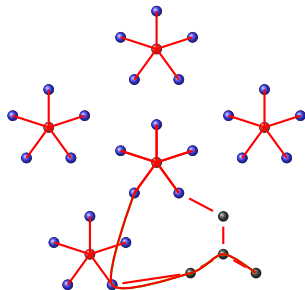
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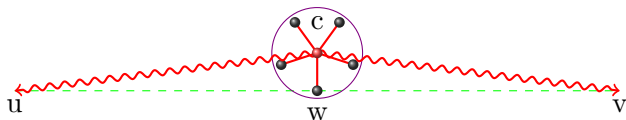
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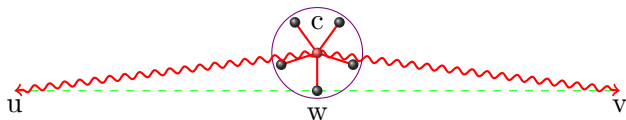
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Analyzing Stretch

Heavy Path



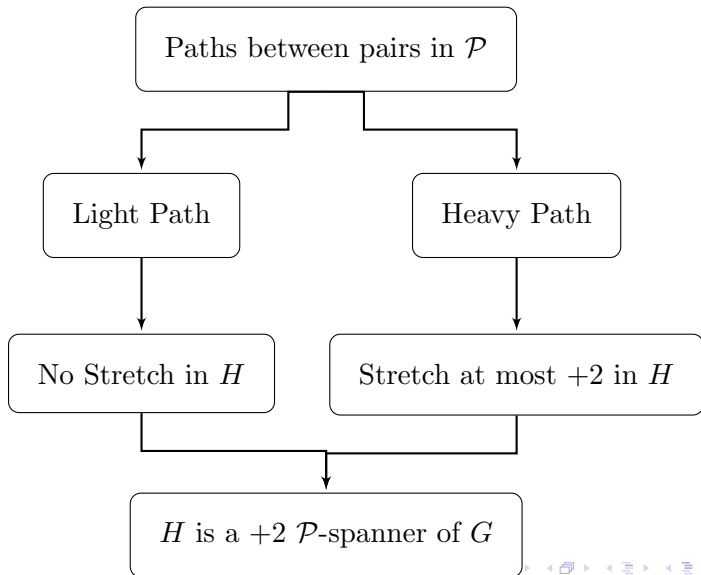
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Light Path



Path of stretch 0 between u and v in H .

Stretch of Spanner



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Size of H is $O(n(|\mathcal{P}| \cdot \log n)^{1/3})$.

We have proved..

Theorem

There is a polynomial time algorithm which, given any graph $G = (V, E)$ on n nodes and any set $\mathcal{P} \subseteq V \times V$, computes a $+2$ \mathcal{P} -spanner of G with $\tilde{O}(n|\mathcal{P}|^{1/3})$ edges.

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- Our +4k D -spanner is sparser for “large” enough D .

Thank You!!

KV13 T. Kavitha and Nithin M. Varma. Small stretch pairwise spanners. In *ICALP(1)*, pages 601-612, 2013.