

A Parametric I/O Model for Modern Storage Devices

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Modeling Performance

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"Algorithm/Data Structure **X** has $O(f(N))$ performance, where *is the number of data pages on disk"*

… is probably one of the most commonly read phrases in SIGMOD papers.

Memory Hierarchy

 $\begin{array}{c}\n\text{BS} \stackrel{\frown}{\text{BS}} \\
\hline\n\text{DISC}\n\end{array}$

Small, fast main memory (size M)

(size M) large, slow external memory

Small, fast main memory

One I/O at a time

Small, fast main memory

(size M) $($ size M) $)$

0 access cost

Small, fast main memory

(size M) large, slow external memory

0 access cost

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Small, fast main memory

(size M) large, slow external memory

total cost \cong total # reads/writes to disk

Transfer cost 1 unit

0 access cost

Small, fast main memory

(size M) The Contract of the Contract Large, slow external memory

Two (outdated) assumptions

o **Symmetric** cost for **Read & Write** to disk

o **One I/O** at a time

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Small, fast main memory

(size M) The Contract of the Contract Large, slow external memory

Hard Disk Drives

 $\begin{array}{c}\n\text{BS} \stackrel{\frown}{\cong} \\
\text{DISC}\n\end{array}$

Hard Disk Drives

Two assumptions of Traditional I/O Model

HDD Stopped Evolving

o Generally, the slowest component

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o Slowest increase in performance

HDDs are moving deeper in the memory hierarchy, and new algorithms are designed for new faster storage devices

How do these modern storage devices perform?

Solid State Drives & NVMs

SSDs

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\hline\n\text{DISC}\n\end{array}$

NVMs

- SATA SSDs • PCM
- PCIe SSDs (NVMe SSDs)
- MRAM
- Zoned SSDs • STT-RAM
- Open SSDs

• 3D Xpoint (Intel's Optane)

Modern Storage Devices

 $\begin{array}{c}\n\text{BS} \stackrel{\frown}{\cong} \\
\text{DISC}\n\end{array}$

Symmetric cost for Read & Write

Read/Write Asymmetry

One I/O at a time

Concurrency

$\begin{array}{c}\n\text{BS} \stackrel{\frown}{\cong} \\
\text{DISC}\n\end{array}$

Read/Write Asymmetry

Out-of-place updates cause invalidation

Invalidation causes **garbage collection**

Plane

Block 0

 $\begin{array}{c}\n\text{BS} \stackrel{\frown}{\text{BS}} \\
\hline\n\text{DISC}\n\end{array}$

Block 1

Writing in a free page isn't costly!

 $\begin{array}{c}\n\text{BS} \stackrel{\frown}{\cong} \\
\text{DISC}\n\end{array}$

Block 0

 $\begin{array}{c}\n\text{BS} \stackrel{\frown}{=} \\
\text{Dis} C\n\end{array}$

Block 1

Not all updates are costly!

What if there is no space?

Block 0

…

Block N

What if there is no space?

Garbage Collection!

…

What if there is no space?

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Garbage Collection!

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Higher average update cost (due to GC) \rightarrow **Read/Write asymmetry**

Read/Write Asymmetry - Example

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\text{DISC}\n\end{array}$

Read/Write Asymmetry

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Concurrency

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Internals of an SSD

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Parallelism at different levels (e.g. channel, chip, die, plane block, page)

Concurrency in SSD (simplified)

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Benchmarking

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\text{DISC}\n\end{array}$

Benchmarking

Tools

- Custom micro-benchmarking infrastructure
- fio
- Intel's SPDK

Setup

- With File System
- Without File System

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Device: Dell P4510 (1TB) \rightarrow 4K Random Read \rightarrow 4K Random Write 600 \times 10³ \rightarrow 8K Random Read \rightarrow 8K Random Write
 \rightarrow 8K Random Write 500 400 For 4K random read, 2.8x IOPS *Asymmetry*: 2.8 300 $\Leftrightarrow \Leftrightarrow$ *Concurrency*: 70 200 1.8x 100 0 0 50 100 150 200 250 300 **Threads**

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DiSC

B
DiSC

Can the File System be the Bottleneck?

Interrupt-based model

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\hline\n\text{DISC}\n\end{array}$

Can the File System be the Bottleneck?

 $\begin{array}{c}\n\text{BS} \stackrel{\frown}{\text{BS}} \\
\hline\n\text{DISC}\n\end{array}$

Measuring Asymmetry/Concurrency

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Table 2: Empirical Asymmetry and Concurrency.

Modern Storage Devices

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Modern Storage Devices

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Most devices have high asymmetry

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How should the I/O model be adapted in light of

read/write asymmetry and concurrency?

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 $PIO(M, k_r, k_w, \alpha)$ assumes a fast main memory with capacity M, and storage of unbounded capacity that has read/write asymmetry α , and read (write) concurrency k_r (k_w).

Performance Analysis

We classify storage-intensive applications into four classes

- Unbatchable Reads, Unbatchable Writes
- Unbatchable Reads, Batchable Writes

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- Batchable Reads, Unbatchable Writes
- Batchable Reads, Batchable Writes

Unbatchable Reads, Batchable Writes

- Can exploit write concurrency (k_w) by batching writes
- Amortized cost per write following PIO is $\frac{\alpha}{\mu}$ k_{w}
- Example: DBMS bufferpool

Unbatchable Reads, Batchable Writes

1

2

3

 ∞ \mathbf{p} $\mathbf \omega$ $\mathbf \omega$ $\bf \vec \circ$ u $\mathbf{\mathsf{p}}$

4

5 6

7

8

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Conc. Write I/Os

Speedup increases with increasing concurrent I/Os

Speedup depends on asymmetry – gain is *higher* for a device with *higher* asymmetry

Batchable Reads, Unbatchable Writes

- Can exploit read concurrency (k_r) by batching read
- Amortized cost per read following PIO is $\frac{1}{1}$ k_r
- Example: Graph traversal

Batchable Reads, Unbatchable Writes

 B_3° $\frac{1}{2}$ DiSC

Speedup increases with increasing concurrent I/Os

Speedup depends on asymmetry – gain is *higher* for a device with *lower* asymmetry

Batchable Reads, Unbatchable Writes

- Can exploit both read and write concurrency (k_r, k_w)
- Amortized cost per read following PIO is $\frac{1}{1}$ k_r
- Amortized cost per write following PIO is $\frac{\alpha}{k}$ k_{w}
- Example: LSM compaction

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Batchable Reads, Batchable Writes

 $\mathcal O$ \mathbf{p} $\mathbf \omega$ $\mathbf \omega$ $\bf \vec{c}$ u \mathbf{p}

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Speedup increases with increasing concurrent I/Os, and depends on asymmetry Impact of utilizing write concurrency is higher than utilizing read concurrency

Importance of using Proper *k*

A sample application with unbatchable reads and batchable writes

We use PCIe SSD $(k_w = 8)$ to run this concurrency-aware application

Optimal speedup at the device concurrency.

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\hline\n\text{DISC}\n\end{array}$

Guidelines for Algorithm Design

Know Thy Device

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Exploit Device Concurrency

Use Concurrency with Care

It is suboptimal to treat a read and a write equally for a device with asymmetry

Asymmetry Controls Performance

Conclusion

Benefits of PIO (M, k, α)

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- algorithms tailored to new devices
- Can capture *any* new device

Prerequisite: quantify *k* and *α*

Make *asymmetry and concurrency* part of *algorithm design*

… not simply an engineering optimization

Build algorithms/data structures for storage devices with asymmetry α and concurrency k

index structures error graph traversal algorithms bufferpool management

Thank You!

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disc.bu.edu/pio

Backup Slides

 $\begin{array}{|c|} \hline \text{BS} \stackrel{\ominus}{\stackrel{\ominus}{\sim}} \\ \hline \text{DISC} \end{array}$

Expected Parallelism

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\hline\n\text{DISC}\n\end{array}$

Expected Parallelism

 E_n = expected number of empty channels after n I/Os are uniformly distributed

We use E_{n-1} and consider where the n^{th} I/O will be routed $E_n =$ E_{n-1} \overline{n} E_{n-1} - 1) + $\left(1 - \frac{E_{n-1}}{n}\right)$ \overline{n} $|E_{n-1}| =$ $n-1$ \overline{n} E_{n-1} Since $E_0 = n$; $E_n =$ $n - 1$ \overline{n} \overline{n} \overline{n} with probability enducing them with probability it will be on a non-empty channel it will be on an empty channel

Fraction of empty channels $= {E_n / n} = \left(1 - \frac{1}{n}\right)$ \overline{n} \overline{n} ≈ $\mathbf 1$ \boldsymbol{e}

So, on average $\left(1 - \frac{1}{2}\right)$ \boldsymbol{e} = **63.2%** channels will be accessed in parallel

Unbatchable Reads, Batchable Writes

 $\begin{array}{c}\n\text{BS} \stackrel{\frown}{\cong} \\
\text{Dis} \stackrel{\frown}{\cong}\n\end{array}$

