



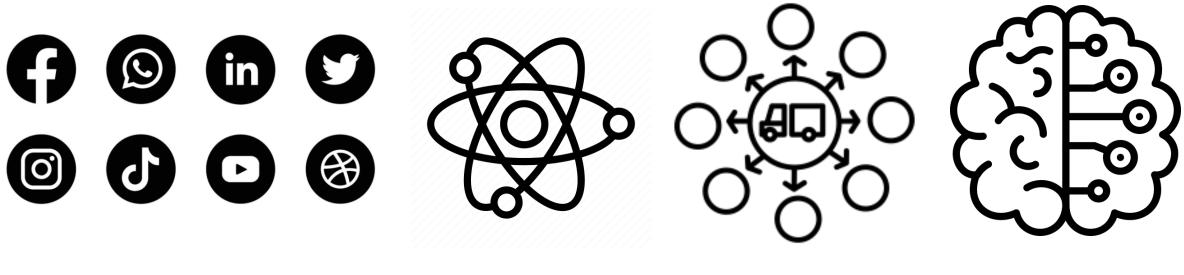
# CAVE: Concurrency-Aware Graph Processing System for SSD

Tarikul Islam Papon Taishan Chen Shuo Zhang Manos Athanassoulis



# Rise of Large Graphs

Graphs are everywhere!



Social Network

BS de DiSC

**Physical Science** 

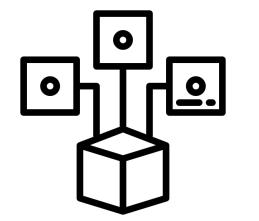
Transportation Network

Machine Learning

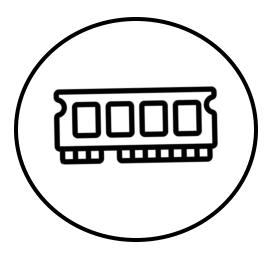
Real-world graphs often have more than a billion nodes

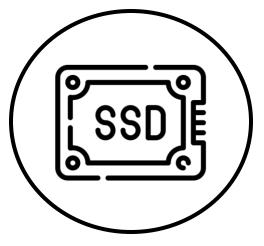


# Processing Large Graphs



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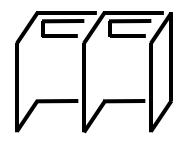


**Distributed Systems** 

Single-node in-memory systems Single-node out-of-core systems

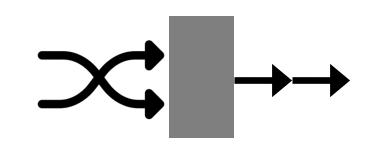


### SOA Out of Core Systems



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Data partitioning

Improve memory & disk locality

Reduce random I/O

#### **Designed for HDDs**

"Tape is Dead. Disk is Tape. Flash is Disk." - Jim Gray



#### Solid State Drives



B<sup>2</sup> SS DSiO

electronic device

fast random access

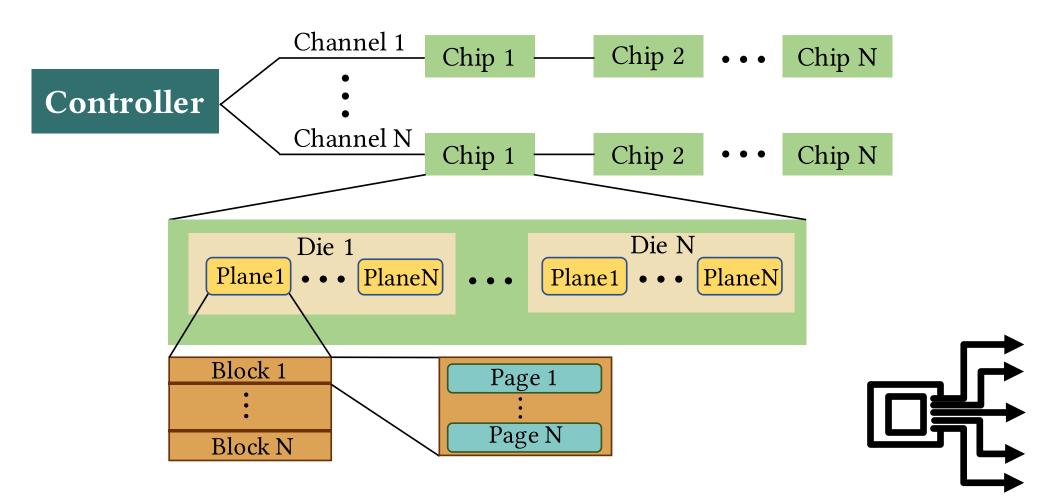
write latency > read latency





#### **SSD** Concurrency

lab **S**SIC

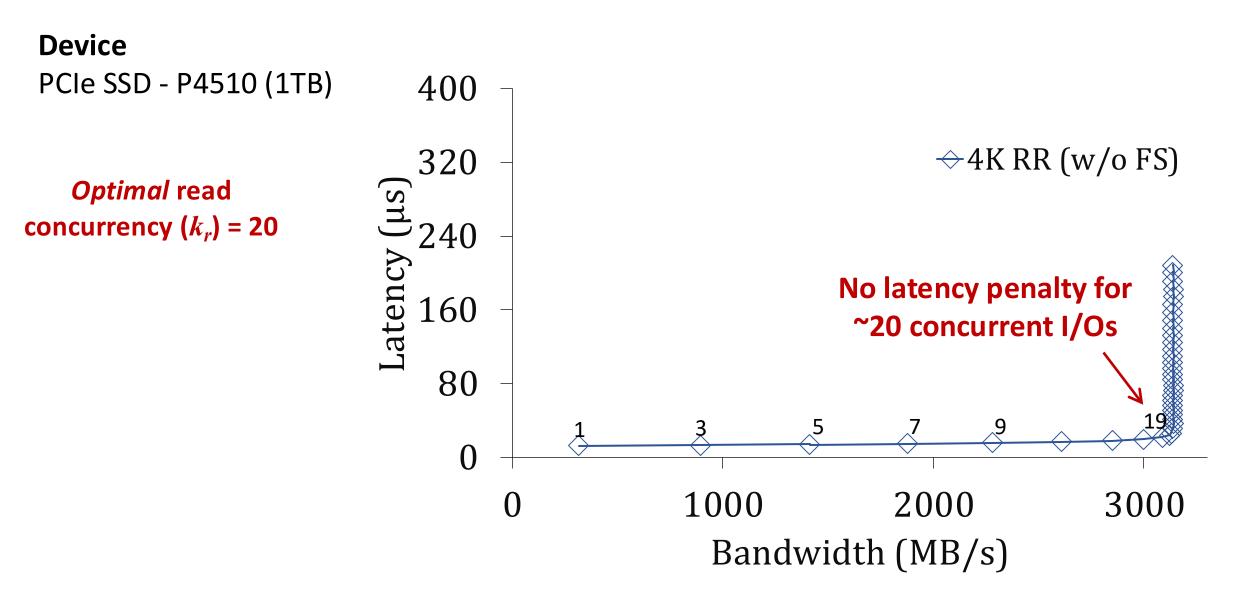


#### Parallelism at different levels





#### Impact of Concurrency

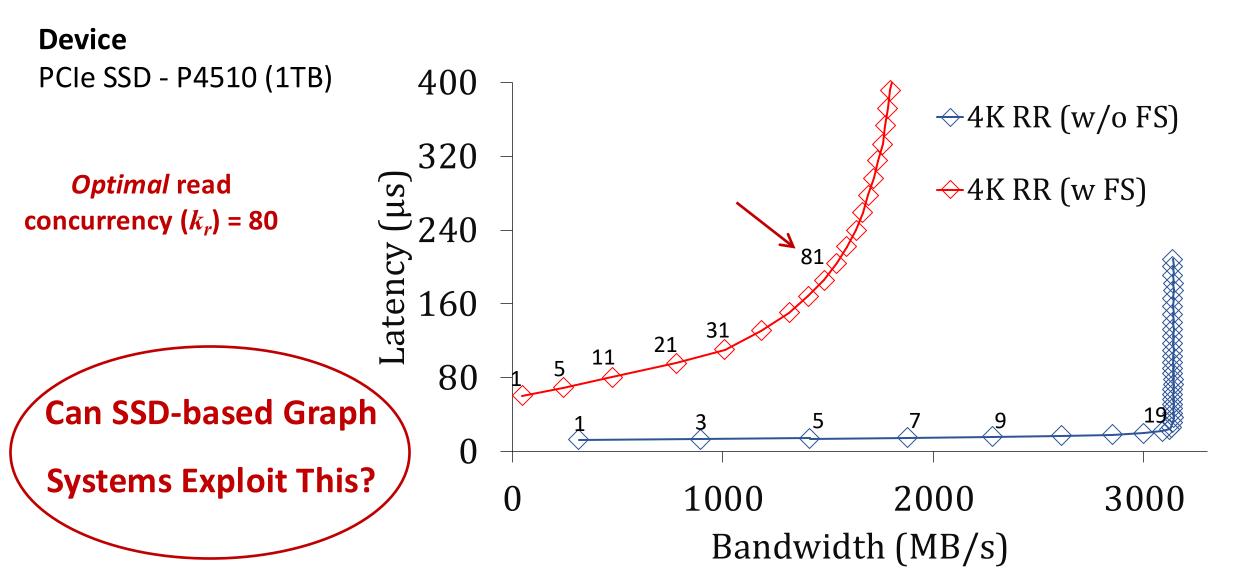






#### DaMoN@SIGMOD 2021

#### Impact of Concurrency



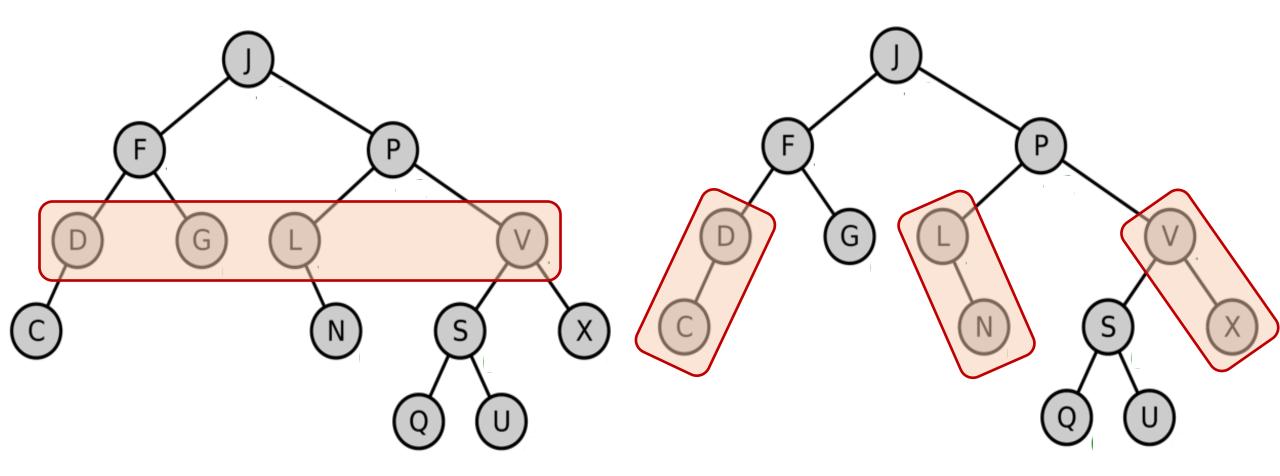


# Parallelizing Graph Traversal

**Intra-Subgraph Parallelization** 

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**Inter-Subgraph Parallelization** 

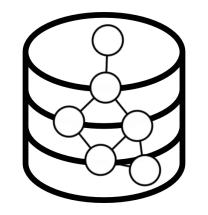


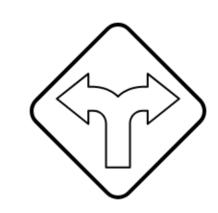
process in parallel up to k<sub>r</sub> nodes/subgraphs

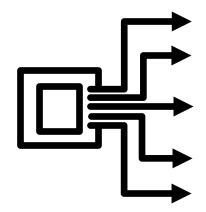


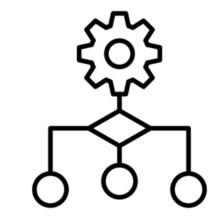


### Our Goal









Optimize for **storagebased** graph workloads Focus on **traversal** operations

Utilize SSD Concurrency Maintain core algorithm properties

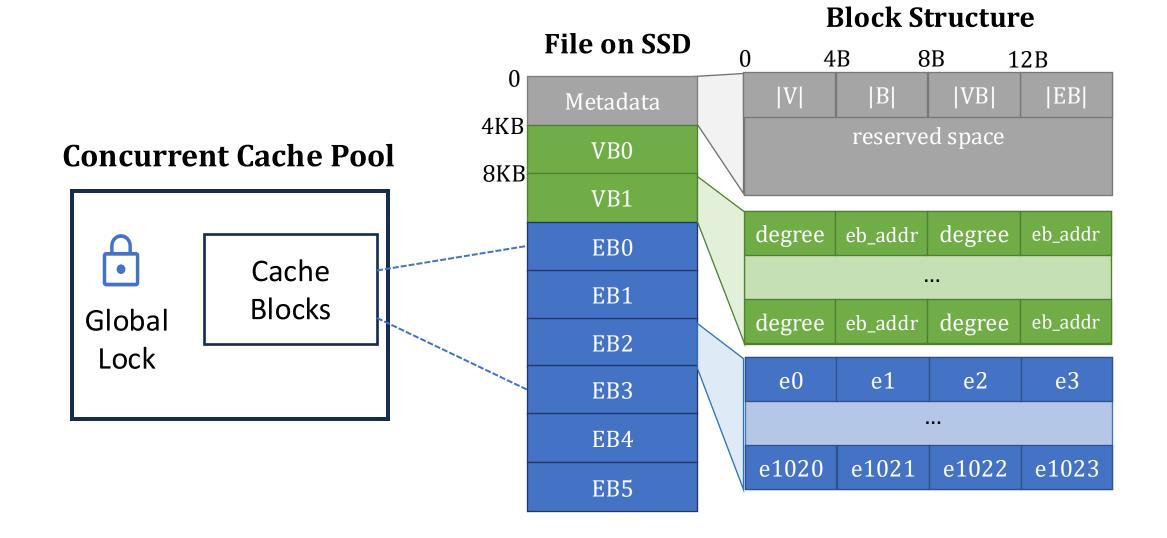
#### **Concurrency-Aware Graph (V, E)** Manager





#### CAVE Architecture

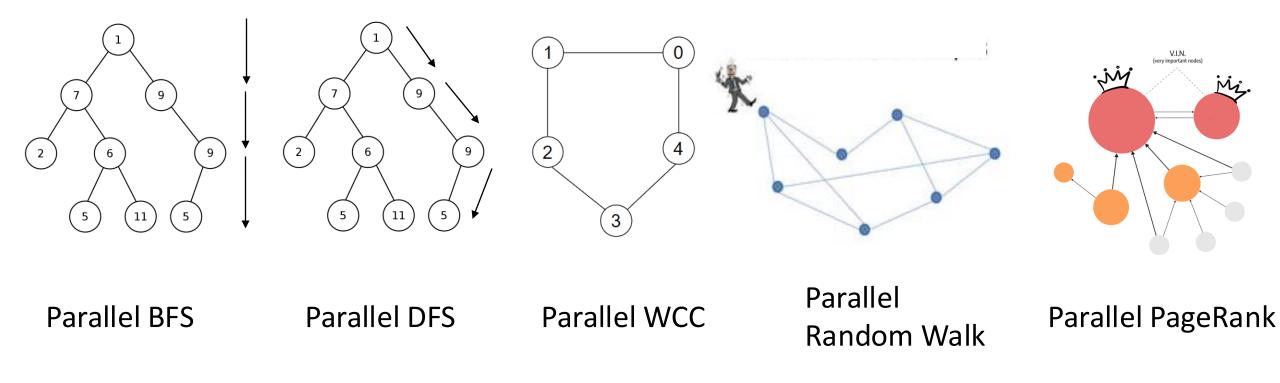
Bb da Iab OSiO





### Concurrent Graph Algorithms

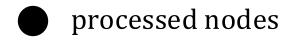
ि <u>वि</u> DisC





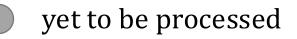


# Parallel BFS



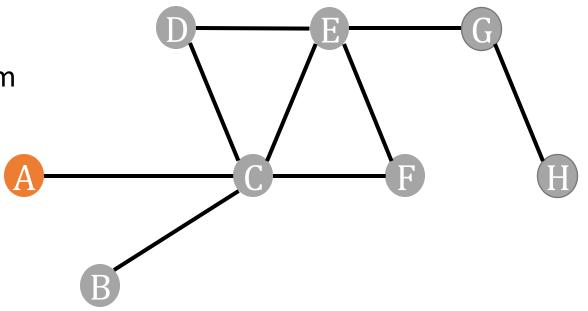


processing in progress



Each iteration involves

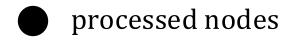
- 1. processing k<sub>r</sub> vertices concurrently from
  - a list of vertices (frontier)
- 2. accessing neighbors of each vertex
- 3. updating vertex values
- 4. determining next frontier





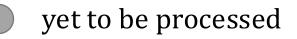


# Parallel BFS



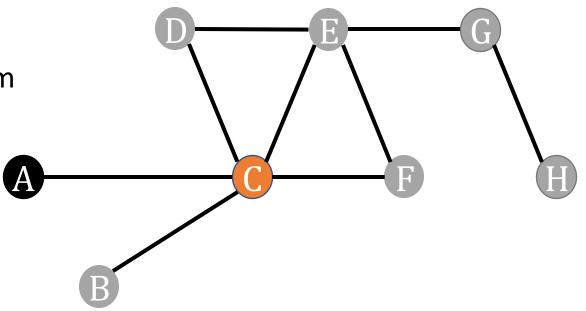


processing in progress



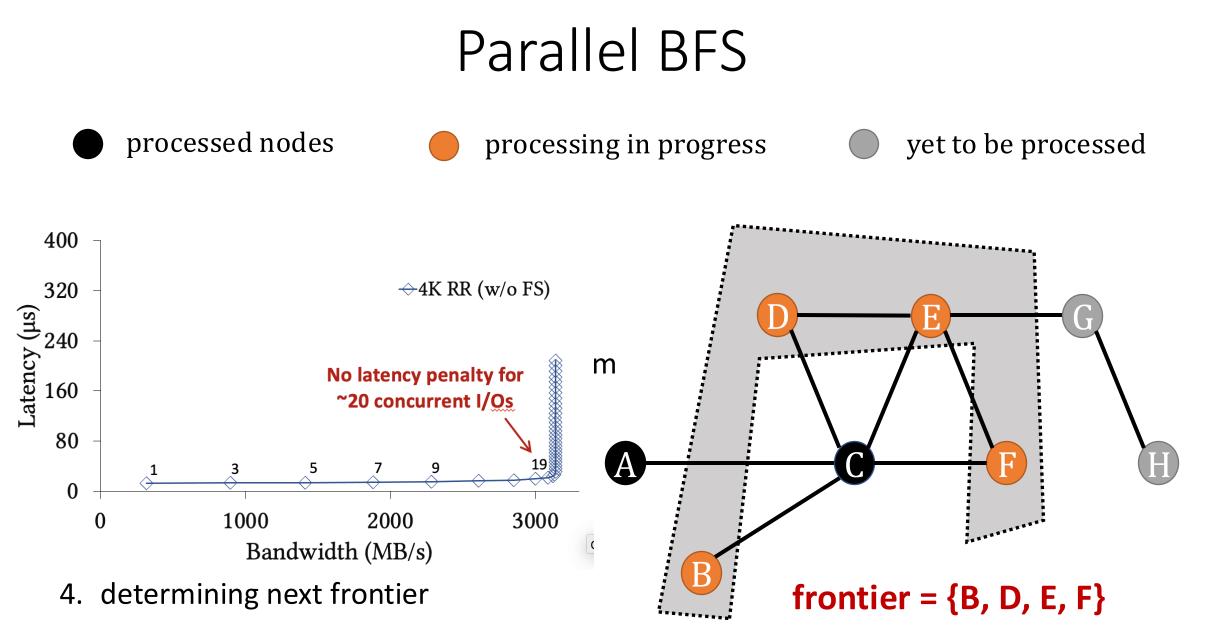
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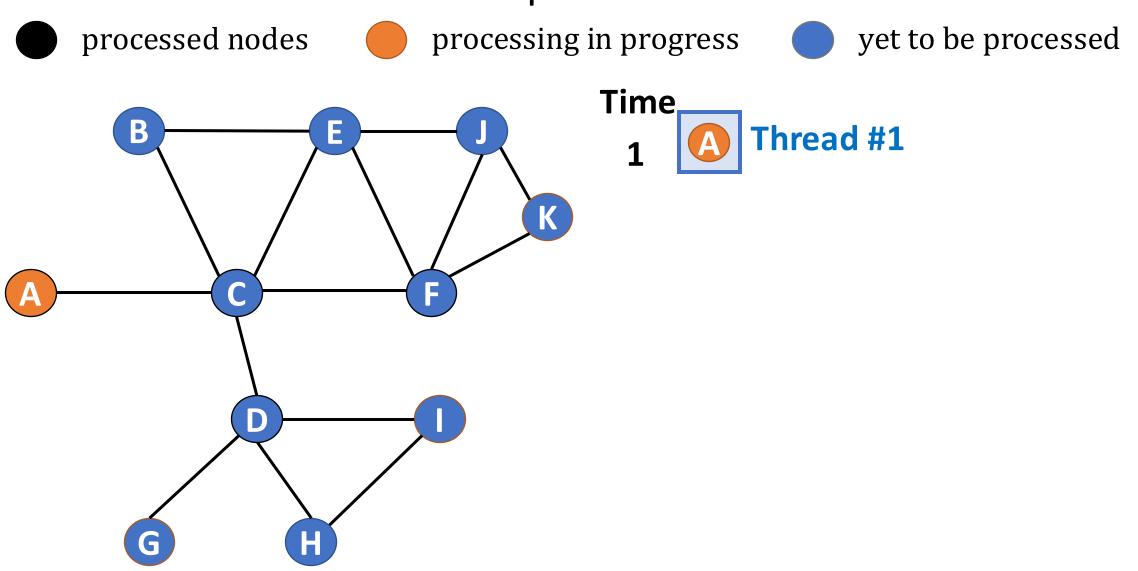






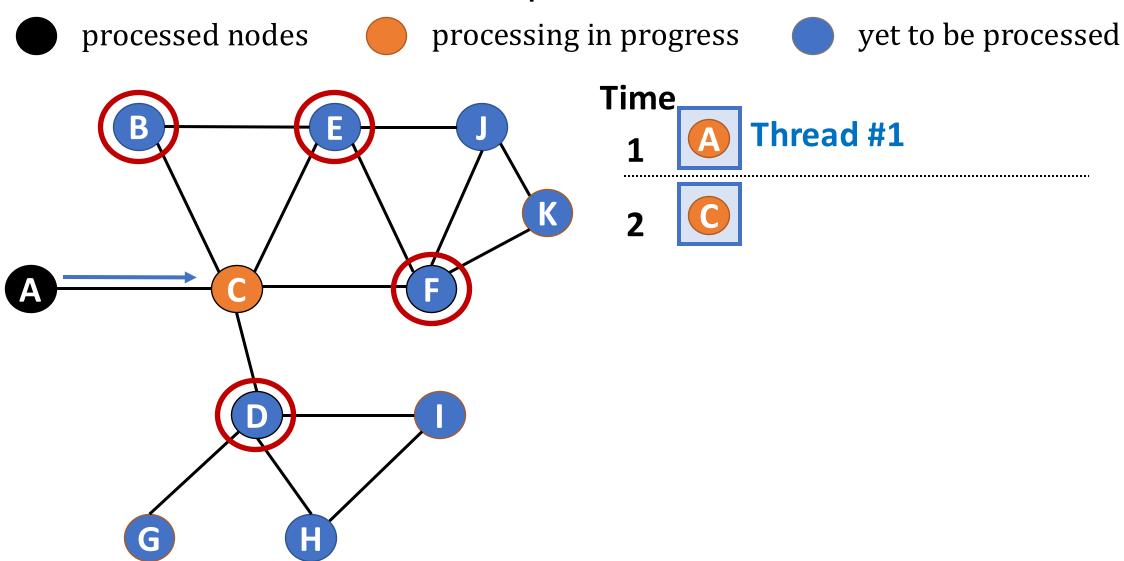






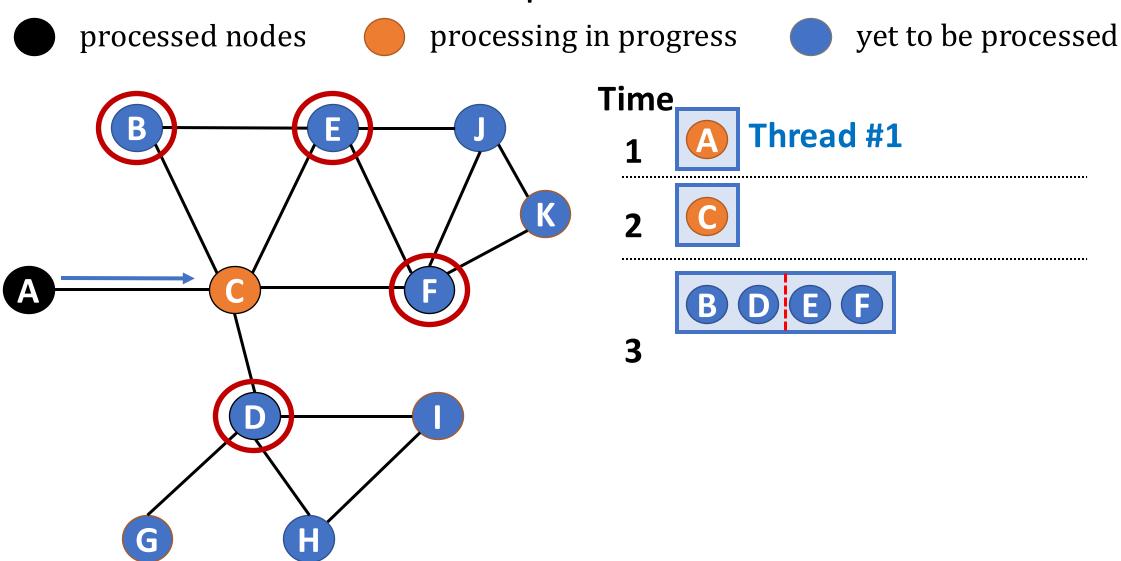






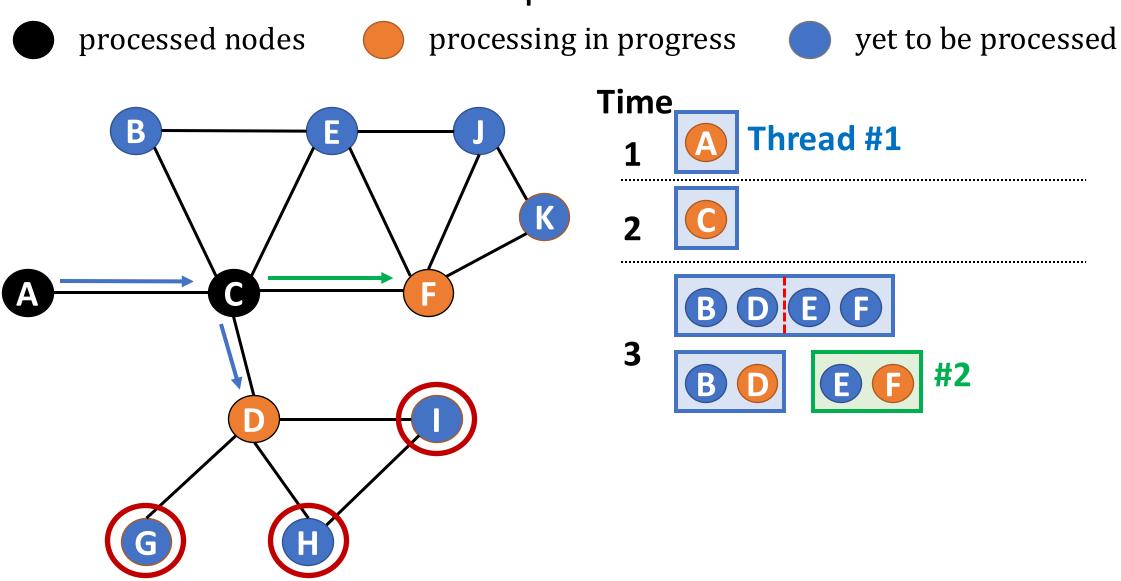




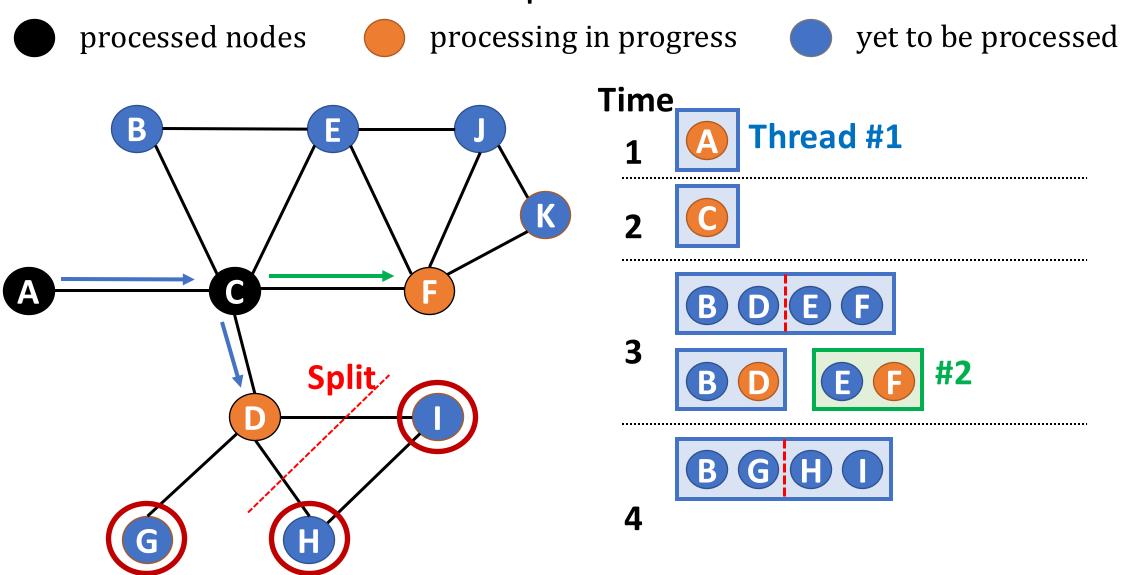






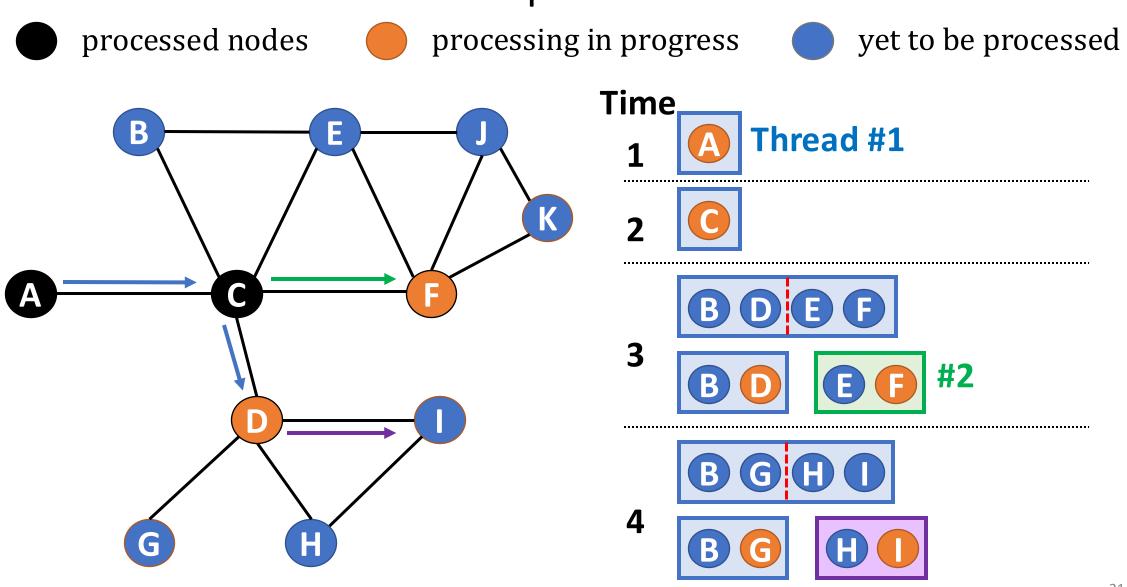








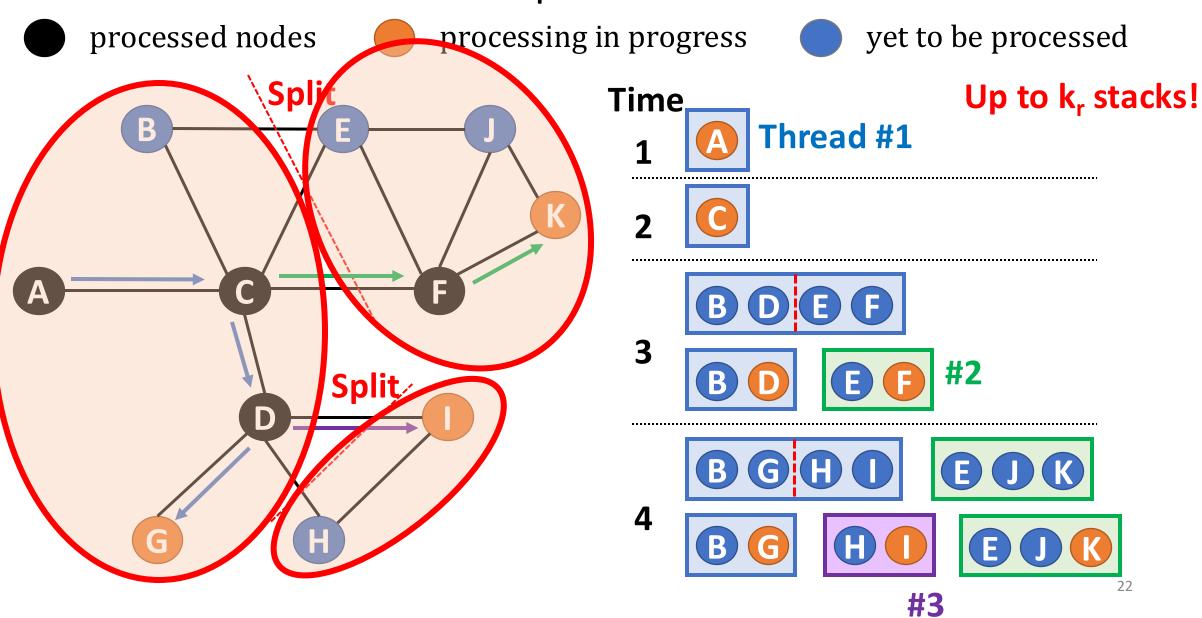




#3









#### **Experimental Evaluation**

Dataset	Description	#Nodes	#Edges	Diameter	Size
FS	Friendster Social Network	65M	1.8B	32	32 GB
TW	Twitter Social Network	53M	2B	18	28 GB
RN	RoadNet Network of PA	1M	1.5M	786	47 MB
LJ	LiveJournal Social Network	5M	69M	16	1 GB
ΥT	YouTube Social Network	1.1M	3M	20	39 MB
SD	Synthetic data	50M	1.25B	6	20 GB

6 datasets

3 devices Optane SSD ( $k_r = 6$ ) PCIe SSD ( $k_r = 80$ ) SATA SSD ( $k_r = 25$ )

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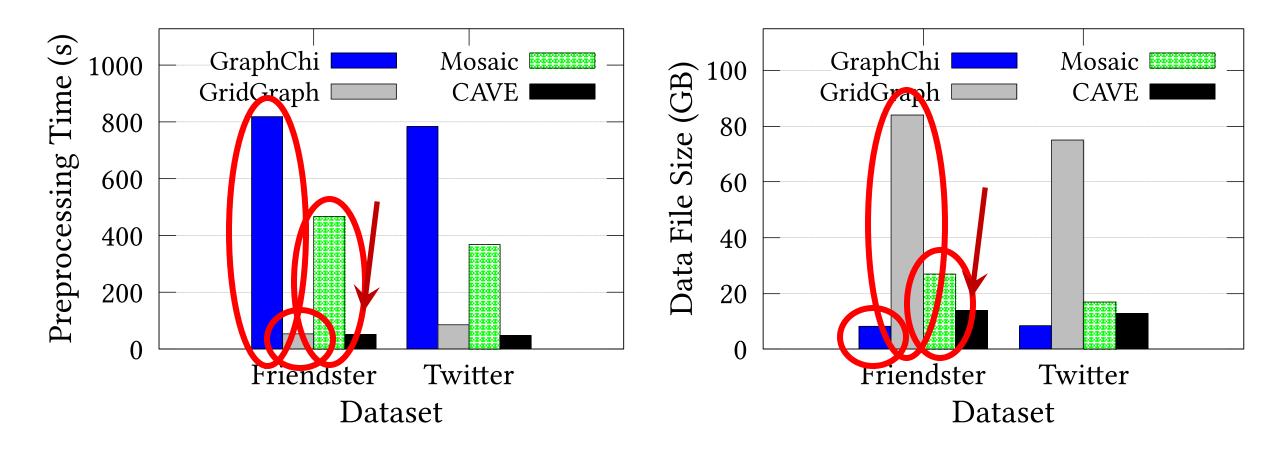
Approaches Used:

GraphChi, GridGraph, Mosaic, CAVE, CAVE\_blocked



# Preprocessing Time and Space Requirement

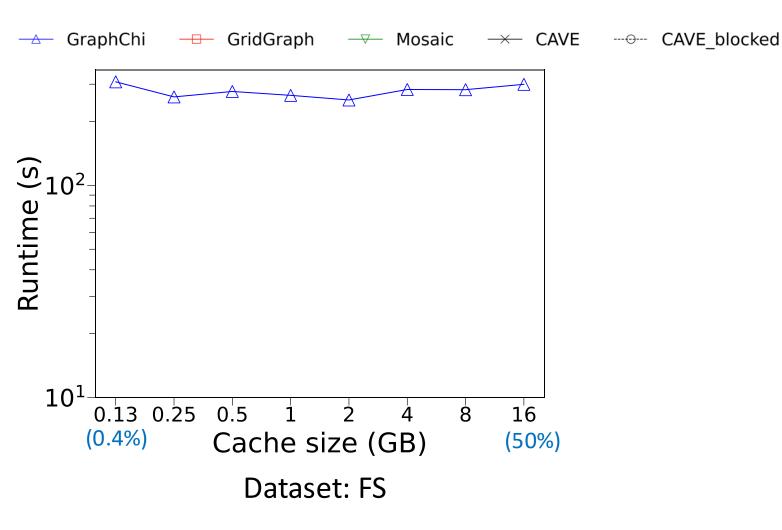
B<sup>2</sup> SS DSiO



#### CAVE has low preprocessing time and low file size

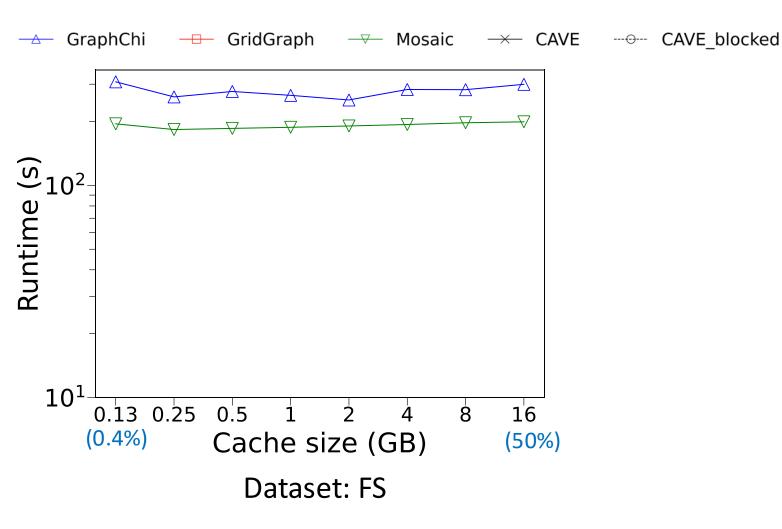


### Evaluation: Parallel BFS





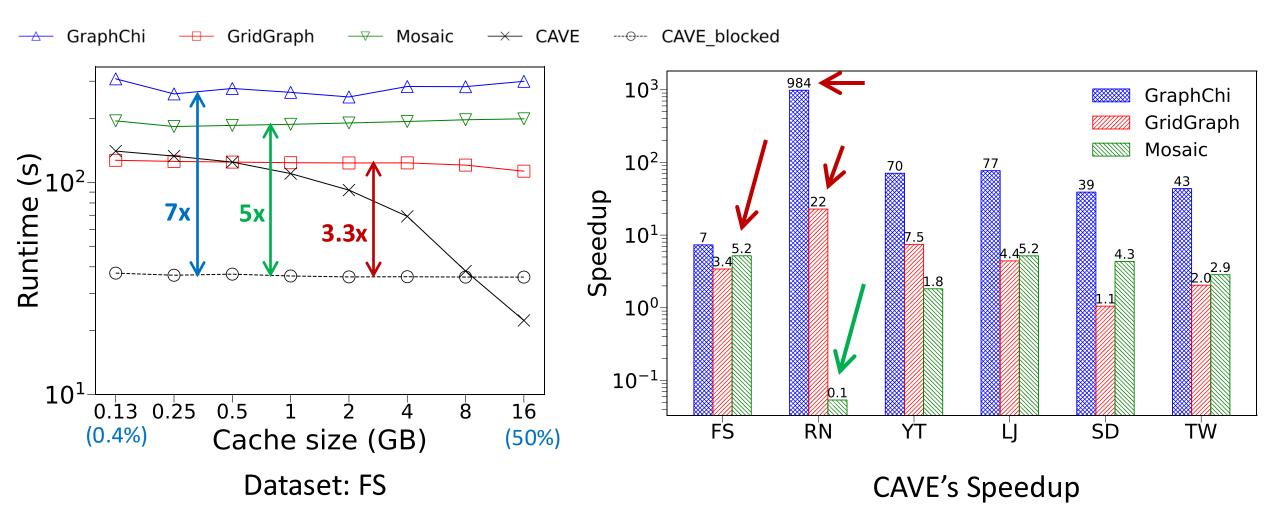
### Evaluation: Parallel BFS







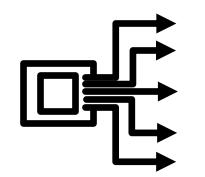
# Evaluation: Parallel BFS



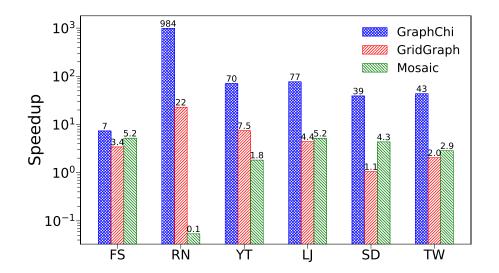
Both CAVE implementations outperforms GridGraph, Mosaic and GraphChi



# Summary

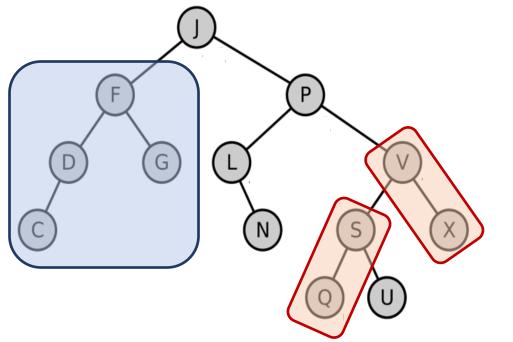


Concurrency-Aware Graph (V, E) Manager CAVE



CAVE implementations outperform SOA systems

SSD concurrency can accelerate graph traversal



Intra- and inter-subgraph parallelization



#### lab 33 DSiC

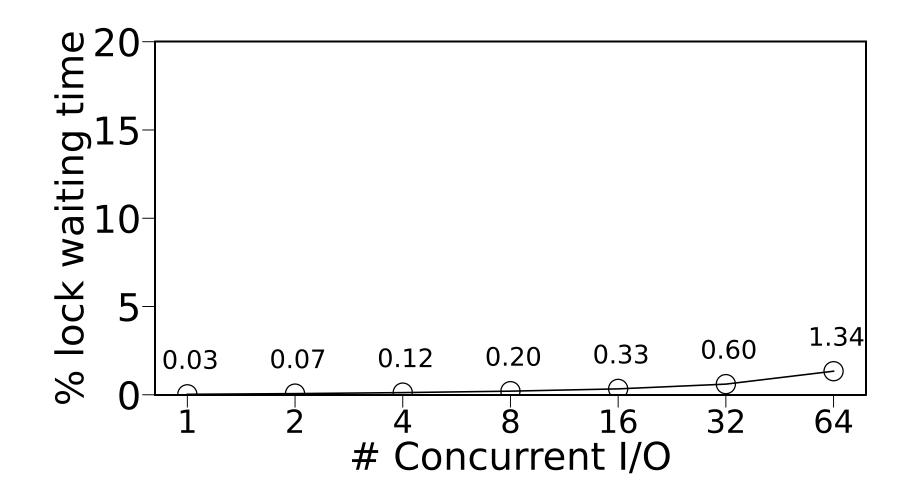
# Thank You!

cs-people.bu.edu/papon disc.bu.edu/papers/sigmod24-cave



### Lock Waiting Time is Low

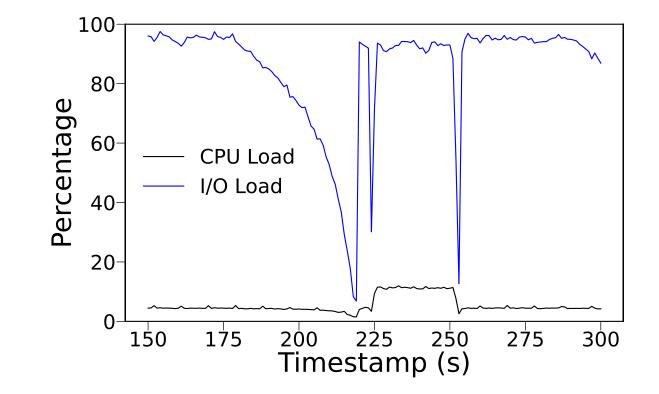
lab **S**SIC





# CAVE is I/O Bound

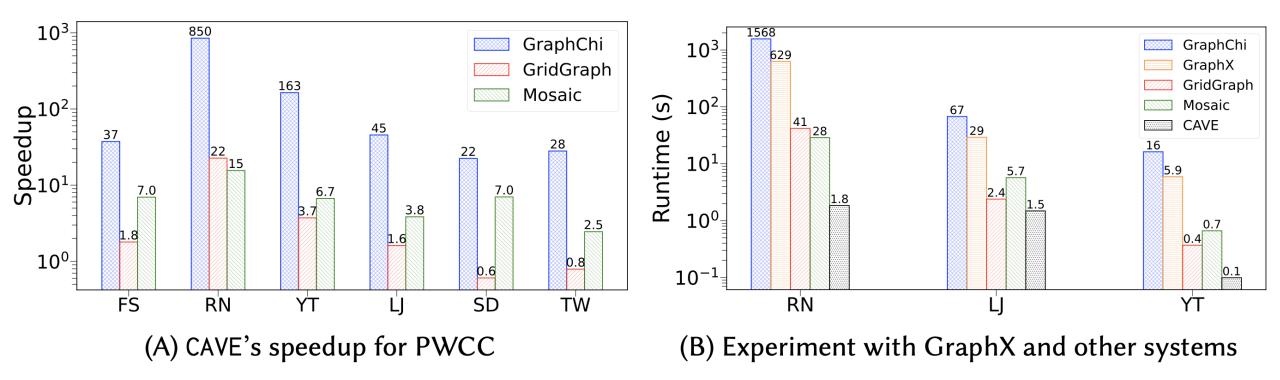
lab **S**SIC





#### CAVE Performs Well for PWCC

lab OSIC

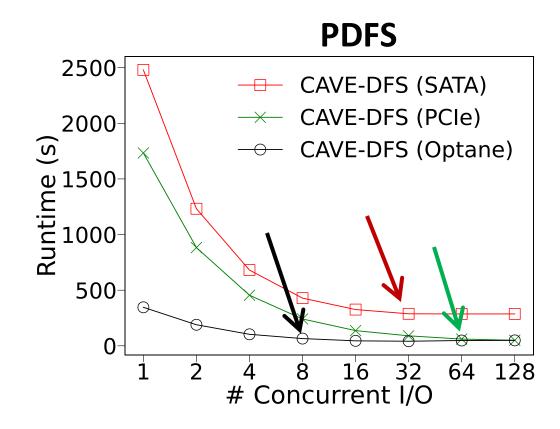




# CAVE Utilizes Concurrent I/O

Dataset: FS

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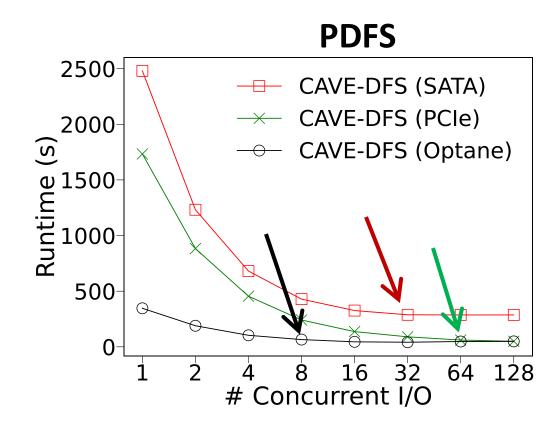
SATA SSD ( $k_r = 25$ ) PCIe SSD ( $k_r = 80$ ) Optane SSD ( $k_r = 6$ )



# CAVE Utilizes Concurrent I/O

Dataset: FS

Bada DisC



SATA SSD ( $k_r = 25$ ) PCIe SSD ( $k_r = 80$ ) Optane SSD ( $k_r = 6$ )

#### **Device gets saturated at** *optimal concurrency*