

Isoperimetric Inequalities For Real-Valued Functions with Applications to Monotonicity Testing

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November 23, 2020

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Overview

For Boolean functions on the hypercube: $f: \{0,1\}^d \rightarrow \{0,1\}$.

Undirected

- Margulis '74
- Talagrand '93



Directed

- Chakrabarty and Seshadhri '13
- Khot, Minzer, Safra '15

We generalize these inequalities to **real-valued** functions: $f: \{0,1\}^d \rightarrow \mathbb{R}$.

Motivation:

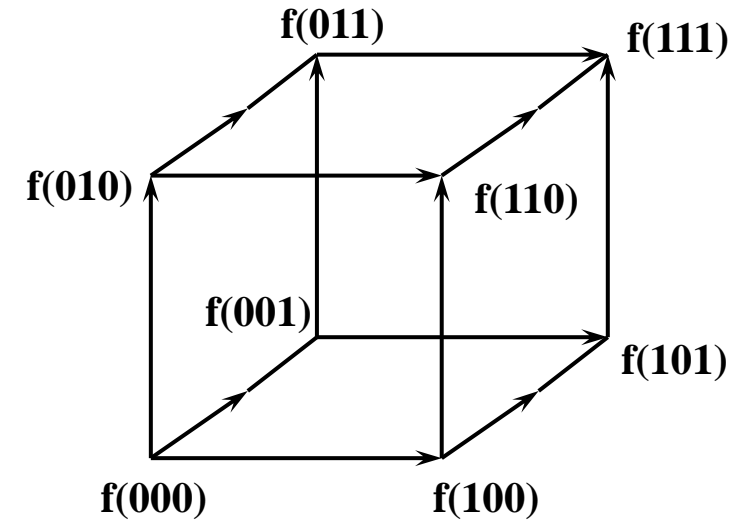
- To understand the structure of real-valued functions.
- To improve sublinear algorithms for monotonicity.

Plan

1. Explain our results in monotonicity testing.
2. Give some background on the inequalities.
3. Prove our generalized inequalities.

The d -dimensional hypercube

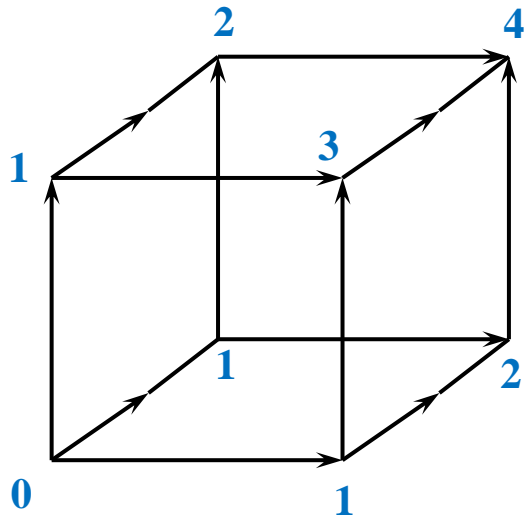
- Hypercube has 2^d vertices, the points in $\{0,1\}^d$.
- $x \rightarrow y$ is an edge if:
 - $x_i = 0, y_i = 1$
 - $x_j = y_j$ for all $j \in [n] \setminus \{i\}$



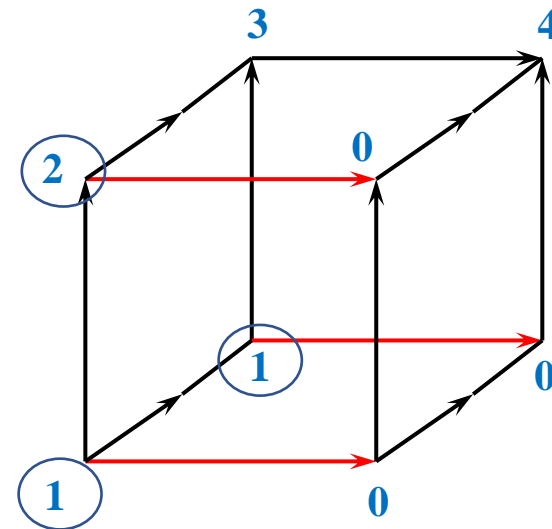
- f is **monotone** if the value of f along every edge does not decrease.
- Edge $x \rightarrow y$ is **influential** if $f(x) \neq f(y)$.
- Edge $x \rightarrow y$ is **violated** if $f(x) > f(y)$.

Distance to monotonicity

- Let $\text{dist}(f, \text{mono})$ denote the distance of f to monotonicity
- $\text{dist}(f, \text{mono})$ = least number values of f that need to be changed to make f monotone



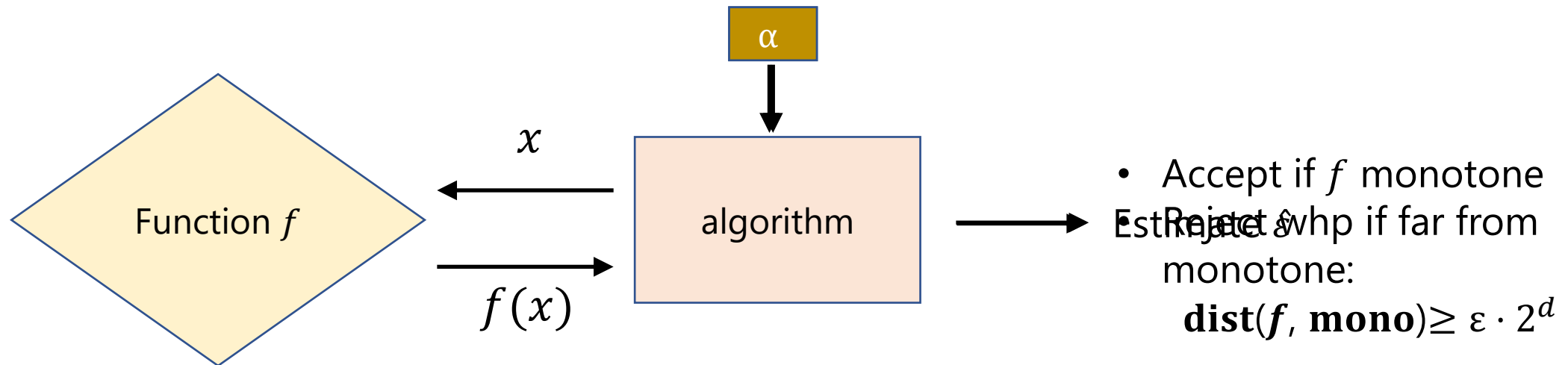
$$\text{dist}(f, \text{mono}) = 0$$



$$\text{dist}(f, \text{mono}) = 3$$

Algorithmic tasks

- Monotonicity testing: [Rubinfeld Sudan '96] [Goldreich Goldwasser Ron '98]
[Goldreich Goldwasser Lehman Ron Samorodnitsky '00]



- Approximating distance to monotonicity: [Parnas, Ron, Rubinfeld '06], [Fattal, Ron '10]

○ Given oracle access to f s.t. $\mathbf{dist}(f, \mathbf{mono}) \geq \alpha \cdot 2^d$. ← can turn this into additive error

○ Achieves c -approximation if it returns estimate $\hat{\varepsilon}$ that whp:

$$\mathbf{dist}(f, \mathbf{mono}) \leq \hat{\varepsilon} \leq c \cdot \mathbf{dist}(f, \mathbf{mono})$$

Results – Monotonicity Testing

Extensively studied problem

[Ergun, Kannan, Kumar, Rubinfeld, Viswanathan '00][Dodis Goldreich Lehman Raskhodnikova '99][Lehman Ron '01][Ailon Chazelle '06][Fischer '04][Halevy Kushilevitz '08][Batu Rubinfeld White '05][Ailon Chazelle Seshadhri Liu '07][Bhattacharyya Grigorescu Jung Raskhodnikova Woodruff '12][Briet Chakraborty Soriano Matsliah '12][Blais Raskhodnikova Yaroslavtsev '14][Chakrabarty Seshadhri '13'14'16'19][Chen Servedio Tan '14][Belovs Blais '16][Pallavoor Raskhodnikova Varma '18][Black Chakrabarty Seshadhri '18'20]

Functions on the hypercube $\{0,1\}^d$, r = number of distinct values of f .

	Boolean	Real-Valued (Previous)	Real-Valued (Our results)
Upper bounds	$\tilde{O}\left(\frac{\sqrt{d}}{\varepsilon^2}\right)$ <p>[Khot Minzer Safra '15]</p>	$o\left(\frac{d}{\varepsilon}\right)$ <p>[Chakrabarty Seshadhri '13]</p>	$\tilde{O}\left(\min\left(\frac{r\sqrt{d}}{\varepsilon^2}, \frac{d}{\varepsilon}\right)\right)$
Lower Bounds	<p>Nonadaptive: $\tilde{\Omega}(\sqrt{d})$ [Fischer Lehman Newman Raskhodnikova Rubinfeld '02] [Chen De Servedio Tan '15] [Chen Waingarten Xie '17]</p> <p>Adaptive: $\tilde{\Omega}(d^{1/3})$ [Chen Waingarten Xie '17]</p>	$\Omega(\min(d, r^2))$ <p>[Blais Brody Matulef '12]</p>	$\Omega(\min(r\sqrt{d}, d))$ Nonadaptive, 1-sided error

nonadaptive =
tester makes all its
queries in advance

Results – Distance Approximation

Functions on the hypercube: $\{0,1\}^d$, $r =$ number of distinct values of f

	Boolean	Real-Valued (Previous)	Real-Valued (Our results)
Upper bounds	$\sqrt{d \log d}$ -factor [Pallavoor Raskhodnikova Waingarten '20]	$d \log r$ -factor [Fattal Ron '10]	$\sqrt{d \log d}$ -factor no dependence on r
Lower bounds	\sqrt{d} - factor (nonadaptive) [Pallavoor Raskhodnikova Waingarten '20]		

All algorithms have query complexity $\text{poly}(d, \frac{1}{\alpha})$

Isoperimetric Inequalities (Undirected)

- An edge (x, y) is **influential** if $f(x) \neq f(y)$.
- Let $I_f(x) = \#$ **influential** edges (x, y) s.t. $f(x) > f(y)$.

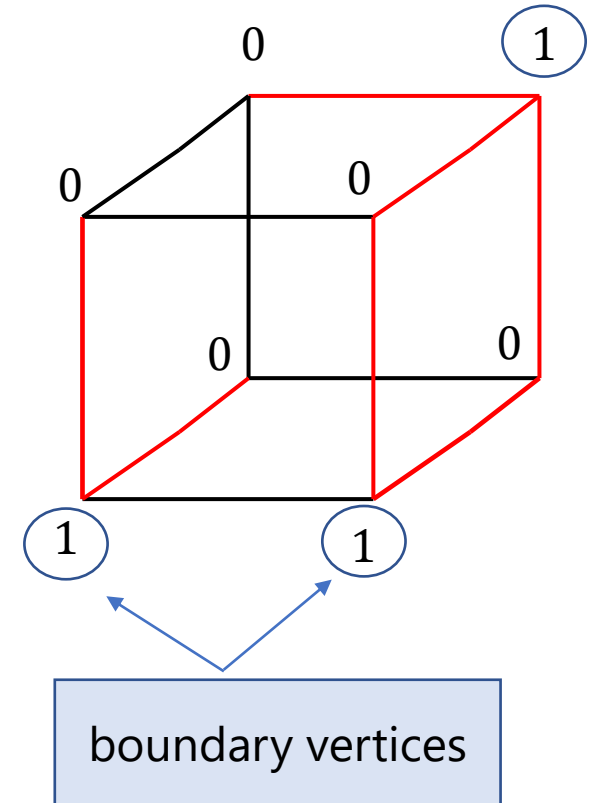
- [Talagrand '93] For a Boolean function f ,

$$\sum_{x \in \{0,1\}^d} \left[\sqrt{I_f(x)} \right] = \Omega(\text{var}(f)) \cdot 2^d$$

$p_0 =$ fraction of zeros
 $\text{var}(f) = p_0(1 - p_0)$

- [Margulis '74] For a Boolean function f ,

$$\frac{(\# \text{influential edges}) \cdot (\# \text{boundary vertices})}{2^{2d}} = \Omega(\text{var}(f)^2)$$



Isoperimetric Inequalities (Directed)

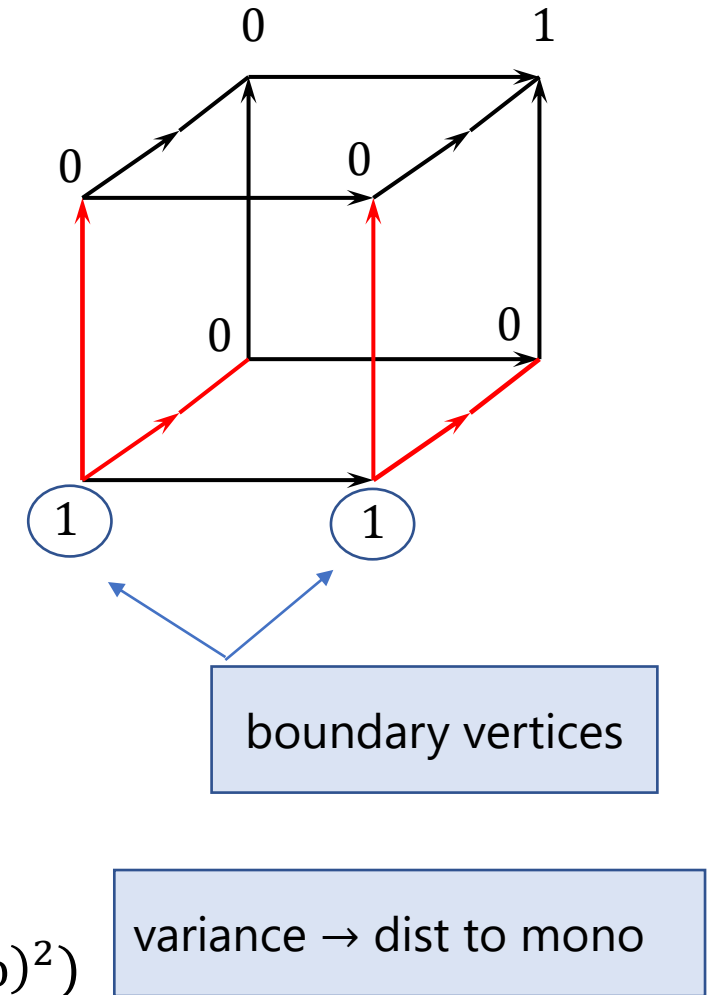
- An edge $x \rightarrow y$ is **violated** if $f(x) > f(y)$.
- Let $I_f^-(x) = \#$ outgoing **violated** edges at x .

- [Khot Minzer Safra '15] For a Boolean function f ,
[Pallavoor Raskhodnikova Waingarten '20]

$$\sum_{x \in \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] = \Omega(\text{dist}(f, \text{mono}))$$

- [Chakrabarty Seshadhri '13] For a Boolean function f ,

$$(\# \text{violated edges}) \cdot (\# \text{boundary vertices}) = \Omega(\text{dist}(f, \text{mono})^2)$$



Our inequalities

- **(Directed)** For all real-valued functions $f: \{0,1\}^d \rightarrow \mathbb{R}$:

$I_f^-(x) = \#$ outgoing **violated** edges at x

$$\sum_{x \in \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] = \Omega(\text{dist}(f, \text{mono}))$$

no dependence on the range of f

- **(Undirected)** For all real-valued functions $f: \{0,1\}^d \rightarrow \mathbb{R}$:

$I_f(x) = \#$ **influential** edges at x

$$\sum_{x \in \{0,1\}^d} \left[\sqrt{I_f(x)} \right] = \Omega(\text{dist}(f, \text{constant}))$$

Number of values that need to be changed to make f constant

For a Boolean function, variance and normalized distance to constant are within a factor of 2

We don't care about the magnitude of change

Main inequality

$$I_f^-(x) = \# \text{ outgoing violated edges at } x$$

- **(Directed)** For all real-valued functions $f: \{0,1\}^d \rightarrow \mathbb{R}$:

$$\sum_{x \in \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] = \Omega(\text{dist}(f, \text{mono}))$$

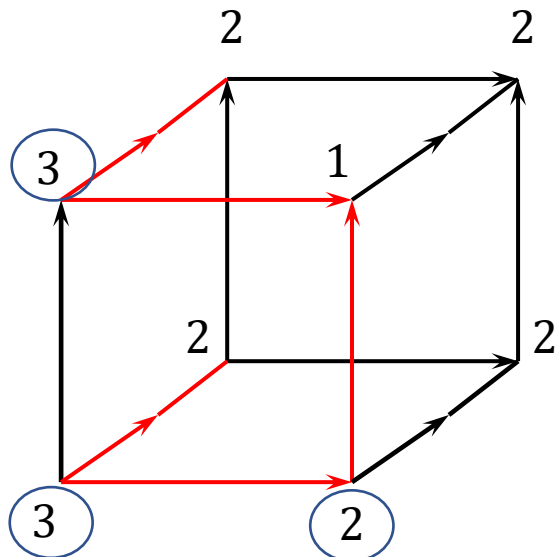
- Inequality we use for our applications.
- Implies all other inequalities mentioned in this talk.
- We show how to prove it.

Main inequality

$$I_f^-(x) = \# \text{ outgoing violated edges at } x$$

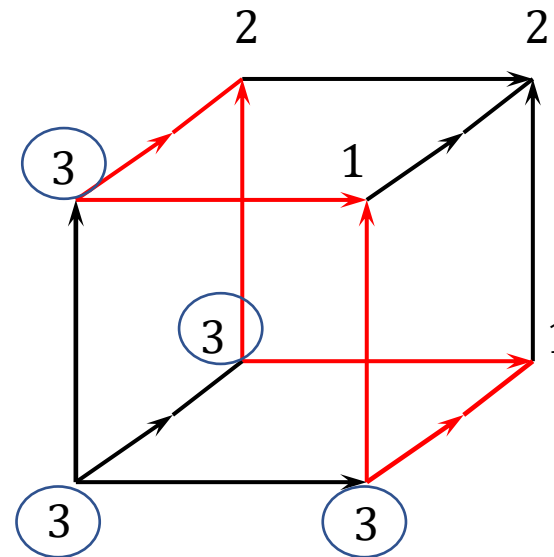
- **(Directed)** For all real-valued functions $f: \{0,1\}^d \rightarrow \mathbb{R}$:

$$\sum_{x \in \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] = \Omega(\text{dist}(f, \text{mono}))$$



$$\text{dist}(f, \text{mono}) = 3$$

$$\sum_{x \sim \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] = \sqrt{2} + \sqrt{2} + \sqrt{1}$$



$$\text{dist}(f, \text{mono}) = 4$$

$$\sum_{x \sim \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] = \sqrt{2} + \sqrt{2} + \sqrt{2}$$

Main inequality

$$I_f^-(x) = \# \text{ outgoing violated edges at } x$$

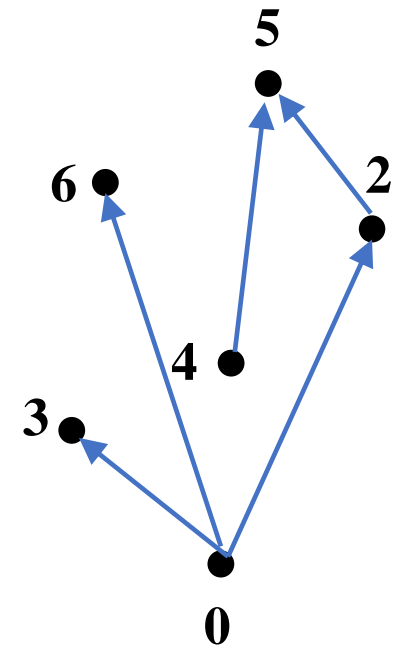
- **(Directed)** For all real-valued functions $f: \{0,1\}^d \rightarrow \mathbb{R}$:

$$\sum_{x \in \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] = \Omega(\text{dist}(f, \text{mono}))$$

- We prove it by reducing to the Boolean case, via [Boolean Decomposition Theorem](#).

Boolean Decomposition Theorem

- It works for every partially ordered domain, which we represent as a DAG G .
- Monotonicity testing on posets first considered by [\[Fischer Lehman Newman Raskhodnikova Rubinfeld '02\]](#).
- Vertices $V(G)$, edges $E(G)$.
- $x \preceq y$ iff there is directed path from x to y .
- Edge $x \rightarrow y$ is violated if $f(x) > f(y)$.



$$f: V(G) \rightarrow \mathbb{R}$$

Boolean Decomposition Theorem

- Let $\text{VIOL}(f)$ denote the violated edges of f .

BD Theorem: Let G be a DAG, and $f: V(G) \rightarrow \mathbb{R}$ a nonmonotone function. For some $k \geq 1$, there exist **Boolean functions** $f_1, f_2, \dots, f_k: V(G) \rightarrow \{0,1\}$ and **disjoint subgraphs** H_1, H_2, \dots, H_k of G such that:

$$(1) \sum_{i \in [k]} \text{dist}(f_i, \text{mono}) \geq \frac{1}{2} \text{dist}(f, \text{mono})$$

collectively capture distance to monotonicity of f

$$(2) \text{VIOL}(f_i) \subseteq \text{VIOL}(f)$$

edges violated by f_i are also violated by f

$$(3) \text{VIOL}(f_i) \subseteq E(H_i)$$

edges violated by f_i are contained in H_i

BD Theorem → Main inequality

$I_f^-(x) = \#$ outgoing **violated** edges at x

$$\sum_{x \in \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] \geq \sum_{x \in \cup H_i} \left[\sqrt{I_f^-(x)} \right]$$

$\cup H_i$ is a subgraph of original graph

$$\geq \sum_{i \in [k]} \sum_{x \in H_i} \left[\sqrt{I_f^-(x)} \right]$$

the H_i are disjoint subgraphs

$$\geq \sum_{i \in [k]} \sum_{x \in H_i} \left[\sqrt{I_{f_i}^-(x)} \right]$$

edges violated by f_i are a subset of edges violated by f

edges violated by f_i are in H_i

from the Boolean case

$$\geq \sum_{i \in [k]} C \cdot \text{dist}(f_i, \text{mono}) \geq \frac{C}{2} \cdot \text{dist}(f, \text{mono})$$

capture $\text{dist}(f, \text{mono})$

Proof of BD Theorem

BD Theorem: Let G be a DAG, and $f: V(G) \rightarrow \mathbb{R}$ a nonmonotone function. For some $k \geq 1$, there exist **Boolean functions** $f_1, f_2, \dots, f_k: V(G) \rightarrow \{0,1\}$ and **disjoint subgraphs** H_1, H_2, \dots, H_k of G such that:

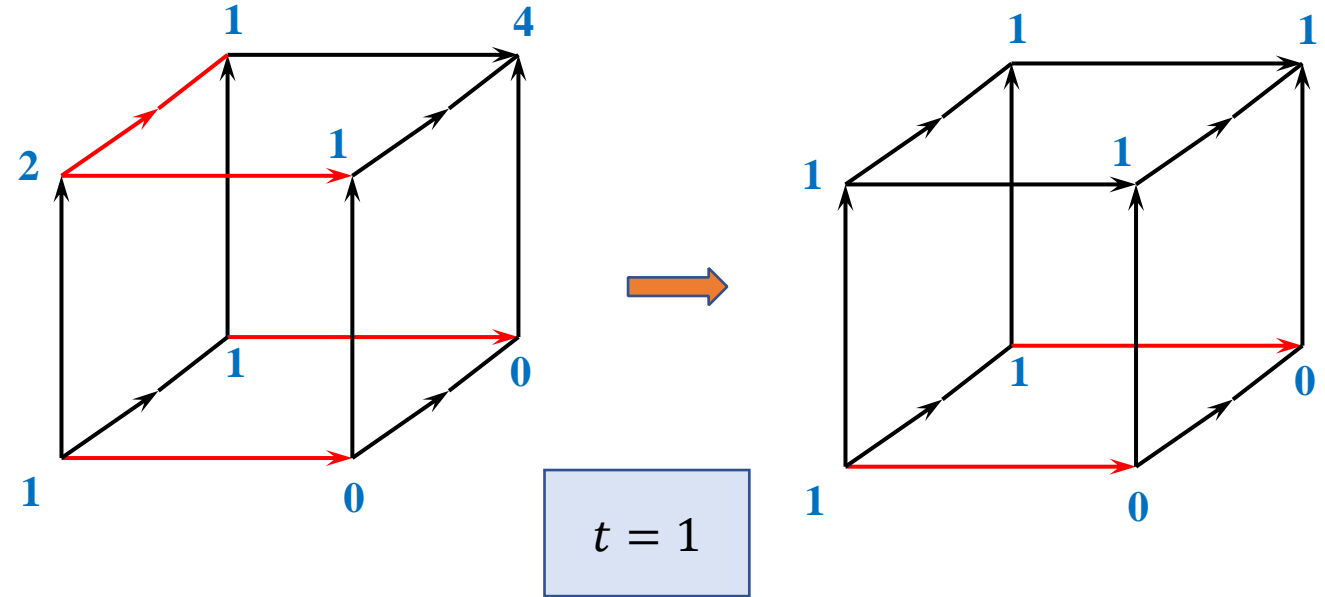
$$(1) \sum_{i \in [k]} \text{dist}(f_i, \text{mono}) \geq \frac{\text{dist}(f, \text{mono})}{2} \quad (2) \text{VIOL}(f_i) \subseteq \text{VIOL}(f) \quad (3) \text{VIOL}(f_i) \subseteq E(H_i)$$

$$\Rightarrow \text{Main inequality } \sum_{x \in \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] = \Omega(\text{dist}(f, \text{mono}))$$

Thresholding intuition

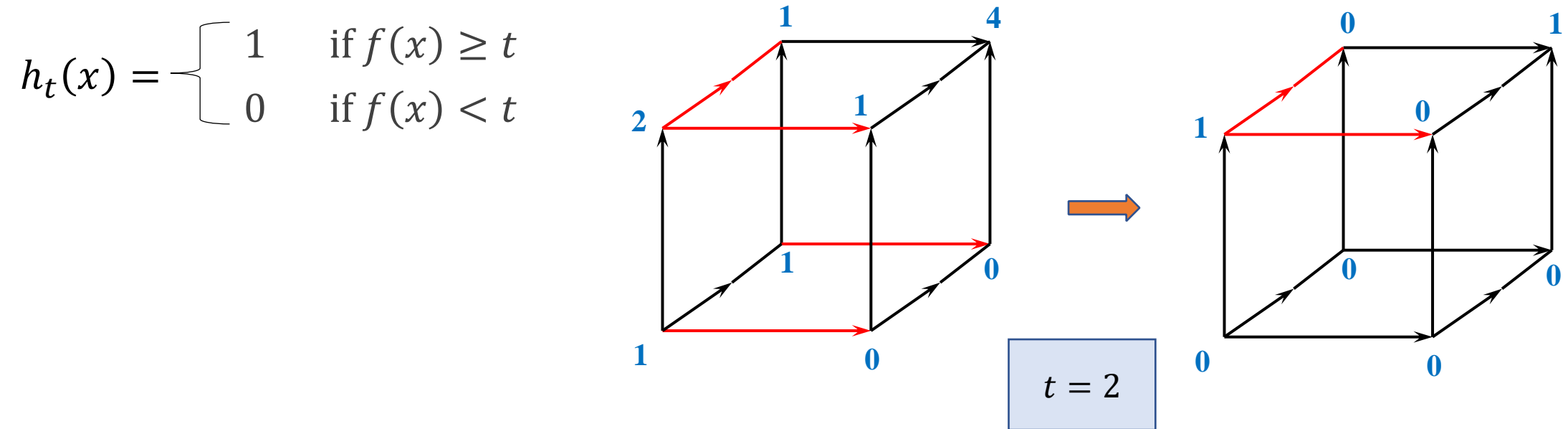
We can reduce from real-valued to Boolean functions via [thresholding](#).

$$h_t(x) = \begin{cases} 1 & \text{if } f(x) \geq t \\ 0 & \text{if } f(x) < t \end{cases}$$



Thresholding intuition

We can reduce from real-valued to Boolean functions via [thresholding](#).



- Edges violated by h_t are a subset of the edges violated by f .
- But $\text{dist}(f, \text{mono})$ can decrease by a factor of r (# distinct values of f)
- Can construct function so that $\text{dist}(f, \text{mono})$ decreases by r for all thresholds $t \in [r]$.
- BD Theorem allows us to apply different thresholds in disjoint locations of hypercube.

Proof of BD Theorem

BD Theorem: Let G be a DAG, and $f: V(G) \rightarrow \mathbb{R}$ a nonmonotone function. For some $k \geq 1$, there exist **Boolean functions** $f_1, f_2, \dots, f_k: V(G) \rightarrow \{0,1\}$ and **disjoint subgraphs** H_1, H_2, \dots, H_k of G such that:

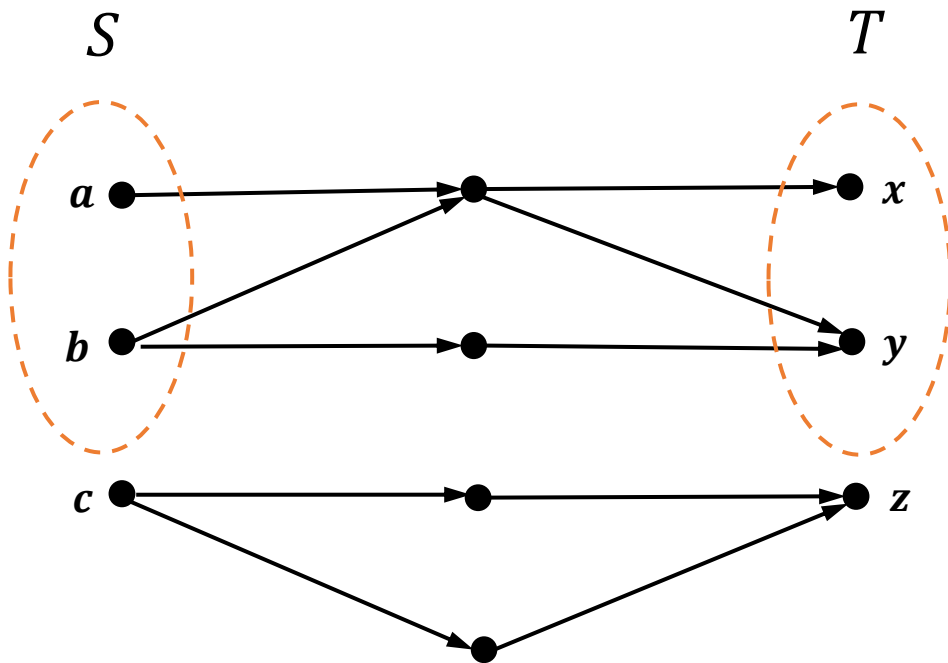
$$(1) \sum_{i \in [k]} \text{dist}(f_i, \text{mono}) \geq \frac{\text{dist}(f, \text{mono})}{2} \quad (2) \text{VIOL}(f_i) \subseteq \text{VIOL}(f) \quad (3) \text{VIOL}(f_i) \subseteq E(H_i)$$

1. How to obtain disjoint subgraphs H_i from a matching of vertices.
2. Specify a special matching.
3. Define Boolean functions f_i given subgraphs H_i .
4. Prove desired properties of f_i .

Step 1: Disjoint Subgraphs H_i

Definition (Sweeping Graphs) For two disjoint sets of vertices $S, T \subseteq V(G)$:

subgraph $\text{Sweep}(S, T)$ = subgraph formed from union of all directed paths from vertices in S to vertices in T

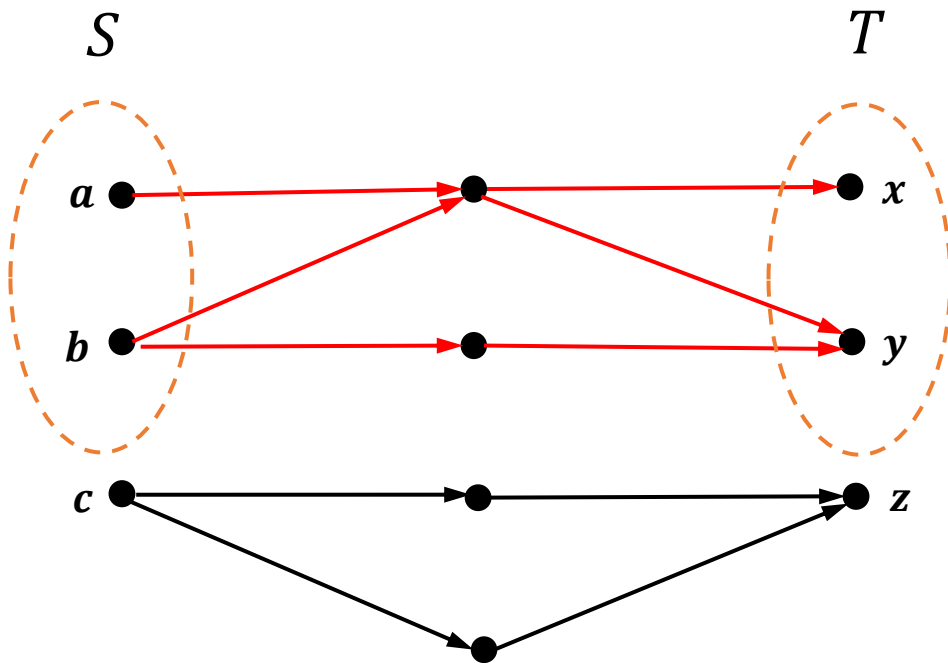


Call (S, T) a **set-pair**.

Step 1: Disjoint Subgraphs H_i

Definition (Sweeping Graphs) For two disjoint sets $S, T \subseteq V(G)$:

subgraph $\text{Sweep}(S, T)$ = subgraph formed from union of all directed paths from vertices in S to vertices in T



Useful properties:

- $\text{Sweep}(S, T)$ is an induced subgraph
- A vertex outside $\text{Sweep}(S, T)$ cannot be both "above" and "below" $\text{Sweep}(S, T)$

it has a path **from** a vertex in $\text{Sweep}(S, T)$

it has a path **to** a vertex in $\text{Sweep}(S, T)$

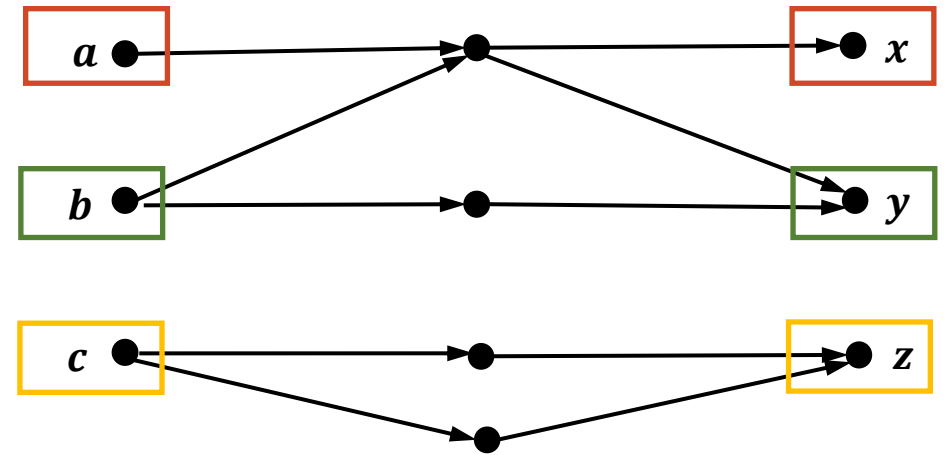
Step 1: Disjoint Subgraphs H_i

We consider matchings $M: S \rightarrow T$, where $S, T \subseteq V(G)$.

S = lower endpoints,
 T = upper endpoints

M contains disjoint pairs (x, y) of vertices such that $x \preceq y$.

A pair (x, y) in M is violated if $f(x) > f(y)$.



[Fischer Lehman Newman
Raskhodnikova Rubinfeld '02].

Fact. For every function f and maximal matching M of violated pairs:

$$|\text{maximal matching}| \leq \text{dist}(f, \text{mono}) \leq 2|\text{maximal matching}|$$

Step 1: Disjoint Subgraphs H_i

Recall $\text{Sweep}(X, Y)$ = subgraph of paths from vertices in X to vertices in Y

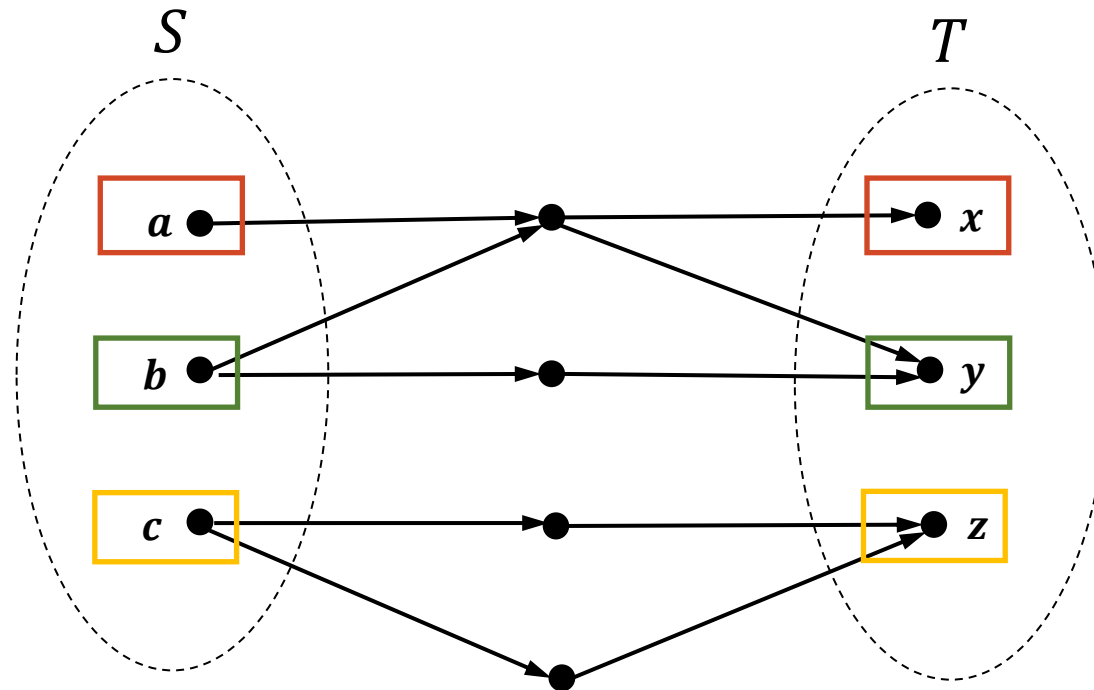
Two set-pairs of vertices (X, Y) and (X', Y') **conflict** if:

- $\text{Sweep}(X, Y)$ intersects $\text{Sweep}(X', Y')$.

Algorithm Merge-Conflicts:

- Input: matching $M: S \rightarrow T$
- Initialize **collection** of set-pairs $(\{s\}, \{t\})$ for all $(s, t) \in M$
- Repeat until there are no conflicts:
 - if two set-pairs (X, Y) and (X', Y') **conflict**, merge them,
 - i.e. remove them from **collection** of pairs, and add new pair $(X \cup X', Y \cup Y')$

Merge-Conflicts Illustration

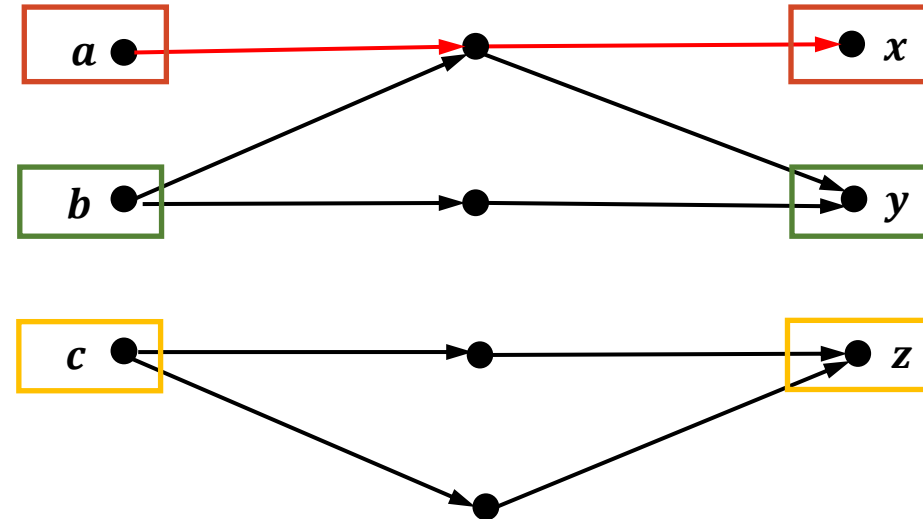


$$M = \{(a, x), (b, y), (c, z)\}$$

$$\text{Collection} = (\{a\}, \{x\}), (\{b\}, \{y\}), (\{c\}, \{z\})$$

Merge-Conflicts Illustration

Sweep($\{a\}, \{x\}$)
union of paths from $\{a\}$ to $\{x\}$



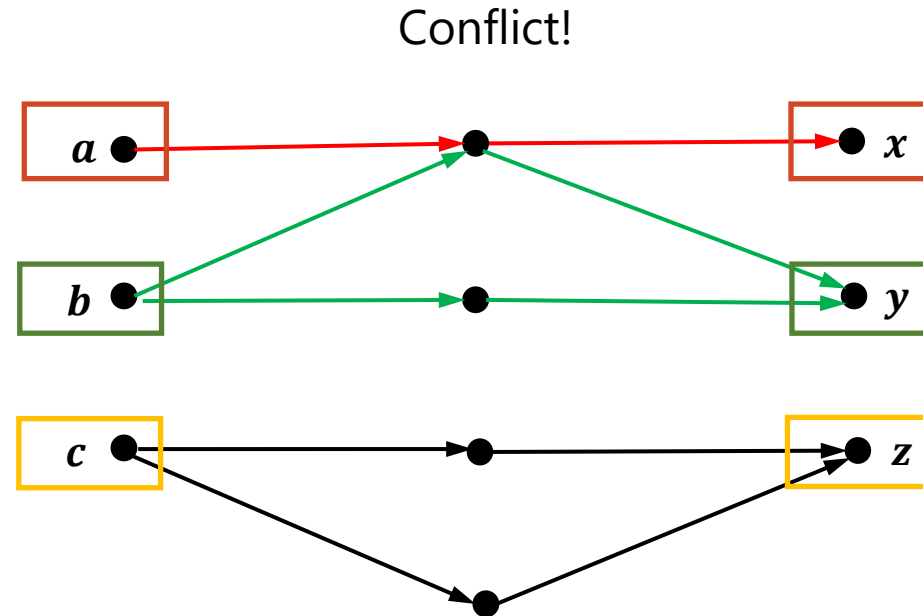
$$M = \{(a, x), (b, y), (c, z)\}$$

$$\text{Collection} = (\{a\}, \{x\}), (\{b\}, \{y\}), (\{c\}, \{z\})$$

Merge-Conflicts Illustration

Sweep($\{a\}, \{x\}$)
union of paths from $\{a\}$ to $\{x\}$

Sweep($\{b\}, \{y\}$)
union of paths from $\{b\}$ to $\{y\}$

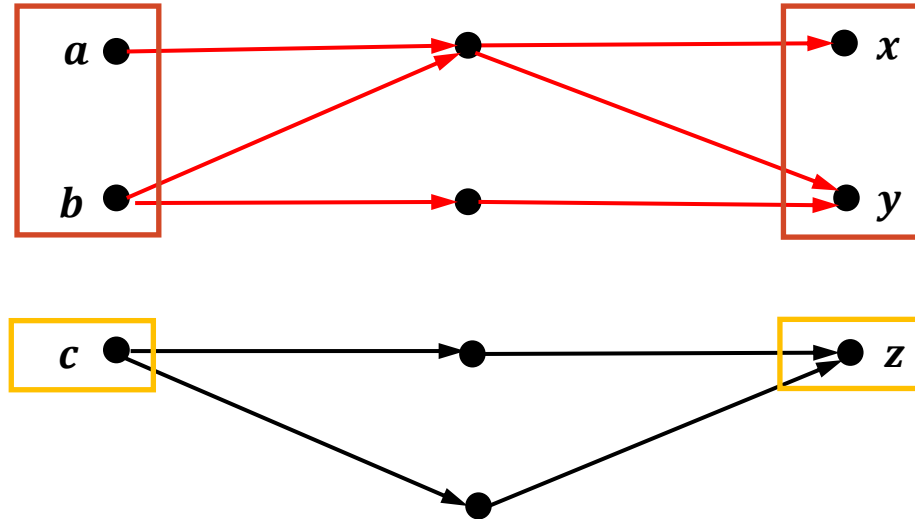


$$M = \{(a, x), (b, y), (c, z)\}$$

$$\text{Collection} = (\{a\}, \{x\}), (\{b\}, \{y\}), (\{c\}, \{z\})$$

Merge-Conflicts Illustration

Sweep($\{a, b\}, \{x, y\}$)
union of paths from $\{a, b\}$ to $\{x, y\}$

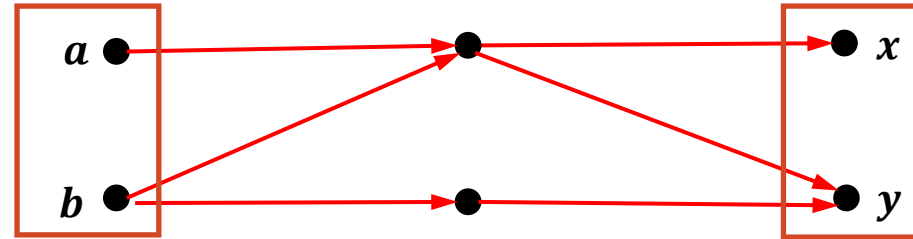


$$M = \{(a, x), (b, y), (c, z)\}$$

$$\text{Collection} = (\{a, b\}, \{x, y\}), (\{c\}, \{z\})$$

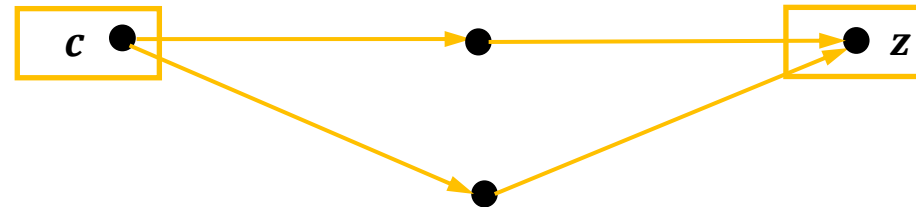
Merge-Conflicts Illustration

Sweep($\{a, b\}, \{x, y\}$)
union of paths from $\{a, b\}$ to $\{x, y\}$



No conflict!

Sweep($\{c\}, \{z\}$)
union of paths from $\{c\}$ to $\{z\}$



$$M = \{(a, x), (b, y), (c, z)\}$$

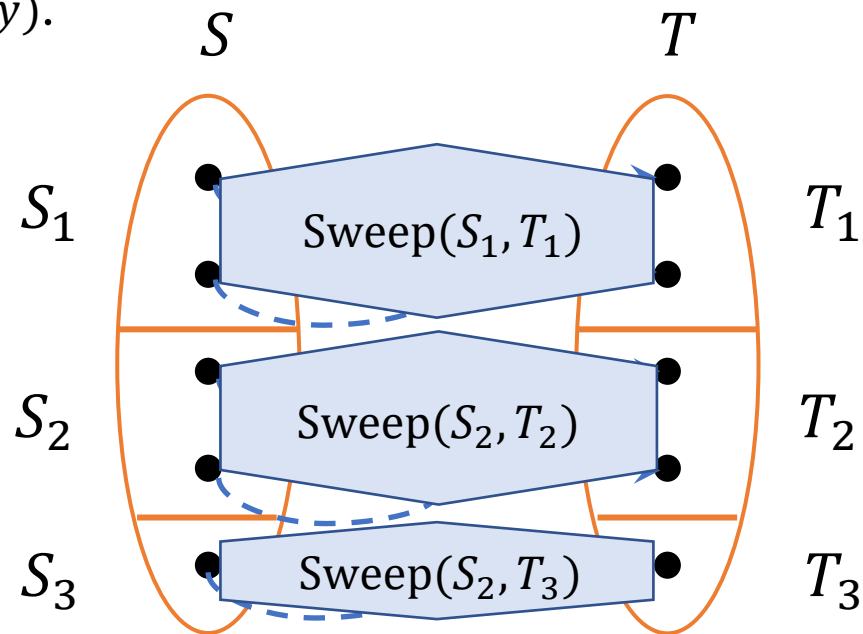
Collection = $(\{a, b\}, \{x, y\}), (\{c\}, \{z\})$

Final collection

Step 1: Disjoint Subgraphs H_i

Algorithm Merge-Conflicts with matching $M: S \rightarrow T$ gives set-pairs $(S_1, T_1), (S_2, T_2), \dots, (S_k, T_k)$ such that:

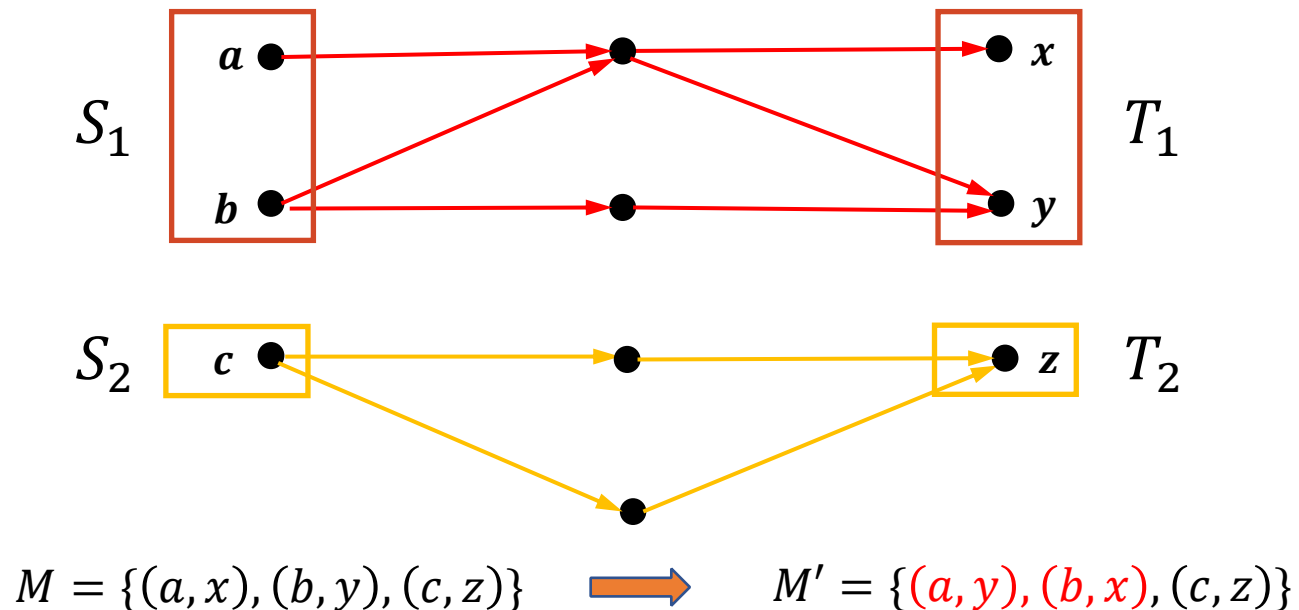
- The sets S_i partition S , the sets T_i partition T .
- The subgraphs $\text{Sweep}(S_i, T_i)$ are vertex-disjoint.
- **(Rematching property)** For $x \in S_i, y \in T_i$ such that $x \preceq y$: there exists another matching $M': S \rightarrow T$ that matches (x, y) .



Step 1: Disjoint Subgraphs H_i

Algorithm Merge-Conflicts with matching $M: S \rightarrow T$ gives set-pairs $(S_1, T_1), (S_2, T_2), \dots, (S_k, T_k)$ such that:

- The sets S_i partition S , the sets T_i partition T .
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Proof of BD Theorem

BD Theorem: Let G be a DAG, and $f: V(G) \rightarrow \mathbb{R}$ a nonmonotone function. For some $k \geq 1$, there exist **Boolean functions** $f_1, f_2, \dots, f_k: V(G) \rightarrow \{0,1\}$ and **disjoint subgraphs** H_1, H_2, \dots, H_k of G such that:

$$(1) \sum_{i \in [k]} \text{dist}(f_i, \text{mono}) \geq \frac{\text{dist}(f, \text{mono})}{2} \quad (2) \text{VIOL}(f_i) \subseteq \text{VIOL}(f) \quad (3) \text{VIOL}(f_i) \subseteq E(H_i)$$

- ✓ How to obtain disjoint subgraphs H_i from a matching of vertices.
- 2. Specify a special matching.
- 3. Define Boolean functions f_i given subgraphs H_i .
- 4. Prove desired properties of f_i .

Step 2: Special matching

Use a special matching M (max-weight, min-cardinality):

- it maximizes **weight** $\sum_{(x,y) \in M} (f(x) - f(y))$,
- and amongst such matchings has the fewest pairs.

- M is maximal
- all pairs in M are violated

Run algorithm Merge-Conflicts with special matching M .

Sweep(S_i, T_i) are the subgraphs H_i .

Violation Lemma. The set-pairs $(S_1, T_1), (S_2, T_2), \dots, (S_k, T_k)$ satisfy:

- For all $i \in [k]$, $x \in S_i$, $y \in T_i$, such that $x \preceq y$, we have $f(x) > f(y)$.

will need to be more careful about thresholding

can threshold while preserving violations.

Step 2: Special matching

Violation Lemma. The set-pairs $(S_1, T_1), (S_2, T_2), \dots, (S_k, T_k)$ obtained from the special matching M satisfy: For all $i \in [k]$, $x \in S_i$, $y \in T_i$, s.t. $x \preceq y$, we have $f(x) > f(y)$.

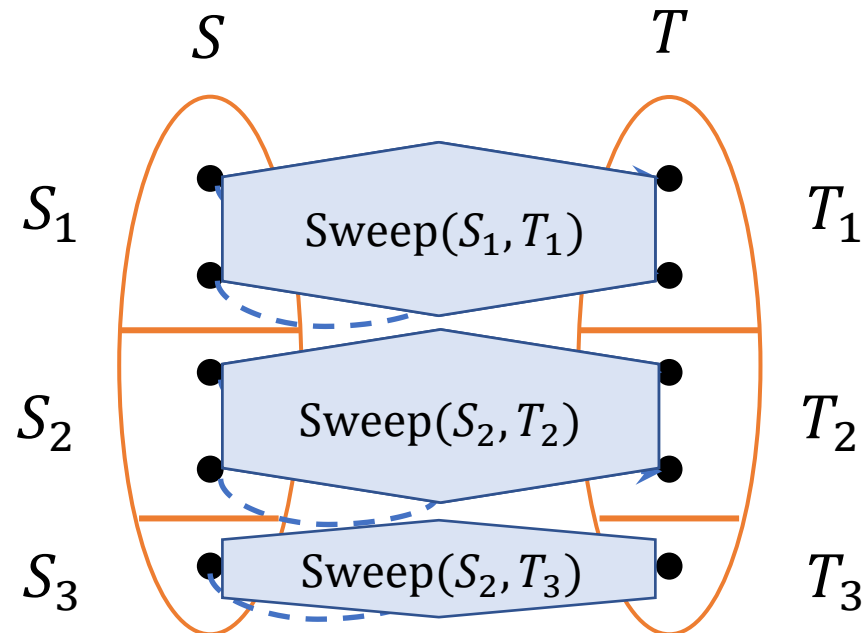
$$\text{weight: } \sum_{(x,y) \in M} (f(x) - f(y))$$

Proof.

- Suppose that for some $x \in S_i$, $y \in T_i$, with $x \preceq y$ we have $f(x) \leq f(y)$.
- Use the [rematching property](#) to get a new matching $M': S \rightarrow T$ that matches (x, y) .
- M' has the same weight as M , since the endpoints have not changed.
- $M' \setminus (x, y)$ has weight at least as big as M , because $f(x) - f(y) \leq 0$.
- But $M' \setminus (x, y)$ has fewer pairs. Contradiction.

Step 1+2 summary

- Start with special matching $M: S \rightarrow T$ (max weight, min-cardinality).
- M is a maximal matching of violated pairs: $|M| < \text{dist}(f, \text{mono}) < 2|M|$
- Run algorithm Merge-Conflicts to obtain set-pairs $(S_1, T_1), (S_2, T_2), \dots, (S_k, T_k)$
- The subgraphs $\text{Sweep}(S_i, T_i)$ are vertex-disjoint.
- **(Violation Lemma)** For $x \in S_i, y \in T_i$ such that $x \preceq y$ we have $f(x) > f(y)$.



Proof of BD Theorem

BD Theorem: Let G be a DAG, and $f: V(G) \rightarrow \mathbb{R}$ a nonmonotone function. For some $k \geq 1$, there exist **Boolean functions** $f_1, f_2, \dots, f_k: V(G) \rightarrow \{0,1\}$ and **disjoint subgraphs** H_1, H_2, \dots, H_k of G such that:

$$(1) \sum_{i \in [k]} \text{dist}(f_i, \text{mono}) \geq \frac{\text{dist}(f, \text{mono})}{2} \quad (2) \text{VIOL}(f_i) \subseteq \text{VIOL}(f) \quad (3) \text{VIOL}(f_i) \subseteq E(H_i)$$

- ✓ How to obtain disjoint subgraphs H_i from a matching of vertices.
- ✓ Specify a special matching.
- 3. Define Boolean functions f_i given subgraphs H_i .
- 4. Prove desired properties of f_i .

Step 3: Define Boolean Functions

Given (S_i, T_i) , define $f_i: V(G) \rightarrow \{0,1\}$

max value of f achieved by points in T_i above z

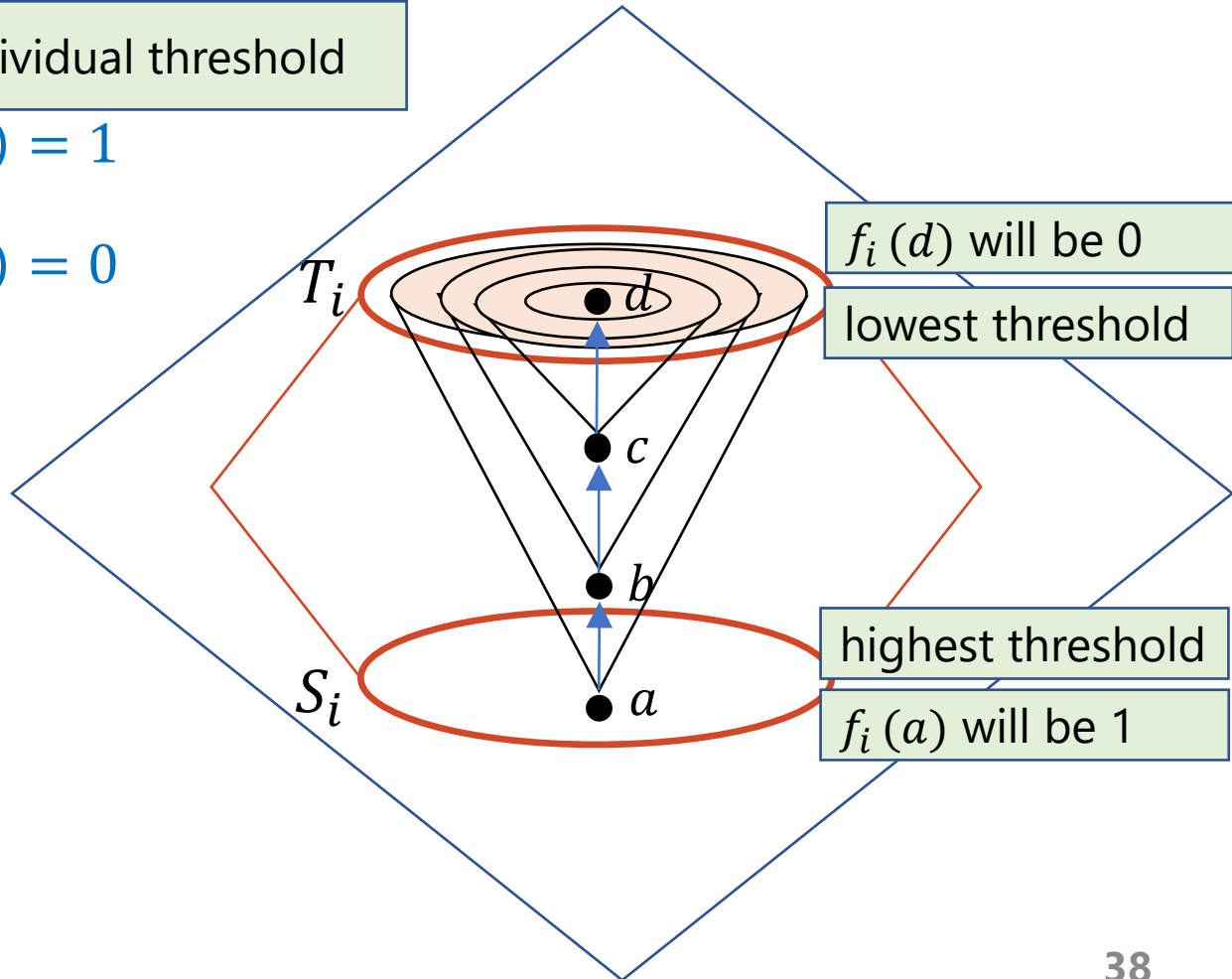
individual threshold

in $\text{Sweep}(S_i, T_i)$

- $f(z) > \max_{x \in T_i, z \leq x} f(x)$, then $f_i(z) = 1$
- $f(z) \leq \max_{x \in T_i, z \leq x} f(x)$, then $f_i(z) = 0$

z

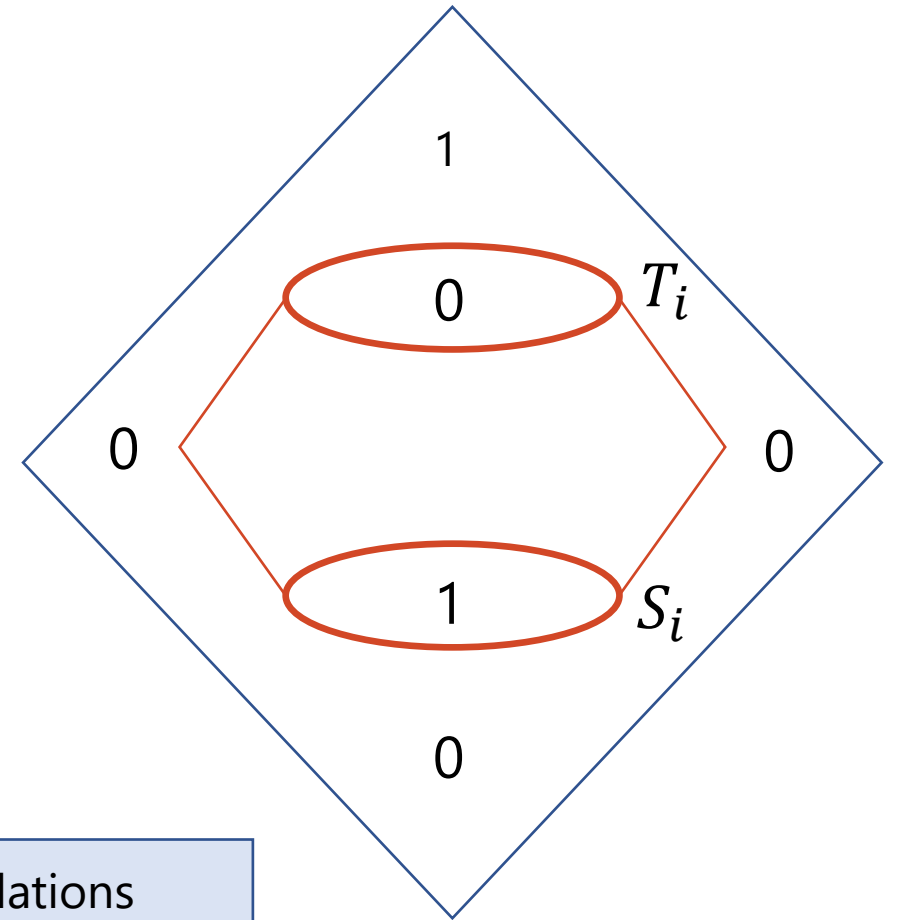
not in $\text{Sweep}(S_i, T_i)$



Step 3: Define Boolean Functions

Given (S_i, T_i) , define $f_i: V(G) \rightarrow \{0,1\}$

- z
- in $\text{Sweep}(S_i, T_i)$
 - $f(z) > \max_{x \in T_i, z \preceq x} f(x)$, then $f_i(z) = 1$
 - $f(z) \leq \max_{x \in T_i, z \preceq x} f(x)$, then $f_i(z) = 0$
 - not in $\text{Sweep}(S_i, T_i)$
 - above, then $f_i(z) = 1$
 - not above, then $f_i(z) = 0$



a vertex cannot be both above and below $\text{Sweep}(S_i, T_i)$

don't want violations outside of $\text{Sweep}(S_i, T_i)$

Proof of BD Theorem

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 - ✓ Define Boolean functions f_i given subgraphs H_i .
4. Prove desired properties of f_i .

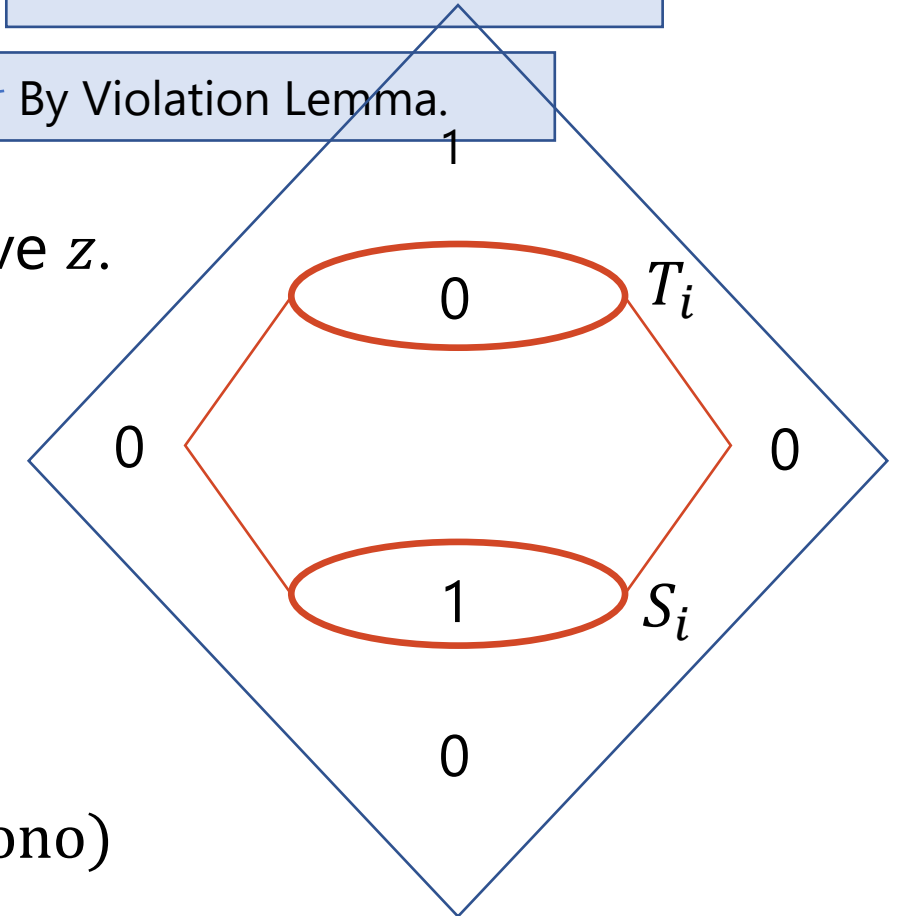
Step 4: Proof of BD Theorem

(1) The functions f_i preserve $\text{dist}(f, \text{mono})$.

- Each vertex in T_i will have value 0.
- Each vertex in S_i will have value 1.
 - If $z \in S_i$, then $f(z) > f(x)$ for all $x \in T_i$ above z .
- $\Rightarrow f_i$ has matching of violated pairs $M_i: S_i \rightarrow T_i$.
- M_i is restriction of M to $\text{Sweep}(S_i, T_i)$.
- All the M_i for $i \in [k]$ are disjoint.

Vertex $z \in T_i$, and z above z

By Violation Lemma.



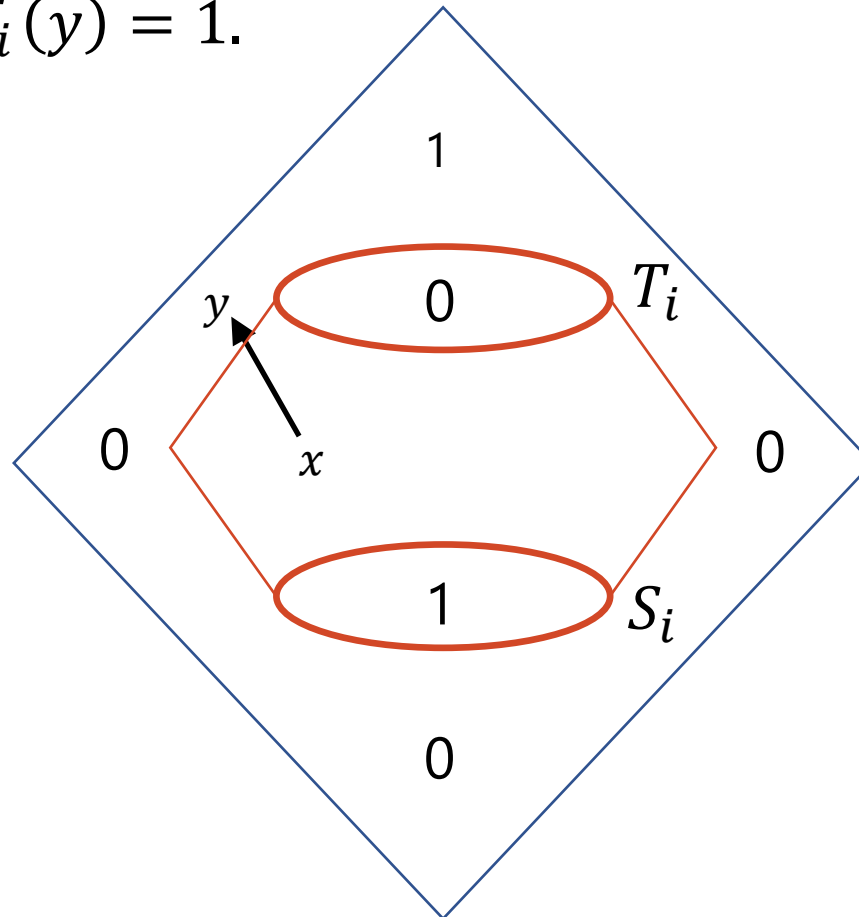
$$\sum_{i \in [k]} \text{dist}(f_i, \text{mono}) \geq \sum_{i \in [k]} |M_i| \geq |M| \geq \frac{1}{2} \text{dist}(f, \text{mono})$$

Step 4: Proof of BD Theorem

(2) Edges violated by f_i are contained in $\text{Sweep}(S_i, T_i)$

Consider edge $x \rightarrow y$ not in $\text{Sweep}(S_i, T_i)$

y above $\text{Sweep}(S_i, T_i)$, $f_i(y) = 1$.

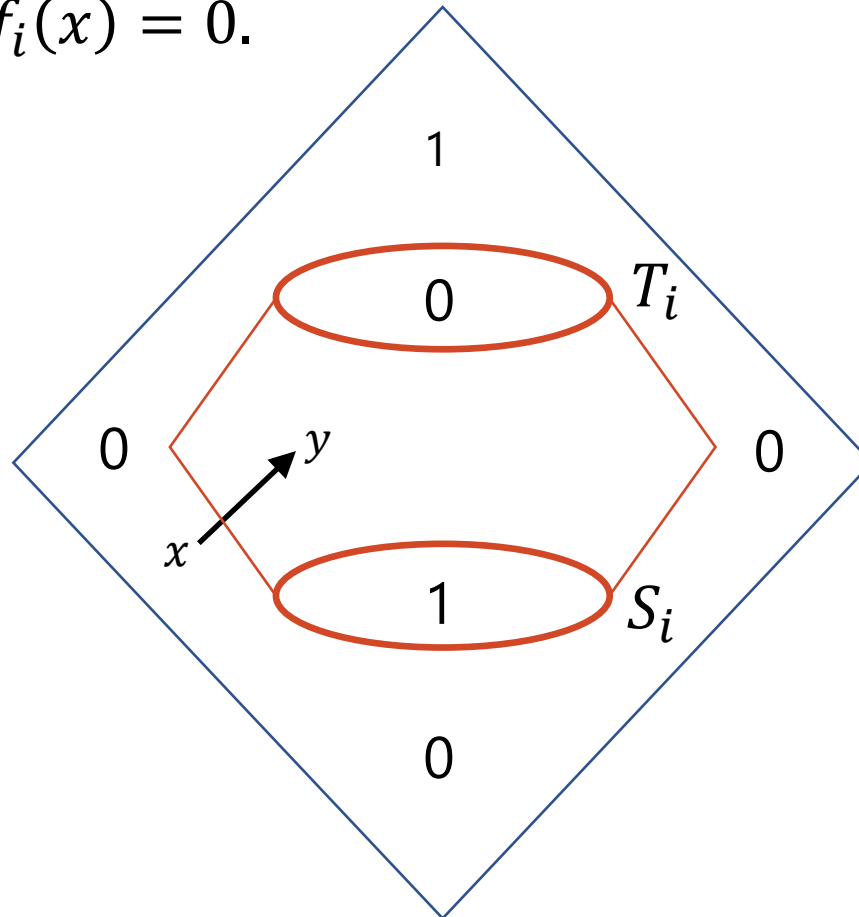


Step 4: Proof of BD Theorem

(2) Edges violated by f_i are contained in $\text{Sweep}(S_i, T_i)$

Consider edge $x \rightarrow y$ not in $\text{Sweep}(S_i, T_i)$

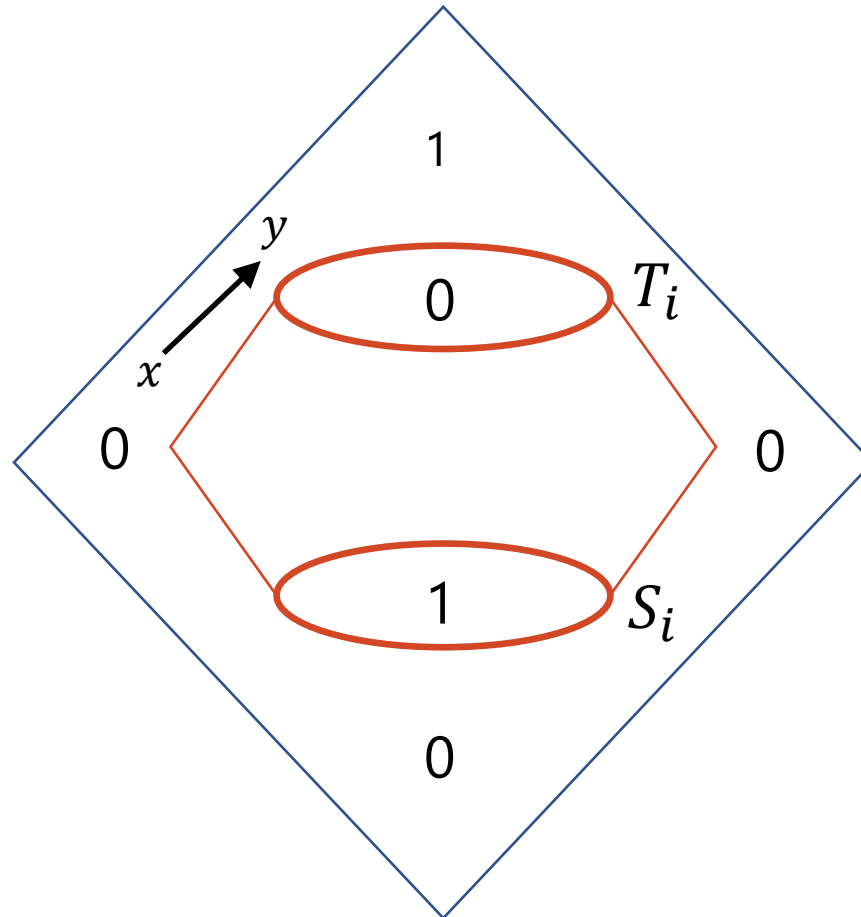
x below $\text{Sweep}(S_i, T_i)$, $f_i(x) = 0$.



Step 4: Proof of BD Theorem

(2) Edges violated by f_i are contained in $\text{Sweep}(S_i, T_i)$

Consider edge $x \rightarrow y$ not in $\text{Sweep}(S_i, T_i)$



Step 4: Proof of BD Theorem

(3) Edges violated by f_i are violated by f

Consider edge $x \rightarrow y$ violated by f_i (in $\text{Sweep}(S_i, T_i)$)

$$f_i(x) = 1, f_i(y) = 0$$

For $t \in T_i$ such that $y \preceq t$, then $x \preceq t$.

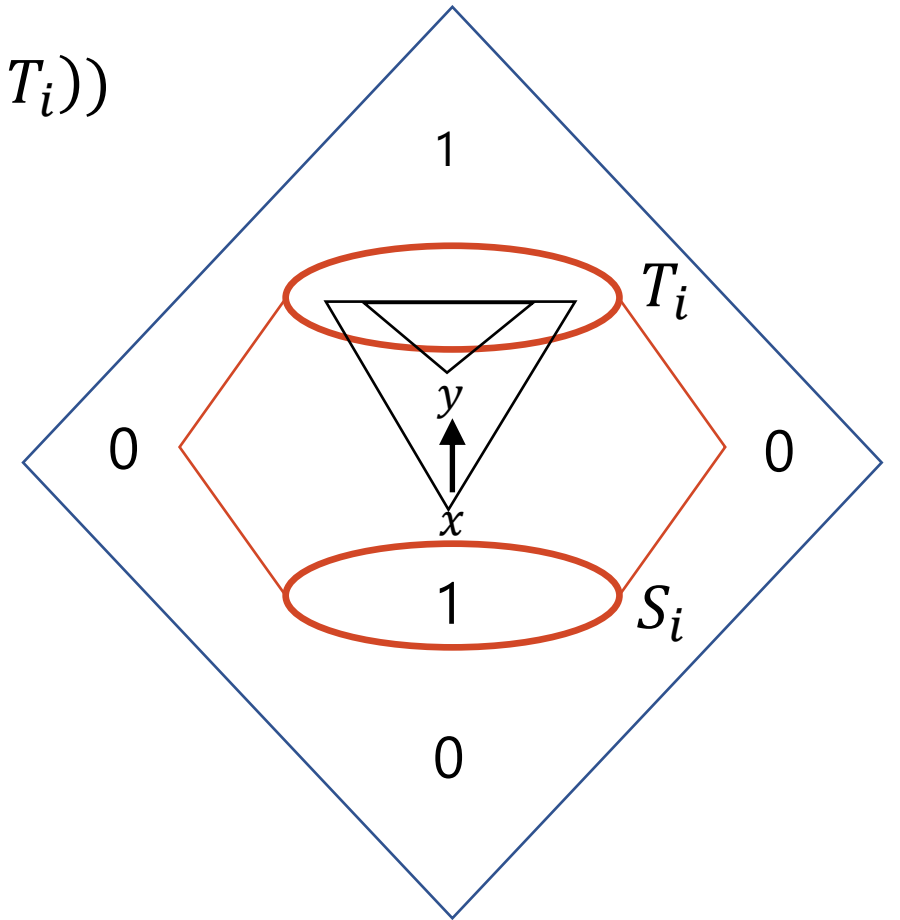
Therefore:

threshold for x

threshold for y

$$f(x) > \max_{t \in T_i, x \preceq t} f(t) \geq \max_{t \in T_i, y \preceq t} f(t) \geq f(y)$$

\Rightarrow Edge $x \rightarrow y$ violated by f



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- ✓ Prove desired properties of f_i .

$$\Rightarrow \text{Main inequality } \sum_{x \in \{0,1\}^d} \left[\sqrt{I_f^-(x)} \right] = \Omega(\text{dist}(f, \text{mono}))$$

Conclusion

- Improved sublinear algorithms for monotonicity.
- Generalized isoperimetric inequalities.
- Proved the Boolean Decomposition Theorem.

Open Question. Do the isoperimetric inequalities hold for other domains?

- Specifically, the hypergrid domain $[n]^d$.
- Margulis type inequality holds [\[Black Chakrabarty Seshadhri '18\]](#). What about Talagrand?
- It would suffice to show such inequality for the Boolean case.
- Use our BD Theorem to generalize to real-valued functions.
- Improve algorithms for monotonicity testing on hypergrid.