



A Parametric I/O Model for Modern Storage Devices

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presentation at DaMoN 2021



Modeling Performance

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"Algorithm/Data Structure **X** has O(f(N)) performance, where N is the number of data pages on disk"

... is probably one of the most commonly read phrases in SIGMOD papers.





Memory Hierarchy

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Small, fast main memory (size M)











Small, fast main memory (size M)





One I/O at a time



Small, fast main memory (size M)











0 access cost

Small, fast main memory (size M)







0 access cost

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> Small, fast main memory (size M)







total cost \cong total # reads/writes to disk





0 access cost

Small, fast main memory (size M)





Two (outdated) assumptions

Symmetric cost for Read & Write to disk

 $\circ~$ One I/O at a time

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Small, fast main memory (size M)





Hard Disk Drives

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Hard Disk Drives

Two assumptions of Traditional I/O Model





HDD Stopped Evolving

• Generally, the slowest component

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• Slowest increase in performance

Device	Size	Seq B/W	Time to read
HDD 1980	100 MB	1.2 MB/s	~ 1 min
HDD 2020	4 TB	125 MB/s	~ 9 hours

HDDs are moving deeper in the memory hierarchy, and new algorithms are designed for new faster storage devices

How do these modern storage devices perform?



Solid State Drives & NVMs

SSDs

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NVMs

 \bullet

- SATA SSDs PCM
- PCIe SSDs (NVMe SSDs)
 - (1101010 ± 3303)
- Zoned SSDs

• STT-RAM

MRAM

• Open SSDs

• 3D Xpoint (Intel's Optane)



Modern Storage Devices



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Symmetric cost for Read & Write



Read/Write Asymmetry



One I/O at a time



Concurrency



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Read/Write Asymmetry







Out-of-place updates cause invalidation

Invalidation causes garbage collection



Plane





Block 0

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Block 1

Writing in a free page isn't costly!





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Block 0

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Block 1

Not all updates are costly!





0'

R'

Writes in SSD

What if there is no space?



. . .

Block 0

Block N





What if there is no space?



Garbage Collection!





Block 0

Block N

. . .



What if there is no space?

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Garbage Collection!





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Higher average update cost (due to GC) \rightarrow *Read/Write asymmetry*



Read/Write Asymmetry - Example

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Intel Device	Advertised Random	Advertised Random	Advertised	
	Read IOPS	Write IOPS	Asymmetry	
D5-P4320	427k	36k	11.9	
DC-P4500	626k	51k	12.3	
DC-P4610	643k	199k	3.2	
Optane 900P	550k	500k	1.1	
Optane H10	330k	250k	1.3	



Read/Write Asymmetry

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Concurrency

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Internals of an SSD

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Parallelism at different levels (e.g. channel, chip, die, plane block, page)



Concurrency in SSD (simplified)

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Benchmarking

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Benchmarking

Tools

- Custom micro-benchmarking infrastructure
- fio
- Intel's SPDK

Setup

- With File System
- Without File System







For 4K random read,

Asymmetry: 2.8

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Concurrency: 70





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Can the File System be the **Bottleneck**?

Interrupt-based model

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Can the File System be the **Bottleneck**?

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Measuring Asymmetry/Concurrency

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Table 2: Empirical Asymmetry and Concurrency.

	4KB			8KB		
Device	α	k _r	k_w	α	k _r	k_w
Optane SSD	1.1	6	5	1.0	4	4
PCIe SSD (with FS)	2.8	80	8	1.9	40	7
PCIe SSD (w/o FS)	3.0	16	6	3.0	15	4
SATA SSD	1.5	25	9	1.3	21	5
Virtual SSD	2.0	11	19	1.9	6	10



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Most devices have high asymmetry



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How should the I/O model be adapted in light of

read/write asymmetry and concurrency?





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PIO(M, k_r, k_w, \alpha) assumes a fast main memory with capacity *M*, and storage of unbounded capacity that has **read/write asymmetry** α , and **read (write) concurrency** k_r (k_w).





Performance Analysis

We classify storage-intensive applications into four classes

- Unbatchable Reads, Unbatchable Writes
- Unbatchable Reads, Batchable Writes
- Batchable Reads, Unbatchable Writes
- Batchable Reads, Batchable Writes





Unbatchable Reads, Batchable Writes

- Can exploit write concurrency (k_w) by batching writes
- Amortized cost per write following PIO is $\frac{\alpha}{k_w}$
- Example: DBMS bufferpool



Unbatchable Reads, Batchable Writes



Speedup increases with increasing concurrent I/Os

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Speedup depends on asymmetry – gain is *higher* for a device with *higher* asymmetry





Batchable Reads, Unbatchable Writes

- Can exploit read concurrency (k_r) by batching read
- Amortized cost per read following PIO is $\frac{1}{k_r}$
- Example: Graph traversal



Batchable Reads, Unbatchable Writes



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Speedup increases with increasing concurrent I/Os

Speedup depends on asymmetry – gain is *higher* for a device with *lower* asymmetry



Batchable Reads, Unbatchable Writes

- Can exploit both read and write concurrency (k_r, k_w)
- Amortized cost per read following PIO is $\frac{1}{k_r}$
- Amortized cost per write following PIO is $\frac{\alpha}{k_w}$
- Example: LSM compaction

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Batchable Reads, Batchable Writes

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Speedup increases with increasing concurrent I/Os, and depends on asymmetry Impact of utilizing write concurrency is higher than utilizing read concurrency



Importance of using Proper k

A sample application with unbatchable reads and batchable writes

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We use PCIe SSD ($k_w = 8$) to run this concurrency-aware application

Optimal speedup at the device concurrency.





Guidelines for Algorithm Design

Know Thy Device

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Exploit Device Concurrency

Use Concurrency with Care

It is suboptimal to treat a read and a write equally for a device with asymmetry

Asymmetry Controls Performance





Conclusion



Benefits of PIO (M, k, α)

- algorithms tailored to new devices
- Can capture *any* new device

Prerequisite: quantify \boldsymbol{k} and $\boldsymbol{\alpha}$





Make asymmetry and concurrency part of algorithm design

... not simply an engineering optimization

Build algorithms/data structures for storage devices with asymmetry α and concurrency k

index structures



graph traversal algorithms

bufferpool management







Thank You!

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Backup Slides

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Expected Parallelism

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Expected Parallelism

 E_n = expected number of empty channels after n I/Os are uniformly distributed

We use E_{n-1} and consider where the n^{th} I/O will be routed it will be on an empty channel with probability $E_n = \left(\frac{E_{n-1}}{n}\right)^n \left(E_{n-1}-1\right) + \left(1 - \frac{E_{n-1}}{n}\right) \left(E_{n-1}\right) = \frac{n-1}{n} E_{n-1}$ with probability it will be on a non-empty channel Since $E_0 = n$; $E_n = \left(\frac{n-1}{n}\right)^n n$

Fraction of empty channels $= \frac{E_n}{n} = \left(1 - \frac{1}{n}\right)^n \approx \frac{1}{e}$

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So, on average $\left(1 - \frac{1}{e}\right) = 63.2\%$ channels will be accessed in parallel

Unbatchable Reads, Batchable Writes

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