Approximating the Exponential, the Lanczos Method and an O(m)-Time Spectral Algorithm for Balanced Separator

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BALANCED GRAPH PARTITIONING AND SPECTRAL METHODS

For an undirected unweighted instance graph G = (V, E) with |V| = n and |E| = m, the conductance of a cut $S \subseteq V$ is defined as

$$\phi(S) = \frac{|E(S,\bar{S})|}{\min\{\operatorname{vol}(S), \operatorname{vol}(\bar{S})\}}$$

where vol(S) is the total degree in set S. A cut S is b-balanced if $vol(S) \ge b \cdot vol(V)$.

*b***-BALANCED CUT PROBLEM:** Given graph G, parameter $\gamma \in (0,1)$ and balance $b \in (0,1/2)$, does G contain a b-balanced cut of conductance at most γ ?

This problem is NP-hard. However, approximation algorithms exist:

Algorithm	Method	Distinguishes $\geq\gamma$ and	Running Time
Iterative Eigenvector	Spectral	$O(\sqrt{\gamma})$	$ ilde{O}(n^2)$
[Leighton, Rao `88]	Flow	$O(\gamma \log n)$	$ ilde{O}(m^{rac{3}{2}})$ [AK `0]
[Arora, Rao, Vazirani `04]	SDP (Flow + Spectral)	$O(\gamma \sqrt{\log n})$	$ ilde{O}(m^{rac{3}{2}})$ [Shern
[Madry `10]	SDP (Flow + Spectral)	$\gamma \mathrm{polylog}(n)$	$\tilde{O}(m^{1+\epsilon})$

We use "spectral methods" to refer to algorithms that explore the graph by performing matrix-vector multiplications involving the graph Laplacian L. Such algorithms detect low-conductance cuts by exploiting the connection between the mixing of random walks in the graph and the cut structure of G.

Spectral methods for finding balanced cuts perform well in many applications and have fast running times and optimized implementations that make them a popular choice among practitioners. The following are the theoretical guarantees of some spectral algorithms for this problem.

Algorithm	Method	Distinguishes $\geq \gamma$ and	Ті	
Iterative Eigenvector	Eigenvector	$O(\sqrt{\gamma})$	Õ	
[Andersen, Peres `09]	Local Random Walks	$O\left(\sqrt{\gamma \log n}\right)$	$ ilde{O}$ (
[Orecchia, Vishnoi `10]	SDP	$O(\sqrt{\gamma})$	Õ	

<u>OUR THEOREM</u>: We give an algorithm that either outputs an $\Omega(b)$ -balanced cut $S \subset V$ such that $\phi(S) \leq O(\sqrt{\gamma})$, or outputs a certificate that no b-balanced cut of conductance γ exists. The algorithm runs in time $O(m \operatorname{poly}(\log n))$.

TECHNICAL COMPONENTS:

1) SDP primal-dual iterative algorithm with a simple random walk interpretation

2) Novel analysis of Lanczos methods for computing heat-kernel vectors

HOW WE UPDATE THE GRAPH AND OUR MIXING ANALYSIS

If a low-conductance balanced cut is found, we perform a soft removal of this cut by modifying the current rand walk as follows: $\tau \left(L + \gamma \sum^{t-1} \sum_{i=1}^{t-1} L(\operatorname{Star}_{i}) \right)$

$$P_{t+1} = e^{-\tau \left(L + \gamma \sum_{j=1}^{\infty} \sum_{i \in S_t} L(\operatorname{Star}_i) \right)}$$

where $Star_i$ is the star graph rooted at vertex *i*.

The transition rate from S_t to all vertices increases, making the process converge faster to its stationary.

Increased Transition Rates



MIXING ANALYSIS: Using properties of the heat-kernel random walk, we show that the mixing improves significan

$$\Psi(P_{t+1}, V) \cdot \Psi(P_t, V) - \frac{1}{2}\Psi(P_t, S_t) \cdot \frac{3}{4}\Psi(P_t, V)$$

After $T = O(\log n)$ iterations, if no low-conductance $\Omega(b)$ -balanced cut is found, the following holds:

$$\Psi(P_T, V) \cdot \frac{1}{\operatorname{poly}(n)}$$

We show that we can turn this fact into a NO certificate for the b-Balanced Cut problem:





HOW TO COMPUTE OUR RANDOM-WALK VECTORS
GOAL: For symmetric diagonally-dominant A and vector u , with sparsity m , compute vector v such t
$ e^{-A}u-v $ · δ in time $ ilde{O}(m \cdot \mathrm{polylog}(A) \cdot \mathrm{polylog}(1/\delta))$
In our case, $A=rac{\log n}{\gamma}L$, so that $ A = ilde{O}(rac{1}{\gamma})$ and the running time is $ ilde{O}(m)$.
ITERATIVE APPROACHES:
• Taylor Series Approximation: requires $\Theta(A \log(1/\delta))$ terms and yields a running time of $ ilde{O}(m)$
• Direct Lanczos Method: requires $\Theta(\sqrt{ A } ext{polylog}(1/\delta))$ iterations . The running time is $ ilde{O}(m)$
• Our Algorithm relies on a linear-system solver for A . We obtain the following running times:
- Using Spielman-Teng solver: $ ilde{O}((m+n)\cdot \log(2+ A)\cdot \mathrm{polylog}(1/\delta))$, yielding $ ilde{O}(m+n)\cdot \log(2+ A)\cdot \mathrm{polylog}(1/\delta)$.
- Using Conjugate Gradient: $ ilde{O}((m+n)\cdot\sqrt{1+ A }\cdot\log(2+ A)\cdot\mathrm{polylog}(1/\delta))$
OUR APPROACH exploits the speed of the linear-system solver by using it to perform the inverse up convergence by applying Lanczos method.
Review of Lanczos Method
IDEA : Perform k matrix-vector multiplications to obtain the subspace
$R_k = \operatorname{Span}\{u, Au, A^2u, A^3u, A^4u, \dots, A^ku\}$
Compute an orthonormal basis Q_k for R_k and let T_k be A restricted to R_k :
$T_k = Q_k A Q_k^T$
As k grows, T_k becomes a better approximation to A. If a function f is close to a polynomial p of degr
$ p(x) - f(x) \cdot \delta \forall x \in \text{Spectrum}(A)$
then
$ Q_k f(T_k)Q_k^T u - f(A)u \cdot 2\delta u $