

A Nearly-linear-time Spectral Algorithm for Balanced Graph Partitioning

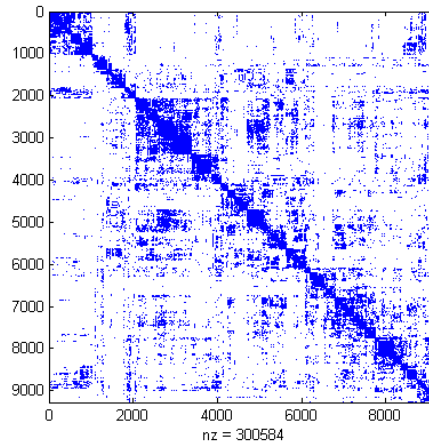
Lorenzo Orecchia
(MIT)

Joint work with
Nisheeth Vishnoi (MSR India) and Sushant Sachdeva (Princeton)

Spectral Algorithms for Graph Problems

What are they?

Spectral algorithms see the input graph as a linear operator



Adjacency matrix of a graph representing similarities between music artists.

Image by David Gleich.

Algorithmic primitives:

- matrix multiplication,
- eigenvector decomposition,
- Gaussian elimination

Spectral Algorithms for Graph Problems

Why are they useful ...
... in practice?

- Simple to **implement**
- Can exploit **very efficient** linear algebra routines
- Perform **provably well** for many problems

... in theory?

- Many new **interesting results** based on spectral techniques:
Laplacian Solvers, Sparsification, s-t Maxflow, etc.
- Geometric viewpoint
- Connections to Markov Chains and Probability Theory

Spectral Algorithms for Graph Partitioning

Spectral algorithms are **widely used** in many graph-partitioning applications: clustering, image segmentation, community-detection, etc.

CLASSICAL VIEW:

- Based on **Cheeger's Inequality**
- Eigenvectors **sweep-cuts** reveal sparse cuts in the graph

NEW TREND:

- **Random walk vectors** replace eigenvectors:
 - Fast Algorithms for Graph Partitioning
 - Local Graph Partitioning
 - Real Network Analysis
- Different random walks: **PageRank**, **Heat-Kernel**, etc.

Why Random Walks? A Practitioner's View

Advantages of Random Walks:

1) Quick approximation to eigenvector in massive graphs

A = adjacency matrix

D = diagonal degree matrix

$W = AD^{-1}$ = natural random walk matrix

$L = D - A$ = Laplacian matrix

Second Eigenvector of the Laplacian can be computed by iterating W :

For random y_0 s.t. $y_0^T D^{-1} \mathbf{1} = 0$, compute

$$D^{-1} W^t y_0$$

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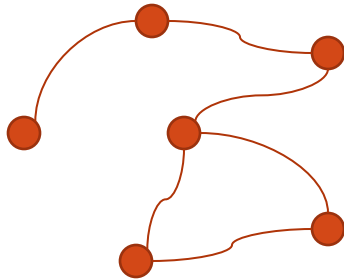
Heuristic: For massive graphs, pick t as large as computationally affordable.

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Advantages of Random Walks:

- 1) Quick approximation to eigenvector in massive graphs
- 2) Statistically robust analogue of eigenvector

Real-world graphs are **noisy**



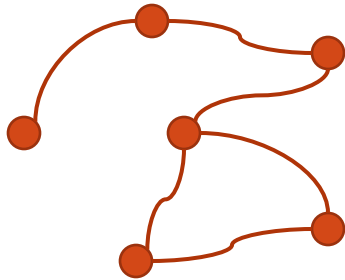
GROUND TRUTH GRAPH

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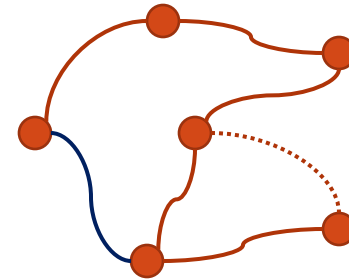
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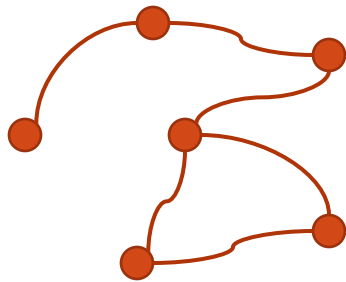


INPUT GRAPH

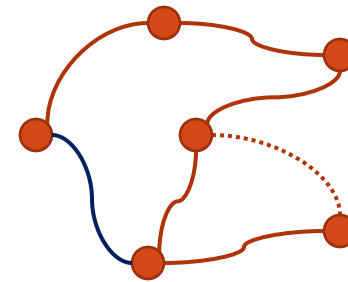
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GROUND-TRUTH GRAPH



INPUT GRAPH

GOAL: estimate eigenvector of ground-truth graph.

OBSERVATION: eigenvector of input graph can have **very large variance**, as it can be **very sensitive to noise**

RANDOM-WALK VECTORS provide **more stable estimates**.

This Talk

QUESTION:

Why random-walk vectors in the design of fast algorithms?

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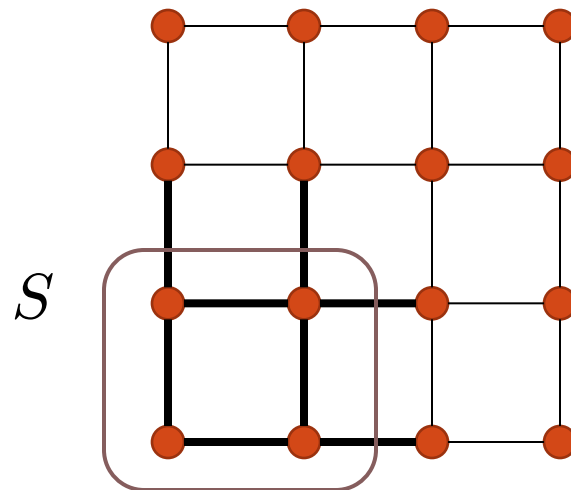
GOALS OF THIS TALK:

- 1) Showcase how these ideas apply to balanced graph partitioning
- 2) Show optimization perspective on why random walks arise

Problem Definition and Overview of Results

Partitioning Graphs - Conductance

Undirected unweighted $G = (V, E)$, $|V| = n$, $|E| = m$

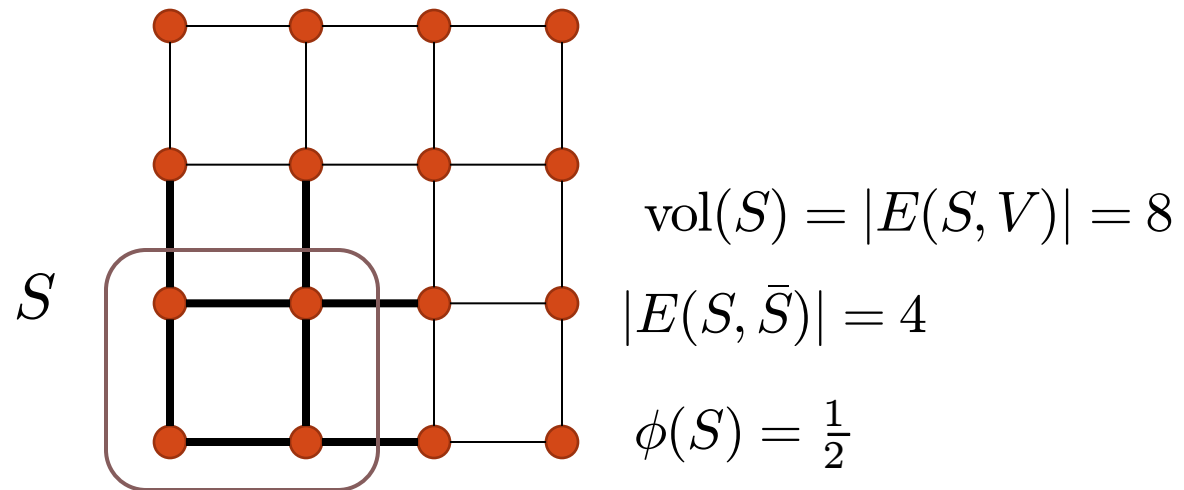


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$$\phi(S) = \frac{|E(S, \bar{S})|}{\min\{\text{vol}(S), \text{vol}(\bar{S})\}}$$

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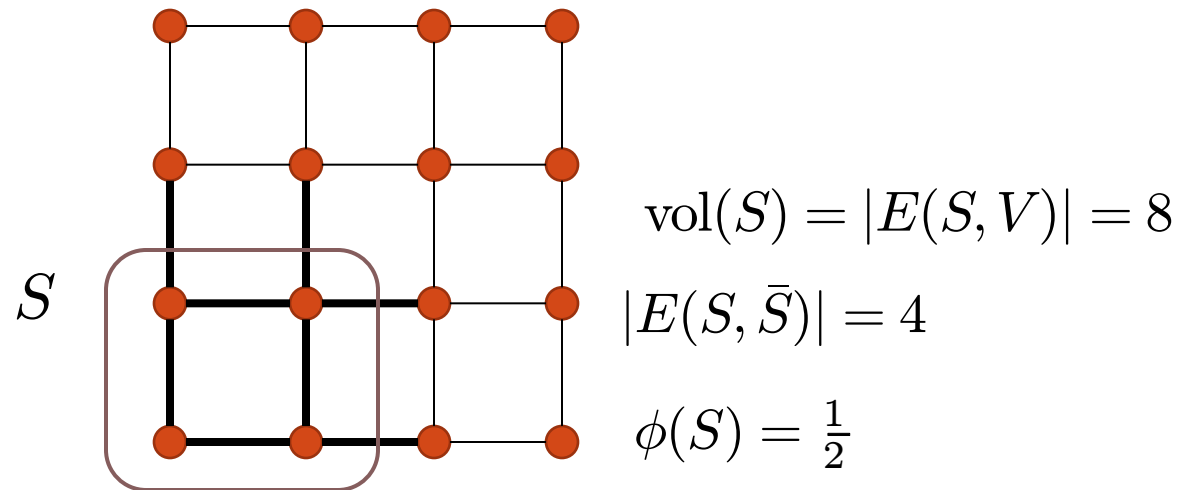


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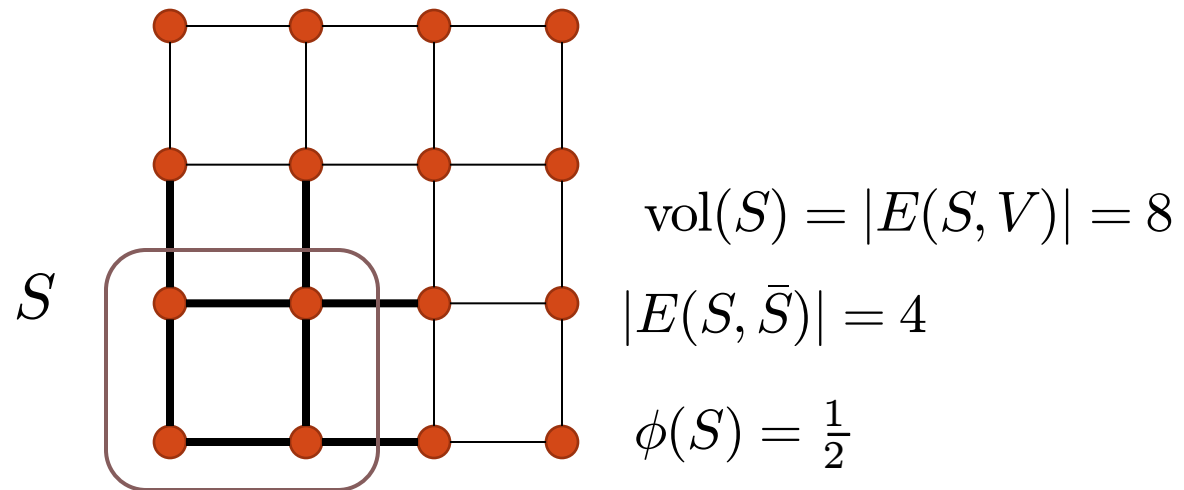


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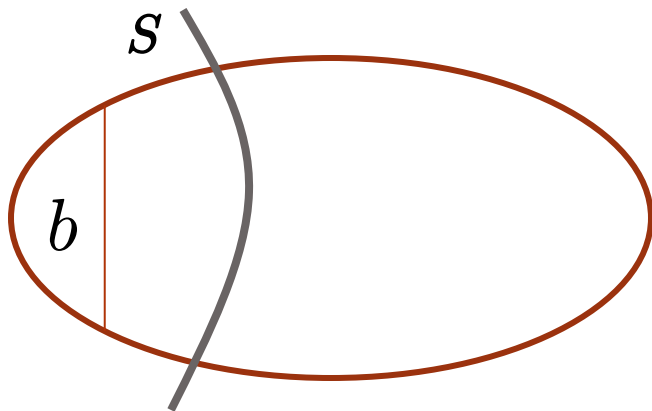
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Partitioning Graphs – Balanced Cut

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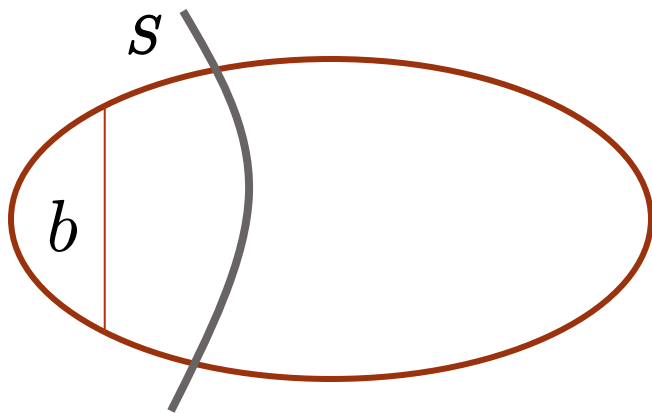
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- Important primitive for many **recursive** algorithms.
- Applications to **clustering** and **graph decomposition**.

Approximation Algorithms

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Fast Approximation Algorithms

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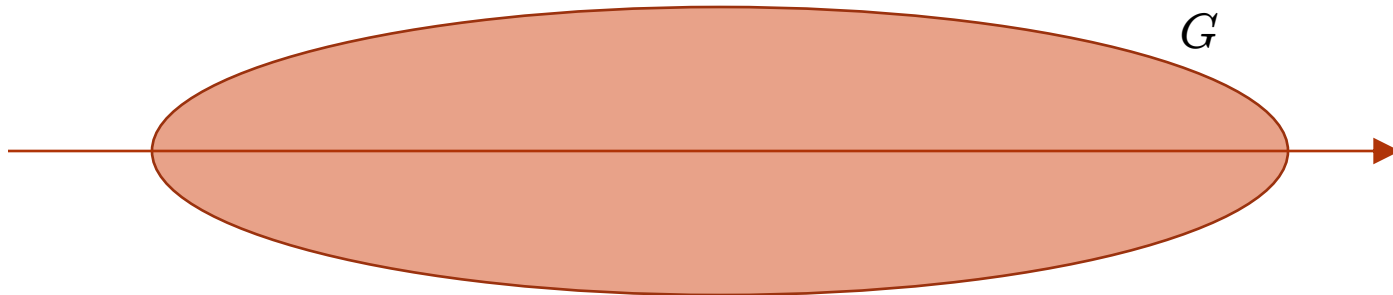
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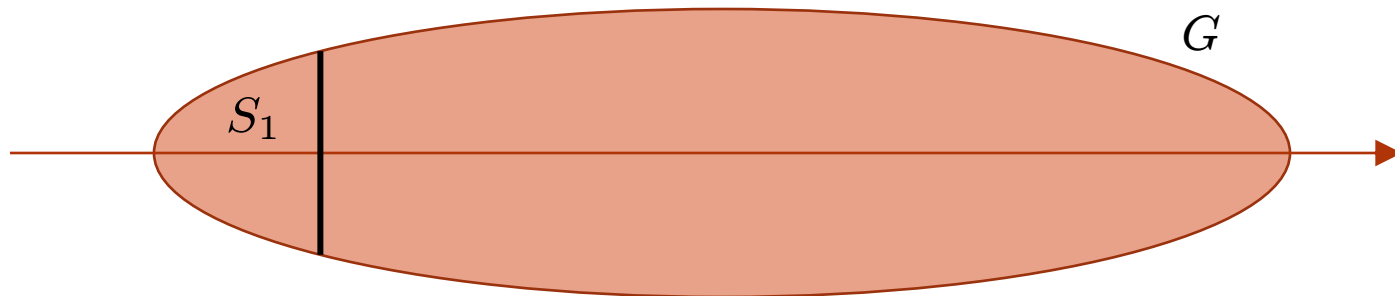


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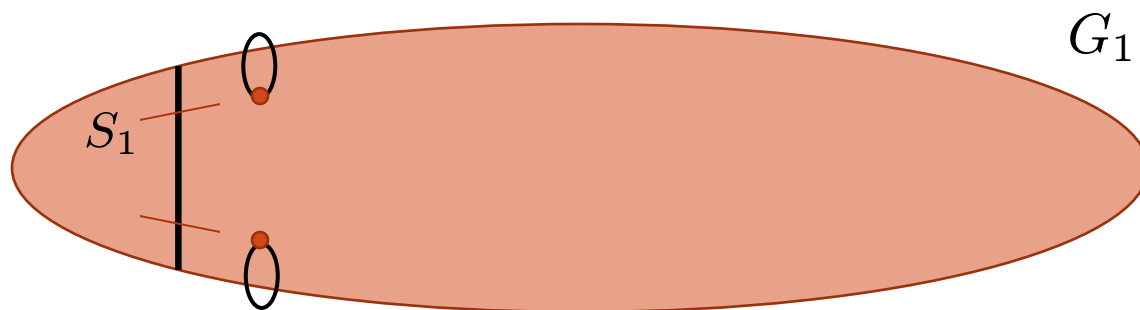
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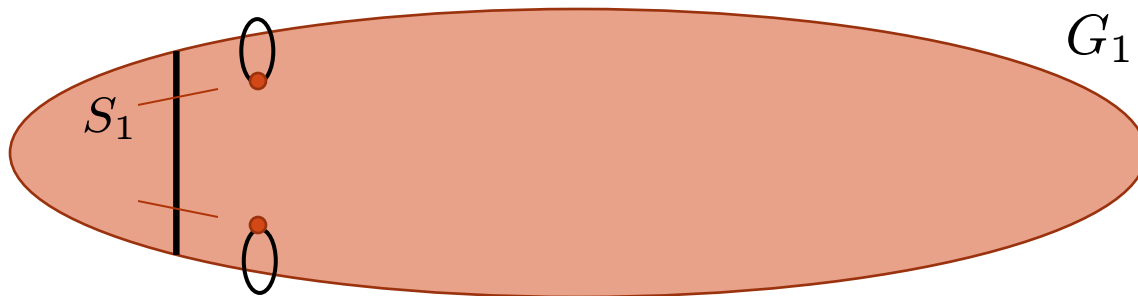
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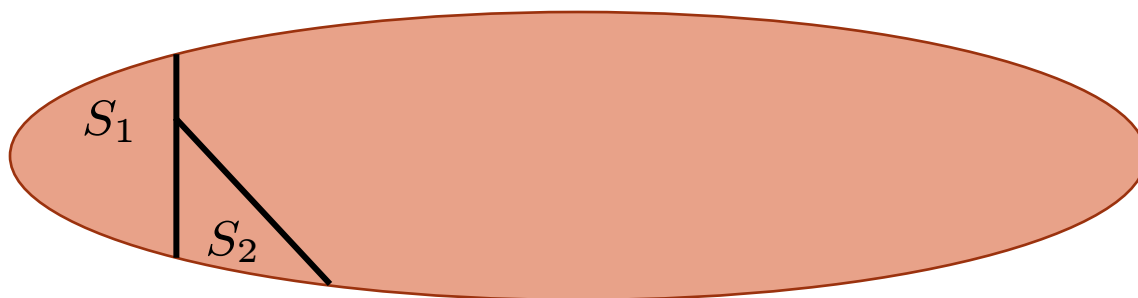
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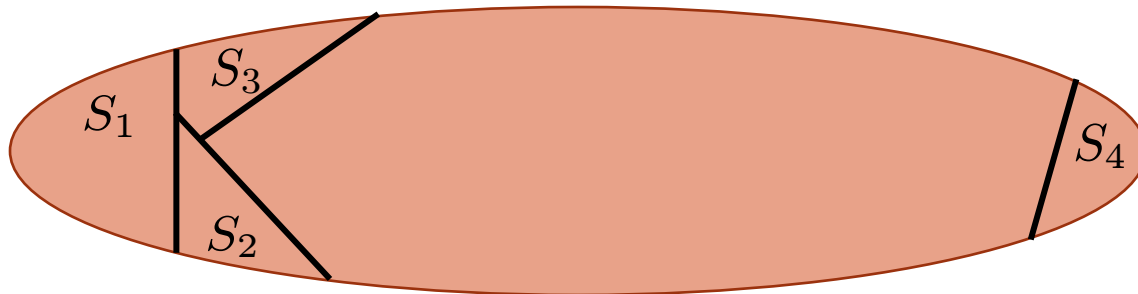
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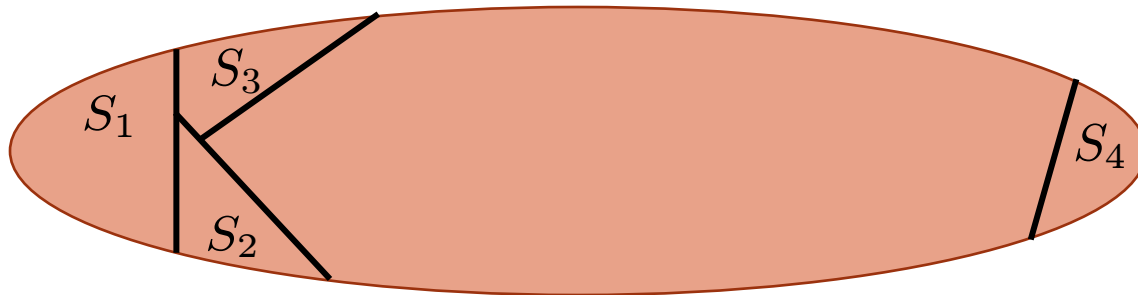
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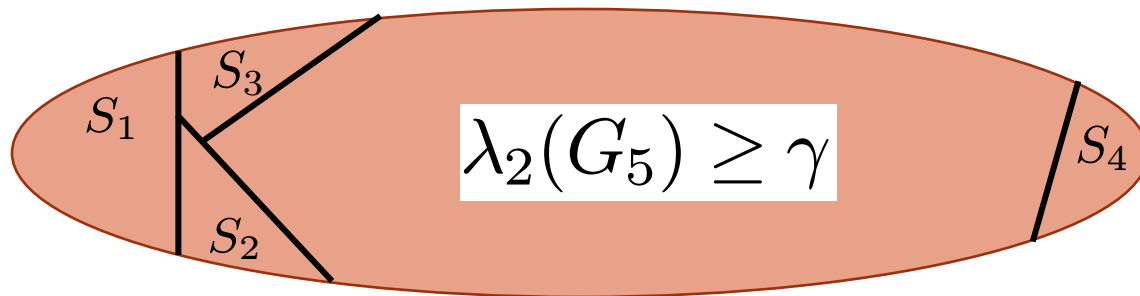
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LARGE INDUCED EXPANDER = **NO-CERTIFICATE**

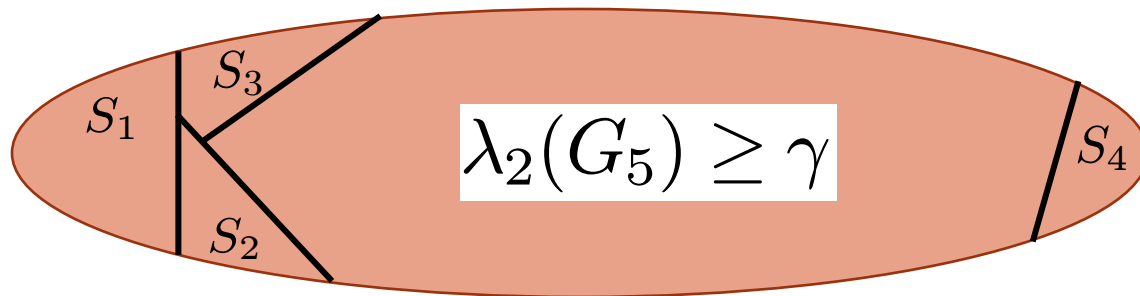
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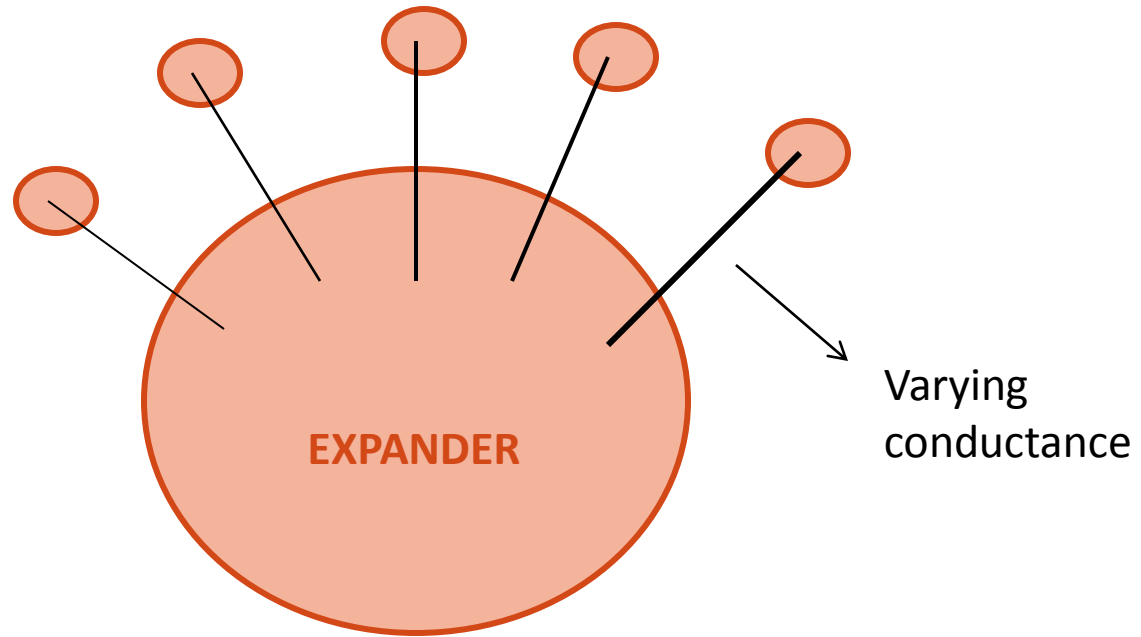
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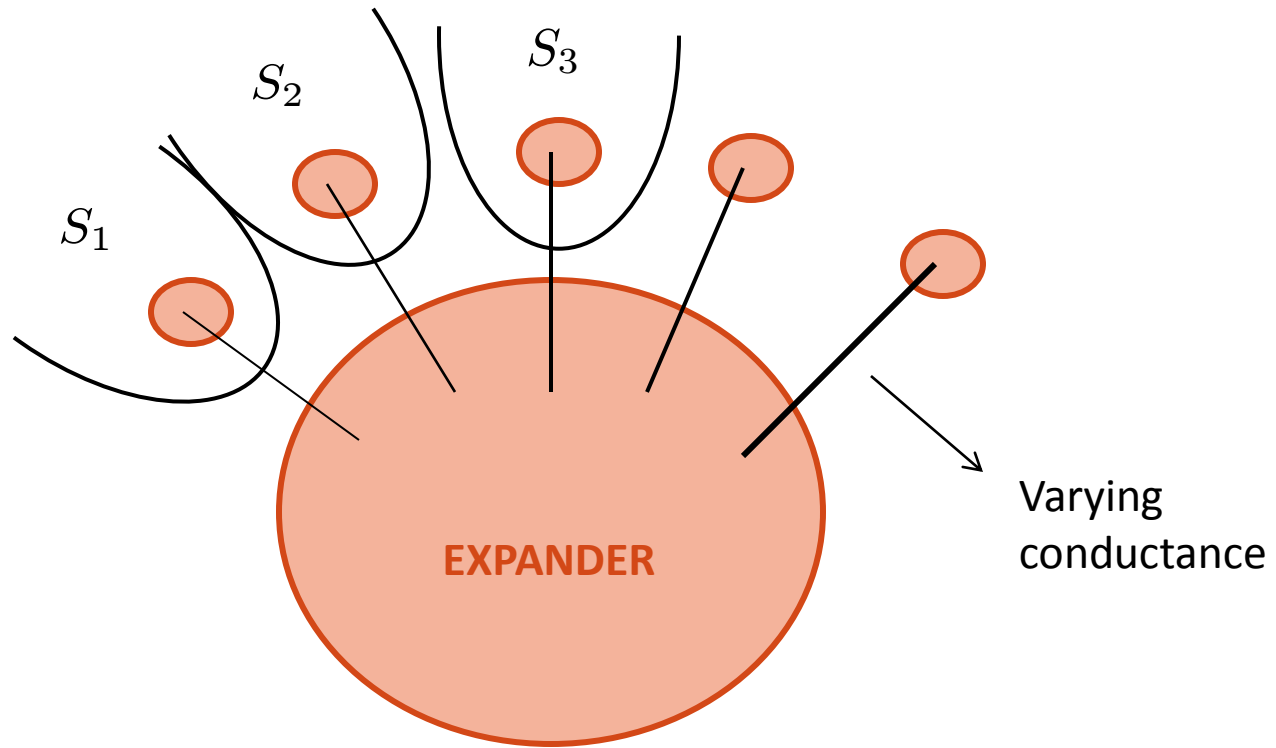
RUNNING TIME: $\tilde{O}(mn) \cdot \tilde{O}(m)$ per iteration, $O(n)$ iterations.

Recursive Eigenvector: The Worst Case



- (n) nearly-disconnected components

Recursive Eigenvector: The Worst Case

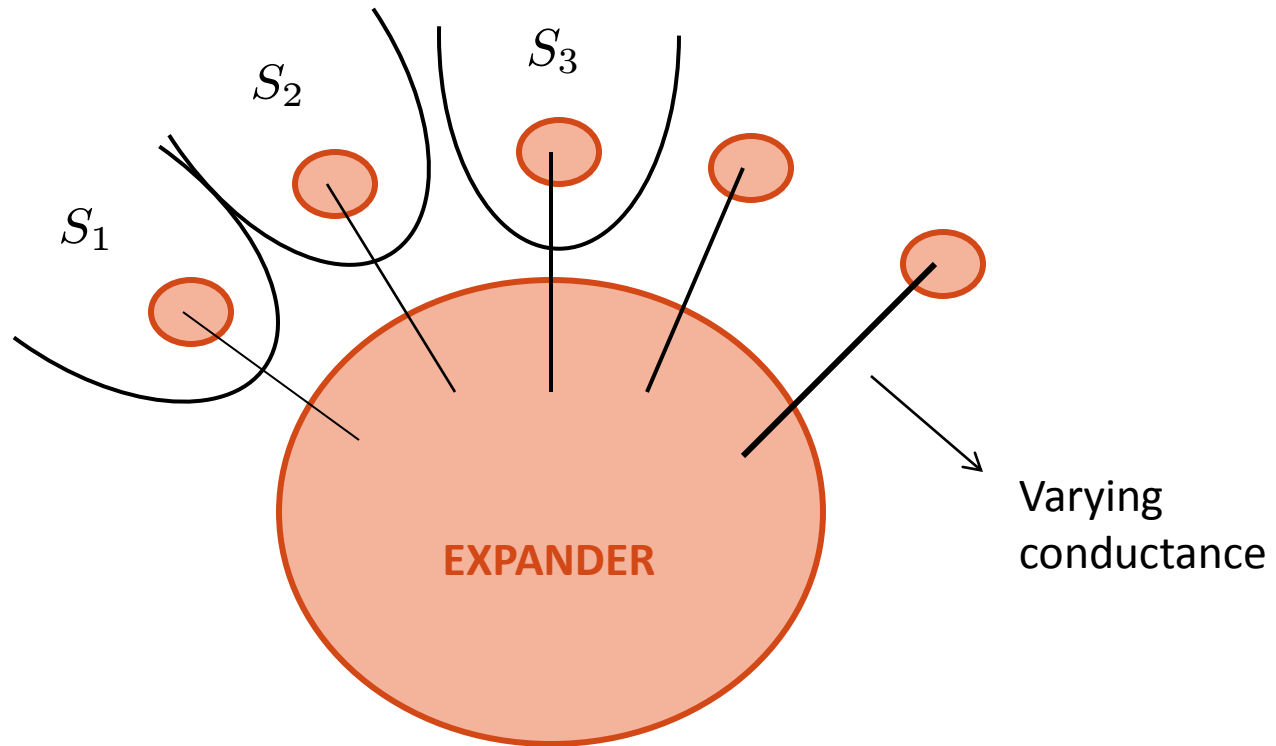


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NB: Recursive Eigenvector eliminates one component per iteration.

- (n) iterations are necessary. Each iteration requires $\Omega(mn)$ time.

Recursive Eigenvector: The Worst Case



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GOAL: Eliminate unbalanced low-conductance cuts faster.

Our Algorithm: Contributions

| Algorithm | Method | Distinguishes $\geq \gamma$ and | Time |
|-----------------------|--------------|---------------------------------|-----------------|
| Recursive Eigenvector | Eigenvector | $O(\sqrt{\gamma})$ | $\tilde{O}(mn)$ |
| OUR ALGORITHM | Random Walks | $O(\sqrt{\gamma})$ | $\tilde{O}(m)$ |

MAIN FEATURES:

- Compute $O(\log n)$ global heat-kernel random-walk vectors at each iteration
- Unbalanced cuts are removed in $O(\log n)$ iterations
- Method to compute heat-kernel vectors, i.e. $e^{-tL}v$, in time $\tilde{O}(m)$

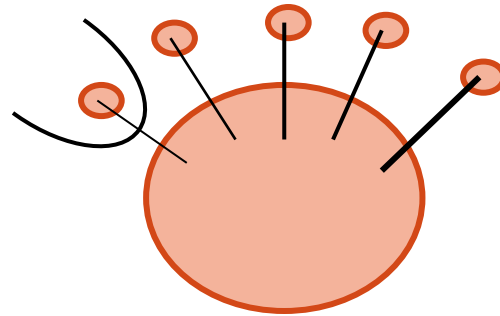
TECHNICAL COMPONENTS:

- 1) New iterative algorithm with a simple random walk interpretation
- 2) Novel analysis of Lanczos methods for computing heat-kernel vectors

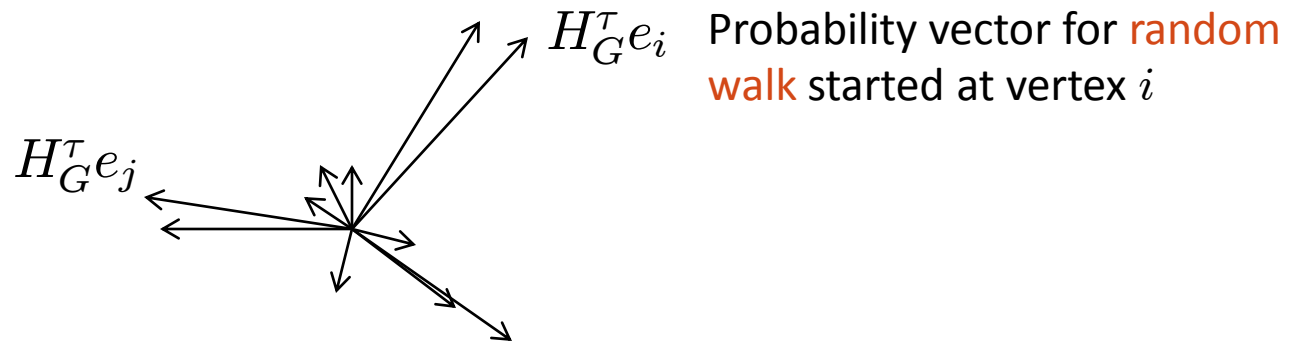
Why Random Walks

GOAL: Eliminate unbalanced cuts of low-conductance efficiently

- The **graph eigenvector** may be correlated with **only one** sparse unbalanced cut.



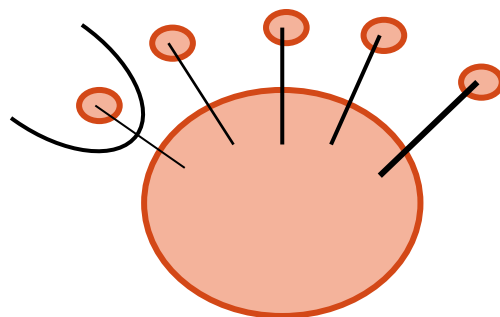
- Consider the Heat-Kernel random walk H_G^τ for $\tau = \log n / \gamma$.



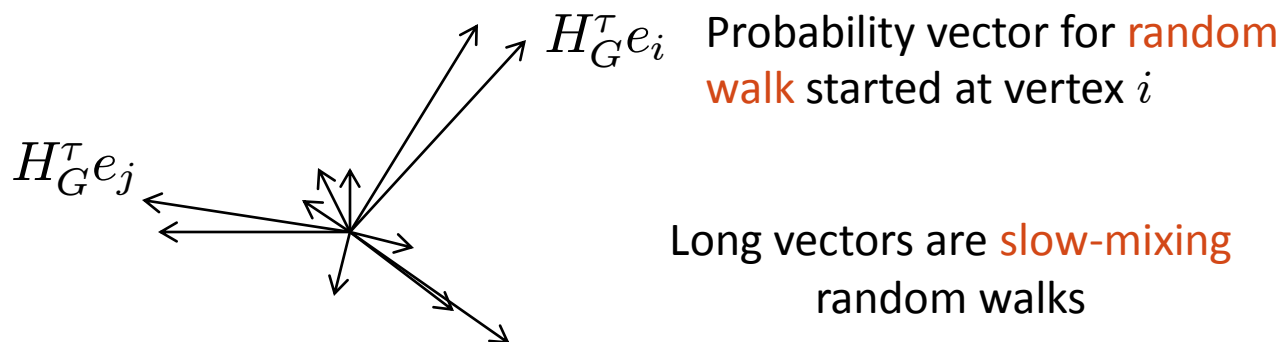
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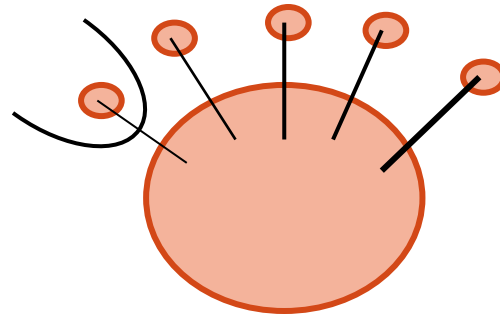
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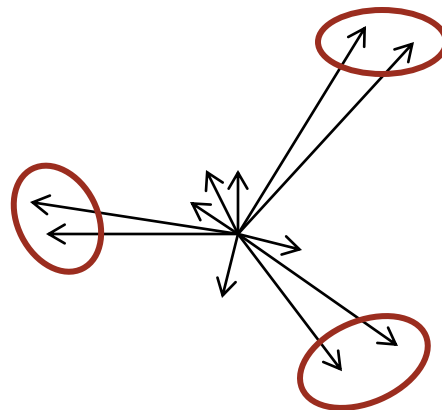
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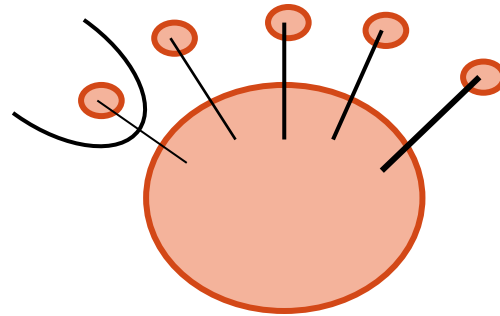
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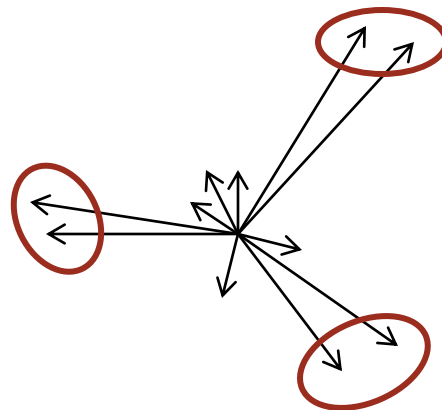
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**SINGLE VECTOR
SINGLE CUT**



- Consider the Heat-Kernel random walk H_G^τ for $\tau = \log n / \gamma$.

**VECTOR EMBEDDING
MULTIPLE CUTS**



Unbalanced cuts of
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Heat-Kernel Random Walk: A Regularization View

Background: Heat-Kernel Random Walk

For simplicity, take G to be **d-regular**.

- The Heat-Kernel Random Walk is a **Continuous-Time Markov Chain** over V , modeling the **diffusion of heat** along the edges of G .
- Transitions take place in **continuous time** t , with an **exponential distribution**.

$$\frac{\partial p(t)}{\partial t} = -L \frac{p(t)}{d}$$

$$p(t) = e^{-\frac{t}{d}L} p(0)$$

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- In practice, can replace **Heat-Kernel with natural random walk** W^t

Regularized Spectral Optimization

Eigenvector Program

$$\begin{aligned} \frac{1}{d} \min x^T L x \\ \text{s.t. } \|x\|_2 = 1 \\ x^T \mathbf{1} = 0 \end{aligned}$$



SDP Formulation

$$\begin{aligned} \frac{1}{d} \min L \bullet X \\ \text{s.t. } I \bullet X = 1 \\ \mathbf{1}\mathbf{1}^T \bullet X = 0 \\ X \succeq 0 \end{aligned}$$

Programs have **same optimum**. Take optimal solution

$$X^* = x^* (x^*)^T$$

Regularized Spectral Optimization

SDP Formulation

$$\begin{aligned} & \frac{1}{d} \min \quad L \bullet X \\ \text{s.t.} \quad & I \bullet X = 1 \\ & \mathbf{1}\mathbf{1}^T \bullet X = 0 \\ & X \succeq 0 \end{aligned} \quad \left. \vphantom{\begin{aligned} & I \bullet X = 1 \\ & \mathbf{1}\mathbf{1}^T \bullet X = 0 \\ & X \succeq 0 \end{aligned}} \right\} \text{Density Matrix}$$

Eigenvector decomposition of X :

$$X = \sum p_i v_i v_i^T \quad \left\{ \begin{array}{l} \forall i, p_i \geq 0, \\ \sum p_i = 1, \\ \forall i, v_i^T \mathbf{1} = 0. \end{array} \right.$$

Eigenvalues of X define **probability distribution**

Regularized Spectral Optimization

SDP Formulation

$$\frac{1}{d} \min L \bullet X$$

$$\text{s.t.} \quad I \bullet X = 1$$

$$J \bullet X = 0$$

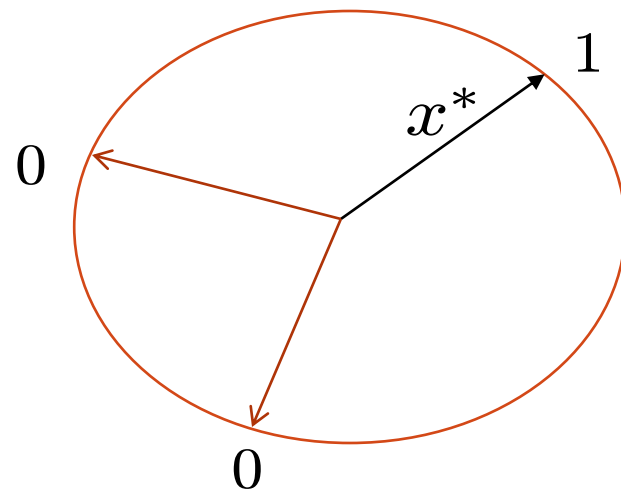
$$X \succeq 0$$

Density Matrix

Eigenvalues of X define **probability distribution**

$$X^* = x^* (x^*)^T$$

TRIVIAL DISTRIBUTION



Regularized Spectral Optimization

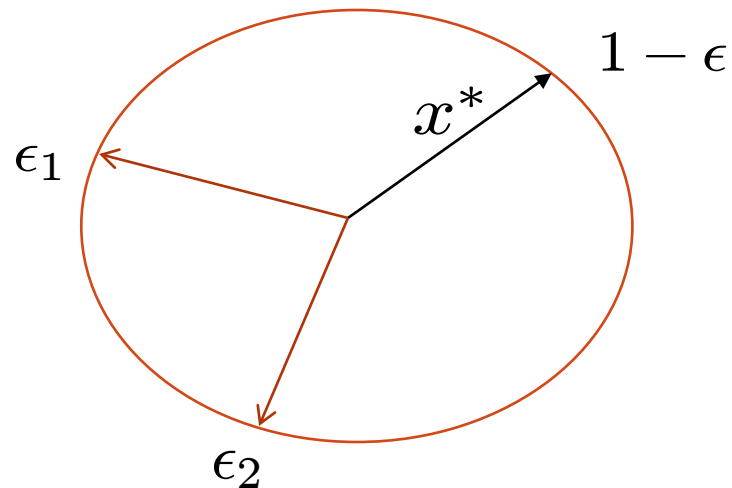
$$\begin{aligned} & \text{Regularized SDP} \\ & \frac{1}{d} \min L \bullet X + \boxed{\eta \cdot F(X)} \quad \begin{array}{l} \text{Regularizer } F \\ \text{Parameter } \eta \end{array} \\ \text{s.t.} \quad & I \bullet X = 1 \\ & J \bullet X = 0 \\ & X \succeq 0 \end{aligned}$$

The regularizer F forces the distribution of eigenvalues of X to be **non-trivial**

$$X^* = x^* (x^*)^T$$

REGULARIZATION

$$X^* = \sum p_i v_i v_i^T$$



Regularizers

Regularizers are **SDP-versions** of common regularizers

- von Neumann Entropy

$$F_H(X) = \text{Tr}(X \log X) = \sum p_i \log p_i$$

- p-Norm, $p > 1$

$$F_p(X) = \frac{1}{p} \|X\|_p^p = \frac{1}{p} \text{Tr}(X^p) = \frac{1}{p} \sum p_i^p$$

- And more, e.g. log-determinant.

Our Main Result

Regularized SDP

$$\begin{aligned} & \frac{1}{d} \min L \bullet X + \eta \cdot F(X) \\ \text{s.t.} \quad & I \bullet X = 1 \\ & J \bullet X = 0 \\ & X \succeq 0 \end{aligned}$$

RESULT:

Explicit correspondence between regularizers and random walks

REGULARIZER

OPTIMAL SOLUTION OF REGULARIZED PROGRAM

$$F = F_H \xrightarrow{\text{Entropy}} X^* \propto H_t \quad \text{where } t \text{ depends on } \eta$$

where α depends on η

$$F = F_p \xrightarrow{p\text{-Norm}} X^* \propto T_{q, \frac{1}{p-1}} \quad \text{where } q \text{ depends on } \eta$$

Discussion: Vector vs Density Matrix

Variable is **density matrix**, not vector

Q: Can we produce a single vector?

A: Density Matrix X describes distributions over vectors.

Assuming distribution is Gaussian, sample a vector

$$x = X^{\frac{1}{2}} u$$

where $u \sim N(0, I_{n-1})$

For example, the vector

$$x = H_{t/2} u \quad \text{Random walk on random seed}$$

is a sample from the solution of an **entropy-regularized problem**

PART 1

The New Iterative Procedure

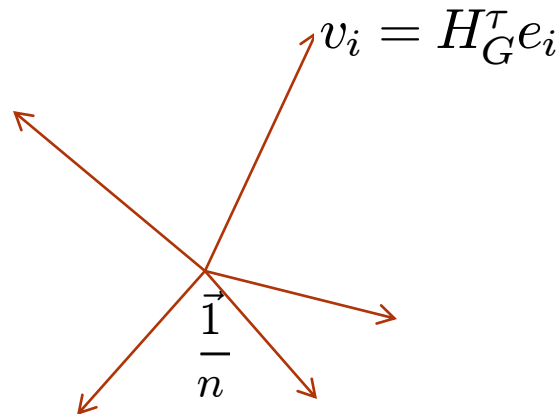
Our Algorithm for Balanced Cut

IDEA BEHIND OUR ALGORITHM:

Replace eigenvector in recursive eigenvector algorithm with

Heat-Kernel random walk H_G^τ for $\tau = \log n / \gamma$

Consider the embedding $\{v_i\}$ given by H_G^τ :



Our Algorithm for Balanced Cut

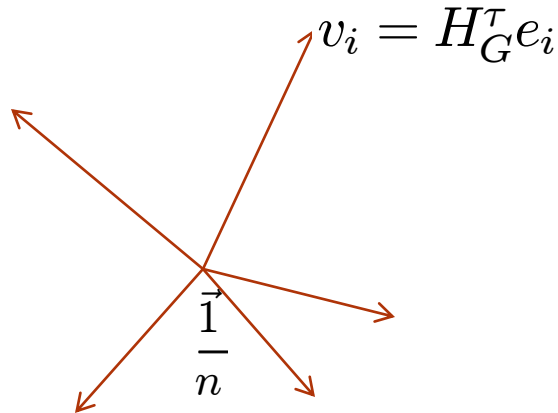
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Stationary distribution is uniform as G is regular

Our Algorithm for Balanced Cut

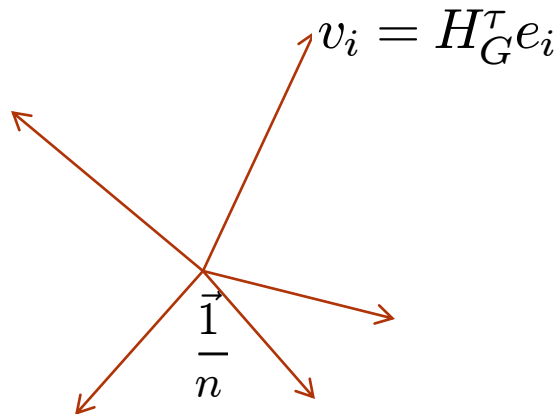
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Consider the embedding $\{v_i\}$ given by H_G^τ :



Stationary distribution is uniform as G is regular

MIXING:

Define the total deviation from stationary for a set $S \subseteq V$ for walk H_G^τ

$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|v_i - \vec{1}/n\|^2$$

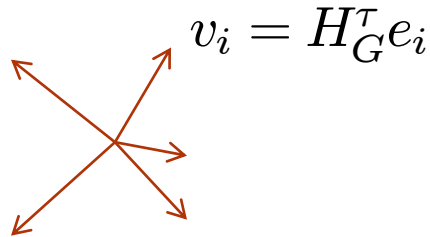
FUNDAMENTAL QUANTITY TO UNDERSTAND CUTS IN G

Our Algorithm: Case Analysis

Recall:

$$\tau = \log n / \gamma \quad \Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$

CASE 1: Random walks have **mixed**



ALL VECTORS ARE SHORT

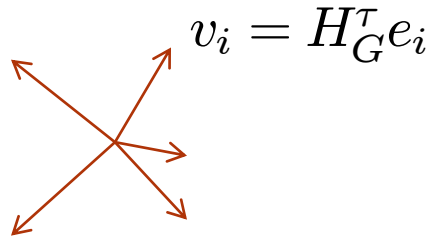
$$\Psi(H_G^\tau, V) \cdot \frac{1}{\text{poly}(n)}$$

Our Algorithm: Case Analysis

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$$\tau = \log n / \gamma \quad \Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$

CASE 1: Random walks have **mixed**



ALL VECTORS ARE SHORT

$$\Psi(H_G^\tau, V) \cdot \frac{1}{\text{poly}(n)}$$

$$\lambda_2 \geq -(\gamma)$$

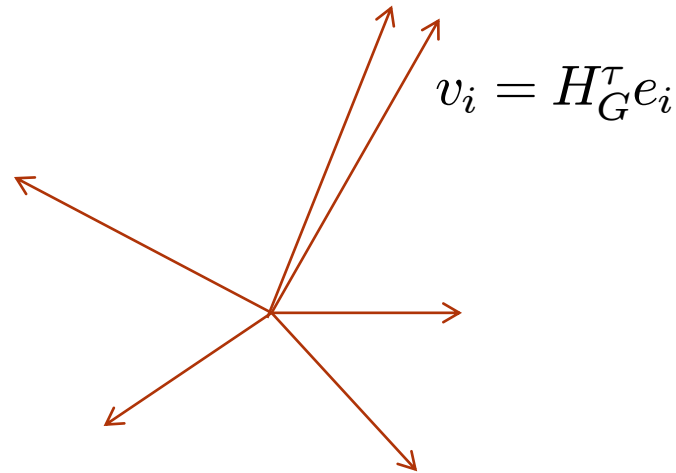
$$\phi_G \geq -(\gamma)$$

By definition of τ

Our Algorithm

$$\tau = \log n / \gamma$$

$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$



CASE 2: Random walks have **not mixed**

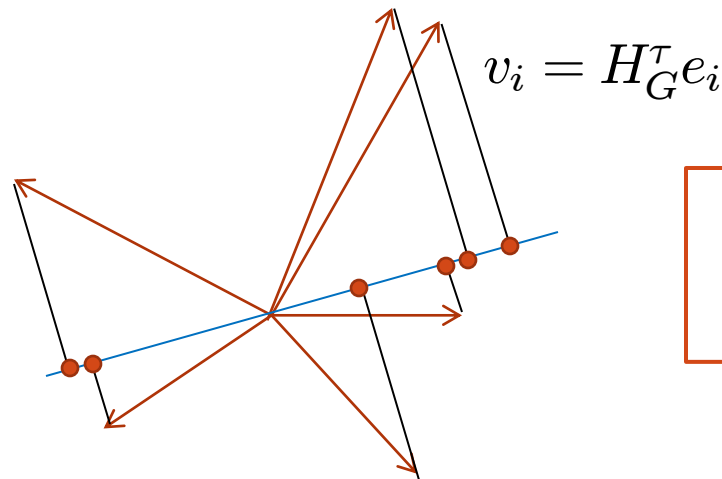
$$\Psi(H_G^\tau, V) > \frac{1}{\text{poly}(n)}$$

We can either find an $\Omega(b)$ -**balanced cut** with conductance $\cdot O(\sqrt{\gamma})$

Our Algorithm

$$\tau = \log n / \gamma$$

$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$



RANDOM PROJECTION
+
SWEEP CUT

CASE 2: Random walks have **not mixed**

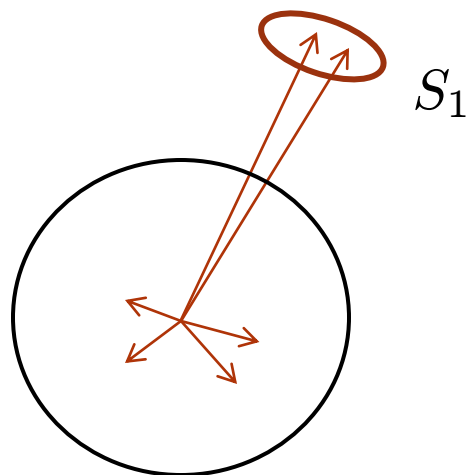
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BALL
ROUNDING

CASE 2: Random walks have **not mixed**

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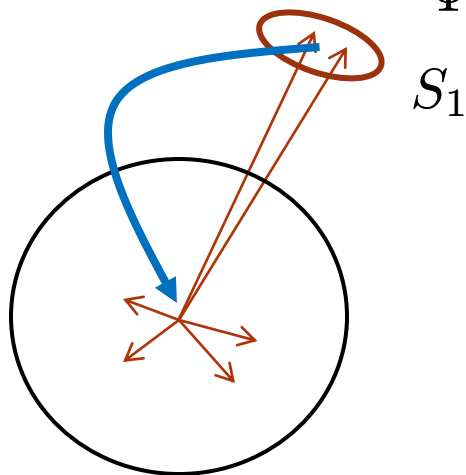
OR a ball cut yields S_1 such that $\phi(S_1) \cdot O(\sqrt{\phi})$ and

$$\Psi(H_G^\tau, S_1) \geq \frac{1}{2} \Psi(H_G^\tau, V).$$

Our Algorithm: Iteration

$$\tau = \log n / \gamma$$

$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$



CASE 2: We found an **unbalanced cut** S_1 with $\phi(S_1) \cdot O(\sqrt{\phi})$ and

$$\Psi(H_G^\tau, S_1) \geq \frac{1}{2} \Psi(H_G^\tau, V).$$

Modify $G = G^{(1)}$ by **adding edges** across (S_1, \bar{S}_1) to construct $G^{(2)}$.

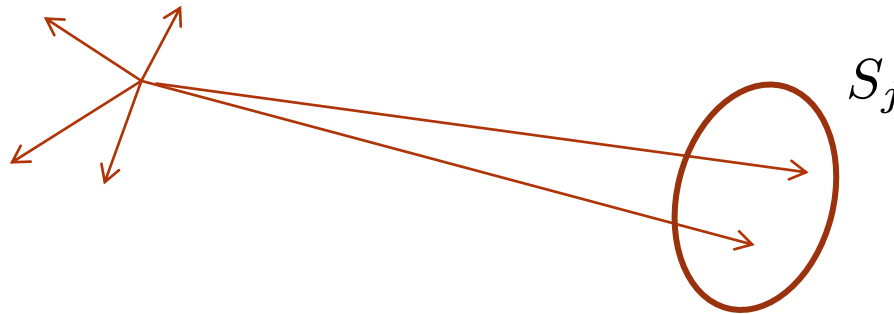
Analogous to **removing unbalanced cut** S_1
in Recursive Eigenvector algorithm

Our Algorithm: Modifying G

CASE 2: We found an **unbalanced cut** S_1 with $\phi(S_1) \cdot O(\sqrt{\phi})$ and

$$\Psi(H_G^\tau, S_1) \geq \frac{1}{2}\Psi(H_G^\tau, V).$$

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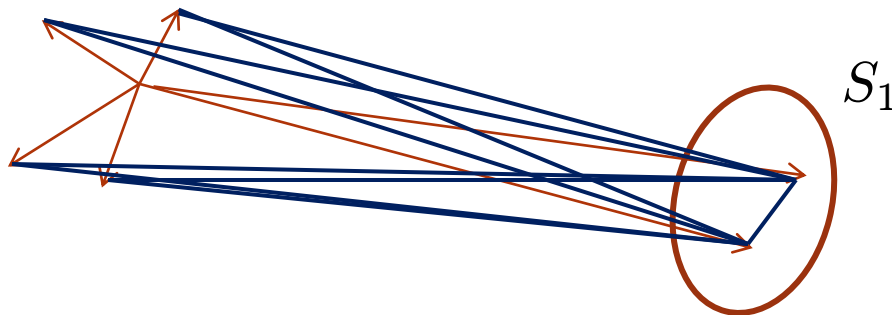


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$$G^{(t+1)} = G^{(t)} + \gamma \sum_{i \in S_t} \text{Star}_i$$

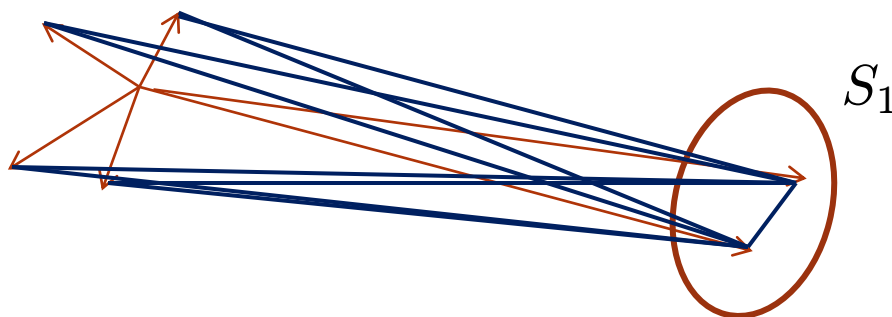
where Star_i is the **star graph** rooted at vertex i .

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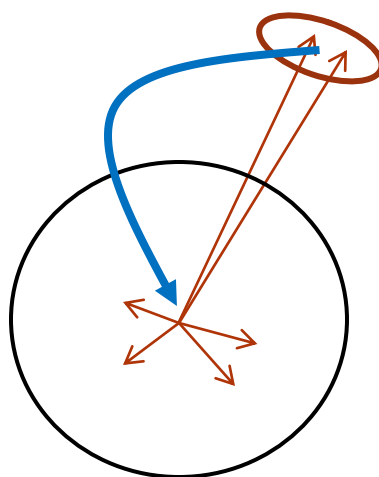
$$G^{(t+1)} = G^{(t)} + \gamma \sum_{i \in S_t} \text{Star}_i$$

where Star_i is the **star graph** rooted at vertex i .

The random walk can now **escape** S_1 more easily.

Our Algorithm: Iteration

$$\tau = \log n / \gamma$$



$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$

CASE 2: We found an **unbalanced cut** S_1 with $\phi(S_1) \cdot O(\sqrt{\phi})$ and

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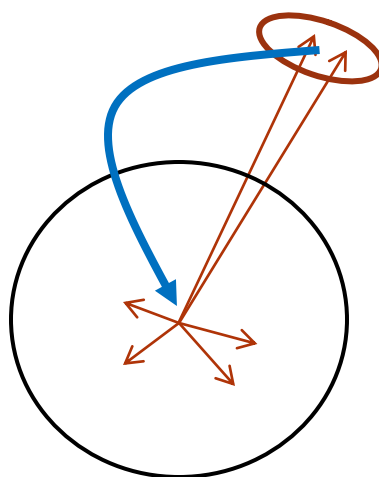
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POTENTIAL REDUCTION:

$$\Psi(H_{G^{(t+1)}}^\tau, V) \cdot \Psi(H_{G^{(t)}}^\tau, V) - \frac{1}{2} \Psi(H_{G^{(t)}}^\tau, S_t) \cdot \frac{3}{4} \Psi(H_{G^{(t)}}^\tau, V)$$

Our Algorithm: Iteration

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CRUCIAL APPLICATION OF STABILITY OF RANDOM WALK

Summary and Potential Analysis

IN SUMMARY:

At every step t of the recursion, we either

1. Produce a $\Omega(b)$ -balanced cut of the required conductance, OR

Potential Reduction

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At every step t of the recursion, we either

1. Produce a $\Omega(b)$ -balanced cut of the required conductance, OR
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$$\Psi(H_G^T, V) \cdot \frac{1}{\text{poly}(n)}, \text{ OR}$$

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$$\Psi(H_{G^{(t+1)}}^\tau, V) \cdot \frac{3}{4} \Psi(H_{G^{(t)}}^\tau, V)$$

Potential Reduction

IN SUMMARY:

At every step $t-1$ of the recursion, we either

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2. Find that

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3. Find an **unbalanced cut** S_t of the required conductance, such that for the process $P^{(t+1)}$, modified to have **increased transitions** from S_t ,

$$\Psi(H_{G^{(t+1)}}^\tau, V) \cdot \frac{3}{4} \Psi(H_{G^{(t)}}^\tau, V)$$

After $T=O(\log n)$ iterations, if no low-conductance $\Omega(b)$ -balanced cut is found:

$$\Psi(H_{G^{(T)}}^\tau, V) \cdot \frac{1}{\text{poly}(n)}$$

From this guarantee, using the definition of $G^{(T)}$, we derive an **SDP-certificate** that no **b-balanced cut** of conductance $O(\gamma)$ exists in G .

NB: Only $O(\log n)$ iterations to remove unbalanced cuts.

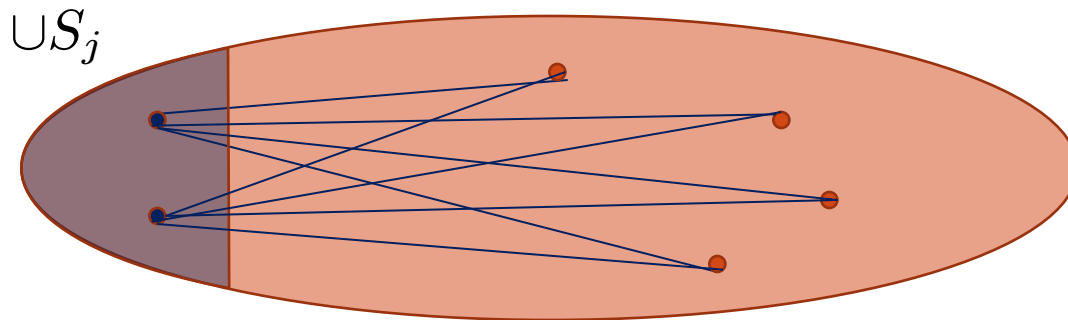
Heat-Kernel and Certificates

- If no balanced cut of conductance is found, our potential analysis yields:

$$\Psi(H_{G^{(T)}}^T, V) \cdot \frac{1}{\text{poly}(n)} \longrightarrow L + \gamma \sum_{j=1}^{T-1} \sum_{i \in S_j} L(\text{Star}_i) \succeq \gamma L(K_V)$$

Modified graph has $\lambda_2 \geq \gamma$

CLAIM: This is a certificate that no balanced cut of conductance $< \gamma$ existed in G .



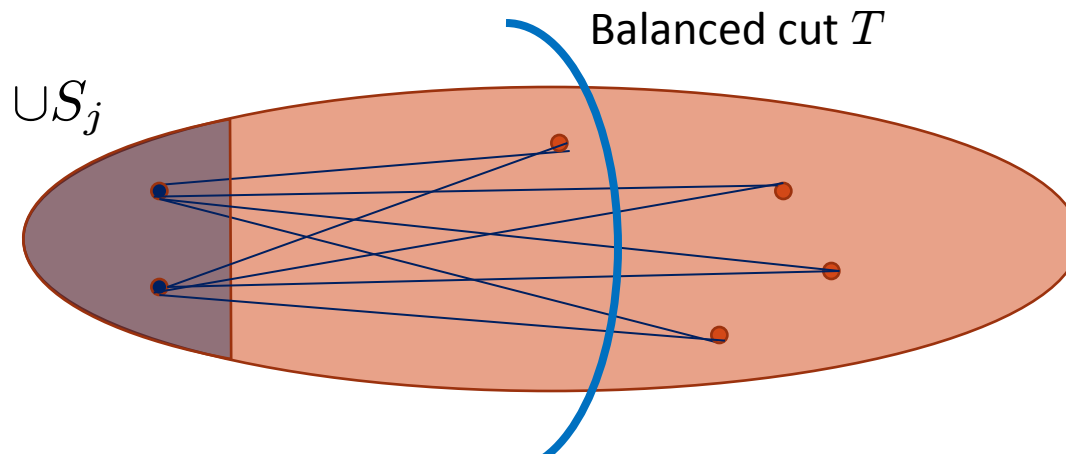
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$$\phi(T) \geq \gamma - \gamma \frac{|\cup S_j|}{|T|}$$

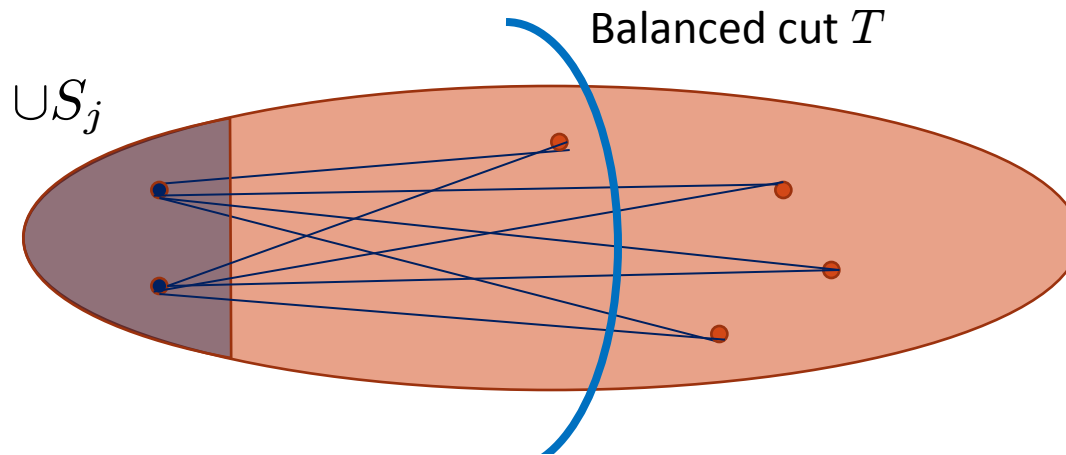
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$$\phi(T) \geq \gamma - \gamma \frac{|US_j|}{|T|} \geq \gamma - \gamma \frac{b/2}{b} \geq \gamma/2$$

Comparison with Recursive Eigenvector

RECURSIVE EIGENVECTOR:

We can **only bound** number of iterations by **volume of graph removed**.

$\Omega(n)$ iterations possible.

OUR ALGORITHM:

Use **variance of random walk** as potential.

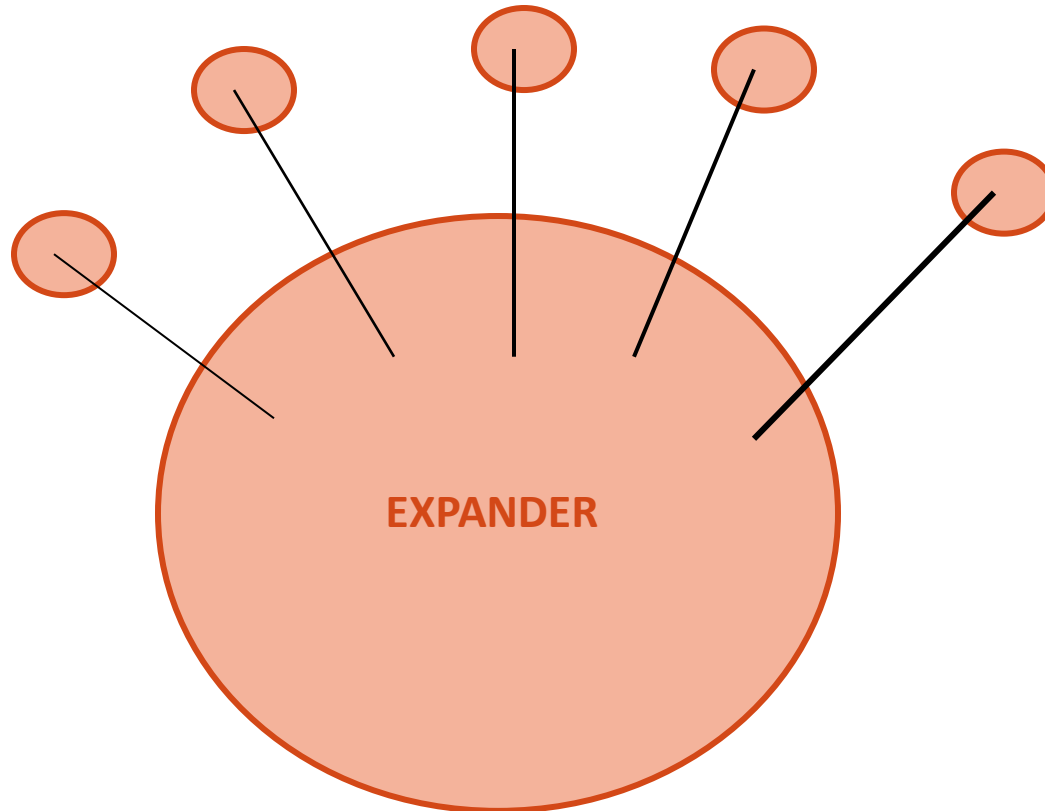
Only $O(\log n)$ iterations necessary.

$$\Psi(P, V) = \sum_{i \in V} \|Pe_i - \vec{1}/n\|^2$$

RIGHT SPECTRAL NOTION OF POTENTIAL

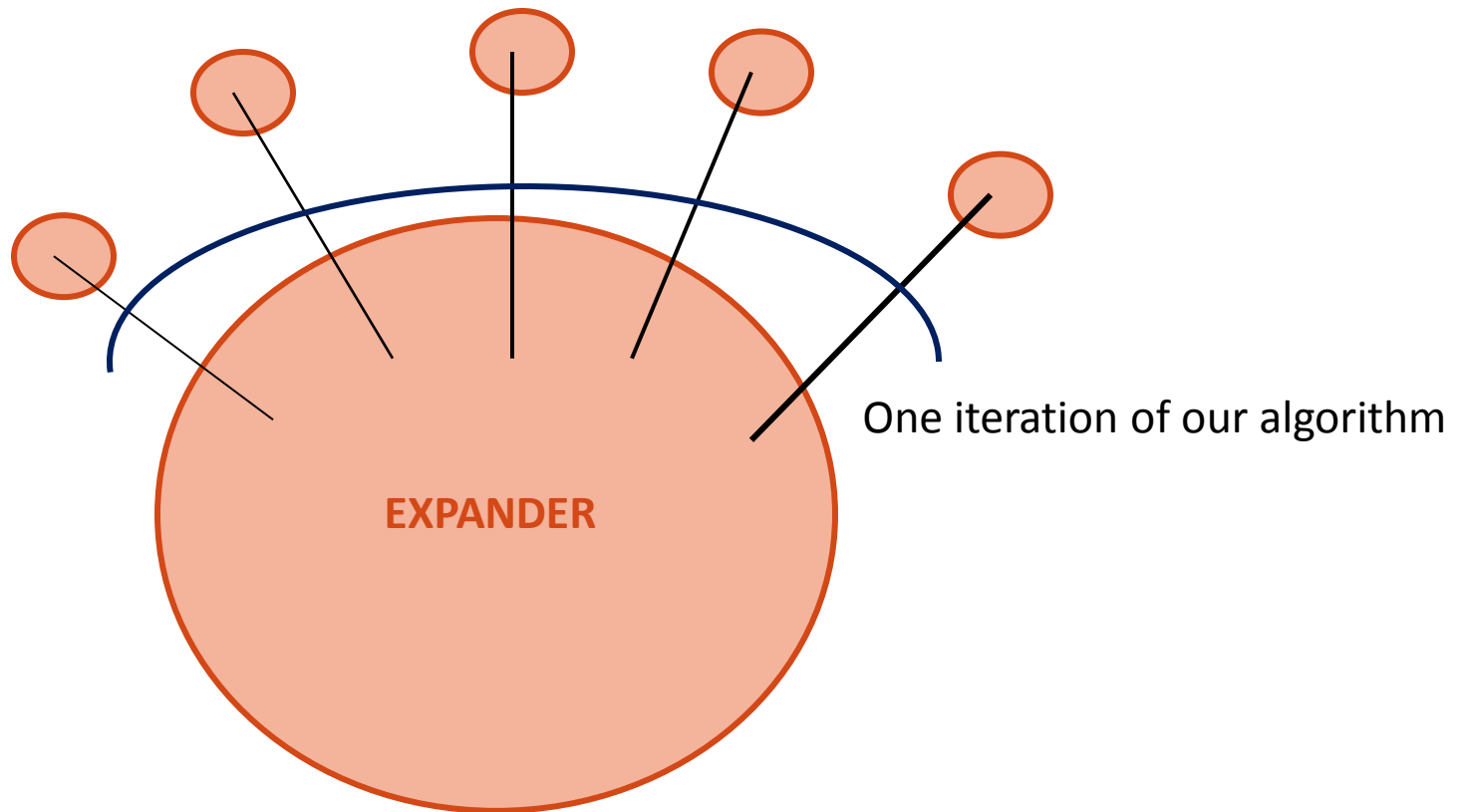
Comparison with Recursive Eigenvector

Recall worst-case example for Recursive Eigenvector:



Comparison with Recursive Eigenvector

Recall worst-case example for Recursive Eigenvector:



Running Time

- Our Algorithm runs in $O(\log n)$ iterations.
- In one iteration, we perform some **simple computation** (projection, sweep cut) on the vector embedding $H_{G^{(t)}}^\tau$.
This takes time $\tilde{O}(md)$, where d is the **dimension of the embedding**.

- Can use **Johnson-Lindenstrauss** to obtain $d = O(\log n)$.
- Hence, we only need to compute $O(\log^2 n)$ **matrix-vector products**

$$H_{G^{(t)}}^\tau u$$

- We show how to perform one such product in time $\tilde{O}(m)$ for all τ .
- **OBSTACLE:**
 τ , the mean number of steps in the Heat-Kernel random walk, is $\Omega(n^2)$ for path.

PART 2

Matrix Exponential Computation

Computation of Matrix Exponential

GOAL: For symmetric diagonally-dominant A , with sparsity m , compute vector v such that

$$\|e^{-A}u - v\| \leq \frac{1}{\text{poly}(n)}$$

in time $\tilde{O}(m)$.

Computation of Matrix Exponential

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Lanczos method: $\tilde{O}(\sqrt{\|A\|})$ matrix-vector multiplications by A

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KNOWN:

Lanczos method: $\tilde{O}(\sqrt{\|A\|})$ matrix-vector multiplications by A

$$A = \frac{\log n}{\gamma} L$$

$$\|A\| = \tilde{O}\left(\frac{1}{\gamma}\right)$$



$$\text{Running Time: } \tilde{O}\left(\frac{m}{\sqrt{\gamma}}\right)$$

Review of Lanczos Method

IDEA: Perform k matrix-vector multiplications

$$\{u, Au, A^2u, A^3u, A^4u, \dots, A^k u\}$$

Review of Lanczos Method

IDEA: Perform k matrix-vector multiplications

$$R_k = \text{Span}\{u, Au, A^2u, A^3u, A^4u, \dots, A^k u\} \quad \begin{array}{l} k\text{-Krylov} \\ \text{Subspace} \end{array}$$

Compute **orthonormal basis** Q_k for R_k , consider A restricted to R_k

$$T_k = Q_k A Q_k^T$$

Review of Lanczos Method

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Compute **orthonormal basis** Q_k for R_k , consider A restricted to R_k

$$T_k = Q_k A Q_k^T$$

As k grows, T_k is better approximation to A .

For many functions f , even for **small** k

$$Q_k f(T_k) Q_k^T \approx f(A)$$

Review of Lanczos Method

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As k grows, T_k is better approximation to A .

For many functions f , even for **small** k

$$Q_k f(T_k) Q_k^T \approx f(A)$$

True if f is close to a **polynomial** of degree $< k$

Lanczos Method and Approximation

CLAIM: There exists a polynomial p such that

$$\sup_{x \in (0, \|A\|)} |p(x) - e^{-x}| \leq \frac{1}{\text{poly}(n)}$$

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OPTIMAL for this approach

Lanczos Method II: Inverse Iteration

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CLAIM: $k = O(\log n)$ matrix-vector multiplication by B

RUNNING TIME: Multiplication by B is SDD linear system

$\tilde{O}(m)$ Time per multiplication  $\tilde{O}(m)$ Total running time

Lanczos Method II: Conclusion

$$\|e^{-A}u - v\| \cdot \delta$$

GENERAL RESULT:

- For general SDD matrix A , running time is

$$\tilde{O}((m + n) \cdot \log(2 + \|A\|) \cdot \text{polylog}(1/\delta))$$

CONTRIBUTION: Analysis has a number of obstacles

- Linear solver is approximate: **error propagation** in Lanczos
- **Loss of symmetry**

Conclusion

NOVEL ALGORITHMIC CONTRIBUTIONS

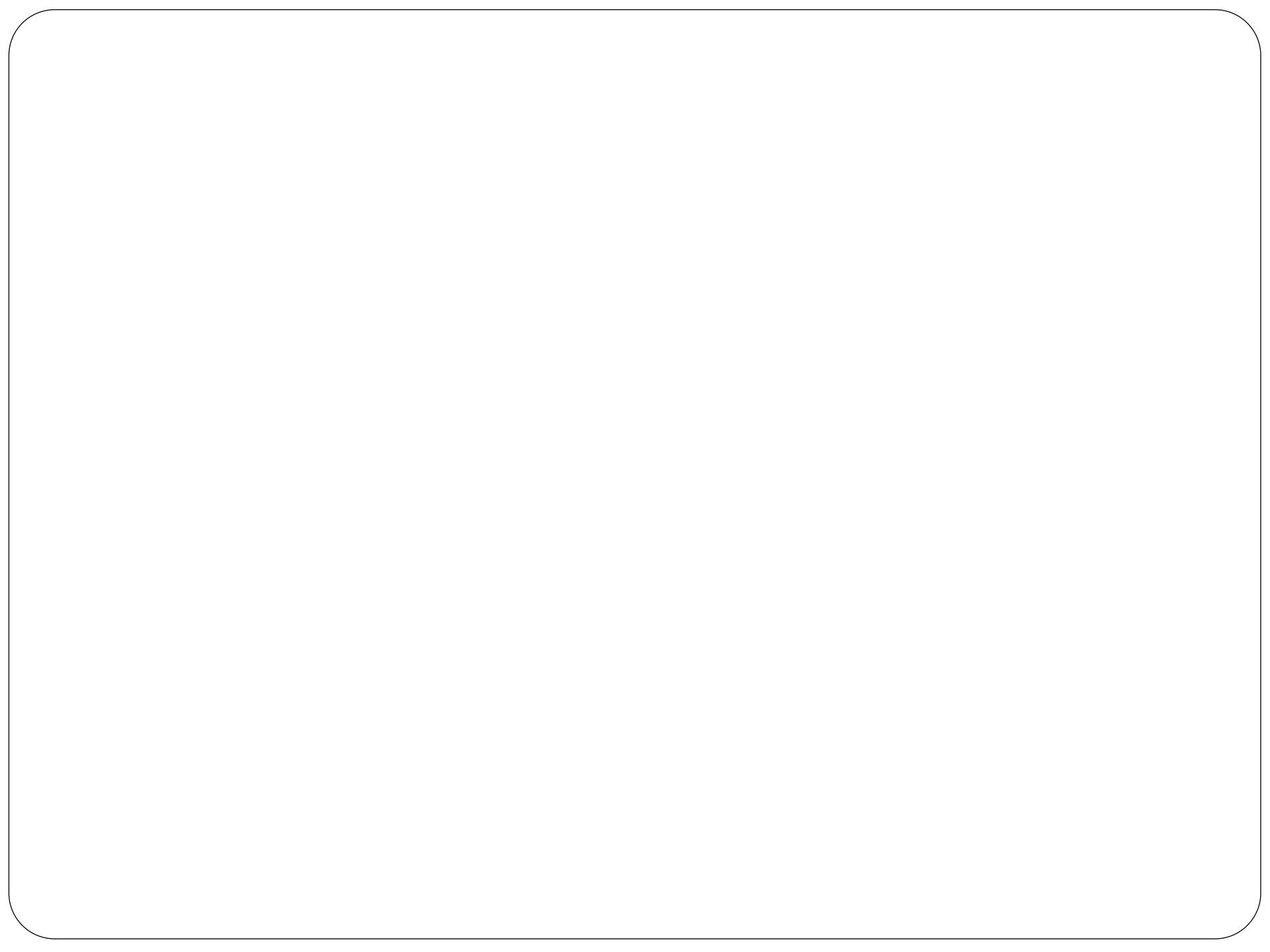
- Balanced-Cut Algorithm using Random Walks in time $\tilde{O}(m)$
- Computing the Heat-Kernel vectors in time $\tilde{O}(m)$

MAIN IDEA

Random walks provide a very useful
stable analogue of the graph eigenvector
via regularization

OPEN QUESTION

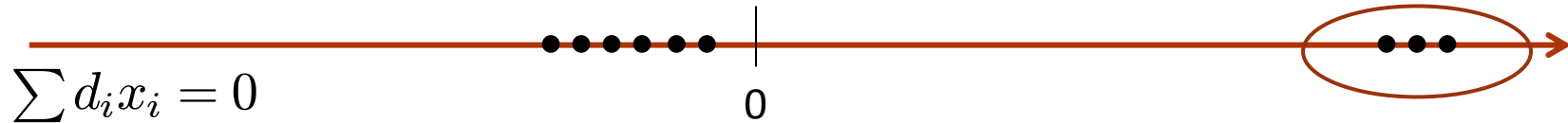
More applications of this idea?
Applications beyond design of fast algorithms?



A Different Interpretation

THEOREM:

Suppose eigenvector x yields an **unbalanced cut** S of low conductance and **no balanced cut** of the required conductance.



Then,

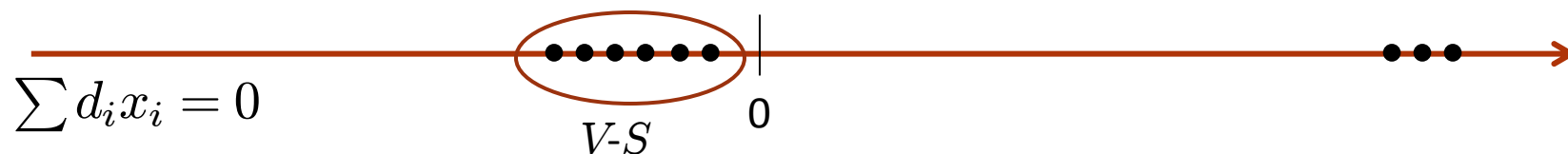
$$\sum_{i \in S} d_i x_i^2 \geq \frac{1}{2} \sum_{i \in V} d_i x_i^2.$$

In words, S contains **most of the variance** of the eigenvector.

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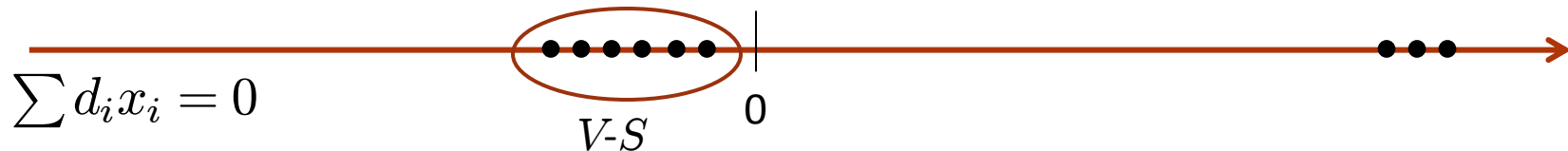
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QUESTION: Does this mean the graph induced by G on $V-S$ is **much closer** to have conductance at least γ ?

ANSWER: NO. x may contain little or no information about G on $V-S$.

Next eigenvector may be only **infinitesimally larger**.

CONCLUSION: To make significant progress, we need an analogue of the eigenvector that captures sparse

Theorems for Our Algorithm

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$$\Psi(P^{(t)}, V) > \frac{1}{\text{poly}(n)} \longrightarrow \text{Can find cut of conductance } O(\sqrt{\gamma})$$

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$$P^{(t)} = e^{-\tau Q^{(t)}} \quad \tau = \log n / \gamma \quad \Psi(P, V) = \sum_{i \in V} \|Pe_i - \vec{1}/n\|^2$$

Use the definition of τ . The spectrum of $P^{(t)}$ implies that

$$\underbrace{\sum_{ij \in E} \|P^{(t)}e_i - P^{(t)}e_j\|^2}_{\text{EDGE LENGTH}} \cdot O(\gamma) \cdot \underbrace{\Psi(P^{(t)}, V)}_{\text{TOTAL VARIANCE}}$$

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Hence, by a random projection of the embedding $\{P e_i\}$, followed by a sweep cut, we can recover the required cut.

SDP ROUNDING TECHNIQUE

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This is a certificate that no $\Omega(1)$ -balanced cut of conductance $O(\gamma)$ exists, as evaluating the quadratic form for a vector representing a balanced cut U yields

$$\phi(U) \geq - (\gamma) - \frac{\text{vol}(S)}{\text{vol}(U)} O(\gamma) \geq - (\gamma)$$

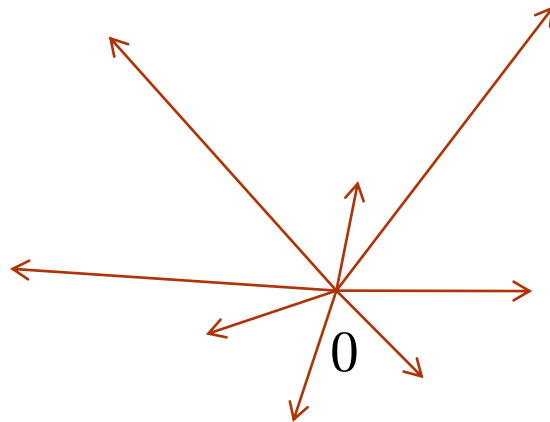
as long as S is sufficiently unbalanced.

SDP Interpretation

$$\mathbb{E}_{\{i,j\} \in E_G} \|v_i - v_j\|^2 \leq \gamma, \quad \text{SHORT EDGES}$$

$$\mathbb{E}_{\{i,j\} \in V \times V} \|v_i - v_j\|^2 = \frac{1}{2m}, \quad \text{FIXED VARIANCE}$$

$$\forall i \in V \quad \mathbb{E}_{j \in V} \|v_i - v_j\|^2 = \frac{1}{b} \cdot \frac{1}{2m}. \quad \text{LENGTH OF STAR EDGES}$$



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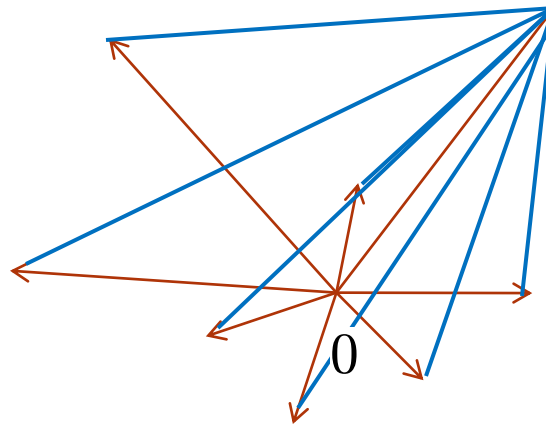
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SHORT RADIUS