

# BU CS 332 – Theory of Computation

## Lecture 18:

- Time Complexity
- Complexity Class P

Reading:

Sipser Ch 7.1-7.2

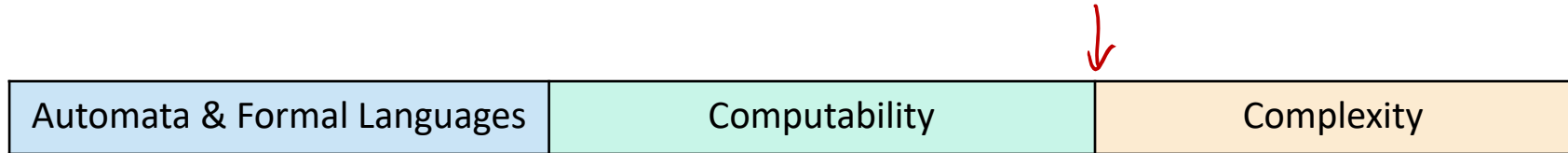
MW 7 due Monday April 13

Midterm (hopefully) graded  
by Thursday

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# Where we are in CS 332



Previous unit: **Computability theory**

What kinds of problems can / can't computers solve?

Final unit: **Complexity theory**

What kinds of problems can / can't computers solve under **constraints on their computational resources?**

*Restricted attention to "efficient algorithms"  
i.e. algs. using limited time or space*

# First topic: Time complexity

Today: Answering the basic questions

1. How do we measure complexity? (as in CS 330)
2. Asymptotic notation (as in CS 330)
3. How robust is the TM model when we care about measuring complexity?
4. How do we mathematically capture our intuitive notion of “efficient algorithms”?

# Running time analysis

For now:  
TM = basic single-tape TM

**Time complexity** of a TM (algorithm) = maximum number of steps it takes on a worst-case input

Running time is a function  $f$  of  $n = \text{input length}$

input lengths  $\downarrow$  running time

Formally: Let  $f : \mathbb{N} \rightarrow \mathbb{N}$ . A TM  $M$  runs in time  $f(n)$  if on every input  $w \in \Sigma^n$ ,  $M$  halts on  $w$  within at most  $f(n)$  steps

(Implicit:  $M$  is a decider)

- Focus on worst-case running time: Upper bound of  $f(n)$  must hold for all inputs of length  $n$
- Exact running time  $f(n)$  does not translate well between computational models / real computers. Instead focus on **asymptotic complexity**.

# Example

How much time does it take for a basic single-tape TM to decide  $A = \{0^m 1^m \mid m \geq 0\}$ ? Input length =  $n = 2m$

Let's analyze one particular TM  $M$ :

~~000111~~

Iteration 1 (step 2)

Iteration 2 (step 2)

Iteration 3



$M =$  "On input  $w$ :

- $O(n)$  →
1. Scan input and reject if not of the form  $0^*1^*$
  2. While input contains both 0's and 1's: (check:  $O(n)$  time  
Cross off one 0 and one 1 (crossing off:  $O(n)$  time
  3. **Accept** if no 0's and no 1's left. Otherwise, **reject**."

Execute this loop  $O(n)$  times

Final check in  $O(n)$

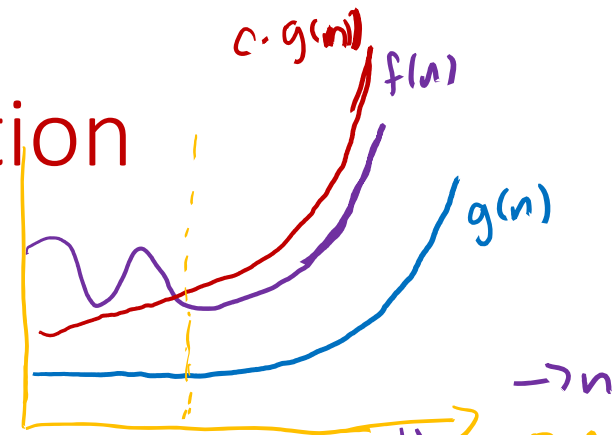
Total runtime:  $O(n) + O(n)[O(n)+O(n)] + O(n)$   
Step 1                      Step 2                      Step 3  
 $= O(n^2)$

# Review of asymptotic notation

$O$ -notation (upper bounds)

$$f, g: \mathbb{N} \rightarrow \mathbb{N}$$

$f(n) = O(g(n))$  means: " $f(n)$  is oh of  $g(n)$ "  $\rightarrow n \geq n_0 \Rightarrow f(n) \leq c g(n)$



There exist constants  $c > 0, n_0 > 0$  such that

$$f(n) \leq c g(n) \text{ for every } n \geq n_0$$

$$2n^2 = O(n^2) \text{ (true) but also:}$$

Example:  $2n^2 = O(n^3)$  ( $c = 2, n_0 = 0$ )

Justification:  $n \geq 0 \Rightarrow 2n^2 \leq 2n^3$

# Caution: = does not mean “equals”

Not reflexive:

$f(n) = O(g(n))$  does **not** mean  $g(n) = O(f(n))$

Example:  $f(n) = 2n^2$ ,  $g(n) = n^3$        $2n^2 = o(n^3)$

NOT the case that  $n^3 = O(2n^2)$

$O(g(n))$  = set of functions  
f w/ rate of growth  
≤ that of g

Alternative (better) notation:  $f(n) \in O(g(n))$

# Examples

- $10^6 n^3 + 2n^2 - n + 10 = O(n^3)$

- $\sqrt{n} + \log n = O(\sqrt{n})$

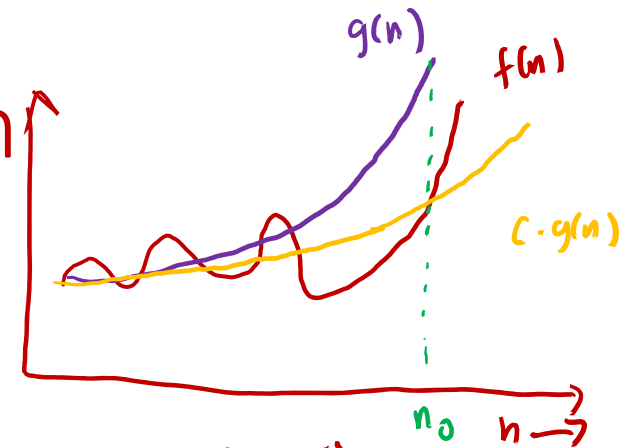
- $n(\log n + \sqrt{n}) = O(n\sqrt{n}) = O(n^{1.5})$

- $n = O(n)$  [ but also  $O(n^2)$ ,  $O(2^n)$ , ... ]



# Review of asymptotic notation

## $\Omega$ -notation (lower bounds)



$f(n) = \Omega(g(n))$  means: "f is (big) omega of g"

There exist constants  $c > 0$ ,  $n_0 > 0$  such that

$$f(n) \geq c g(n) \text{ for every } n \geq n_0$$

Example:  $\sqrt{n} = \Omega(\log n)$  ( $c = 1$ ,  $n_0 = 16$ )

Justification:  $n \geq 16 \Rightarrow \sqrt{n} \geq \log n$  [ $\log = \log_2$ ]

# When should we use $O$ vs. $\Omega$ ?

Upper bounds: Use  $O$

“The merge-sort algorithm **uses at most  $O(n \log n)$**  comparisons in the worst case”

Lower bounds: Use  $\Omega$

“Every comparison-based sorting algorithm **requires at least  $\Omega(n \log n)$**  comparisons in the worst case”

# Review of asymptotic notation

$\Theta$ -notation (tight bounds)

$f(n) = \Theta(g(n))$  means: "f is theta of g"  
 $f(n) = O(g(n))$  AND  $f(n) = \Omega(g(n))$

Example:  $\frac{1}{2}n^2 - 1000n = \Theta(n^2)$

Generally, polynomials are easy:

$$a_d n^d + a_{d-1} n^{d-1} + \dots + a_1 n + a_0 = \Theta(n^d)$$

$a_d > 0$

# Little-oh and little-omega

$O$ -notation and  $\Omega$ -notation are like  $\leq$  and  $\geq$ ;  
 $o$ -notation and  $\omega$ -notation are like  $<$  and  $>$

Asymptotic rate of growth of  $f$  is strictly slower than that of  $g$

$f(n) = o(g(n))$  means: " $f$  is little oh of  $g$ "

For **every** constant  $c > 0$ , there exists  $n_0 > 0$  such that

$$f(n) \leq c g(n) \text{ for every } n \geq n_0$$

Equivalently:  $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$

little omega ( $\omega$ ):  
reverse this to  $\geq$

Example:  $2n^2 = \omega(n^3)$  ( $n_0 = 2/c$ )

Justification:  $n \geq n_0 = \frac{2}{c} \implies 2n^2 \leq c n^3$

$$\lim_{n \rightarrow \infty} \frac{2n^2}{n^3} = \lim_{n \rightarrow \infty} \frac{2}{n} = 0$$

# A handy-dandy chart

Notation	... means ...	Think...	Example	$\lim_{n \leftarrow \infty} \frac{f(n)}{g(n)}$
$f(n) = O(g(n))$	$\exists c > 0, n_0 > 0, \forall n > n_0 :$ $f(n) < cg(n)$	Upper bound	$100n^2$ $= O(n^3)$	If it exists, it is $< \infty$
$f(n) = \Omega(g(n))$	$\exists c > 0, n_0 > 0, \forall n > n_0 :$ $cg(n) < f(n)$	Lower bound	$2^n$ $= \Omega(n^{100})$	If it exists, it is $> 0$
$f(n) = \Theta(g(n))$	both of the above: $f = \Omega(g)$ <b>and</b> $f = O(g)$	Tight bound	$\log(n!)$ $= \Theta(n \log n)$	If it exists, it is $> 0$ and $< \infty$
$f(n) = o(g(n))$	$\forall c > 0, \exists n_0 > 0, \forall n > n_0 :$ $f(n) < cg(n)$	Strict upper bound	$n^2 = o(2^n)$	Limit exists, $= 0$
$f(n) = \omega(g(n))$	$\forall c > 0, \exists n_0 > 0, \forall n > n_0 :$ $cg(n) < f(n)$	Strict lower bound	$n^2 = \omega(\log n)$	Limit exists, $= \infty$

# Asymptotic notation within expressions

Asymptotic notation within an expression is shorthand for an unspecified function satisfying the statement

## Examples:

- $n^{O(1)}$  means  $n^c$  for some constant  $c \geq 0$
- $n^2 + \Omega(n)$  means  $n^2 + g(n)$  for some  $g(n) = \Omega(n)$
- $(1 + o(1))n$  means  $(1 + \epsilon(n))n$  for some  $\epsilon(n) \rightarrow 0$  as  $n \rightarrow \infty$

# FAABs: Frequently asked asymptotic bounds

- **Polynomials.**  $a_0 + a_1n + \dots + a_d n^d$  is  $\Theta(n^d)$  if  $a_d > 0$
- **Logarithms.**  $\log_a n = \Theta(\log_b n)$  for all constants  $a, b > 0$

For every  $c > 0$ ,  $\log n = o(n^c)$

- **Exponentials.** For all  $b > 1$  and all  $d > 0$ ,  $n^d = o(b^n)$
- **Factorial.**  $n! = n(n-1) \cdots 1$

By Stirling's formula,

$$n! = (\sqrt{2\pi n}) \left(\frac{n}{e}\right)^n (1 + o(1)) = 2^{\Theta(n \log n)}$$

*Means:  $\exists g(n) = \Theta(n \log n)$  s.t.  $n! = 2^{g(n)} \Rightarrow \log_2(n!) = g(n)$   
 $\Rightarrow \log(n!) = \Theta(n \log n)$*

# Time Complexity



# Time complexity classes

Let  $f : \mathbb{N} \rightarrow \mathbb{N}$

$\text{TIME}(f(n))$  is a class (i.e., set) of languages:

"complexity class"

A language  $A \in \text{TIME}(f(n))$  if there exists a basic single-tape (deterministic) TM  $M$  that

- 1) Decides  $A$ , and
- 2) Runs in time  $O(f(n))$

# Example

$$A = \{0^m 1^m \mid m \geq 0\}$$

$M$  = "On input  $w$ :

1. Scan input and reject if not of the form  $0^*1^*$
2. While input contains both 0's and 1's:  
Cross off one 0 and one 1
3. **Accept** if no 0's and no 1's left. Otherwise, **reject**."

•  $M$  runs in time  $O(n^2) \implies A \in \text{TIME}(n^2)$

• Is there a faster algorithm?

# Example

$$A = \{0^m 1^m \mid m \geq 0\}$$

$M'$  = "On input  $w$ :

00000 11111

Iteration 1  
Iteration 2  
Iteration 3

1. Scan input and reject if not of the form  $0^*1^*$
2. While input contains both 0's and 1's:
  - **Reject** if the total number of 0's and 1's remaining is odd
  - Cross off every other 0 and every other 1 (cuts input size by a factor of 2)
3. **Accept** if no 0's and no 1's left. Otherwise, **reject**."

execute  
this loop  
 $O(\log n)$

- Running time of  $M'$ :  $O(n)$  +  $O(\log n) \cdot O(n)$  +  $O(n)$  =  $O(n \log n)$   
step 1                      step 2                      step 3
- Is there a faster algorithm?  $\Rightarrow A \in \text{TIME}(n \log n)$

# Example

Running time of  $M'$ :  $O(n \log n)$

**Theorem (Sipser, Problem 7.49):** If  $L$  can be decided in  $o(n \log n)$  time on a 1-tape TM, then  $L$  is regular

$A$  not regular  $\Rightarrow m'$  is (asymptotically) the fastest algorithm deciding  $A$

Does it matter that we're using the 1-tape model for this result?

**It matters:** 2-tape TMs can decide  $A$  faster

$M''$  = "On input  $w$ :

1. Scan input and reject if not of the form  $0^*1^*$   $O(n)$
2. Copy 0's to tape 2  $O(n)$
3. Scan tape 1. For each 1 read, cross off a 0 on tape 2  $O(n)$
4. If 0's on tape 2 finish at same time as 1's on tape 1, **accept**.  
Otherwise, **reject**."  $O(n)$

*Faster than what's possible on 1-tape*

**Analysis:**  $A$  is decided in time  $O(n)$  on a 2-tape TM

**Moral of the story (part 1):** Unlike decidability, time complexity depends on the TM model

## How *much* does the model matter?

**Theorem:** Let  $t(n) \geq n$  be a function. Every multi-tape TM running in time  $t(n)$  has an equivalent single-tape TM running in time  $O(t(n)^2)$  [converting from multi-tape to single-tape incurs  $\leq$  quadratic overhead]

### Proof idea:

We already saw how to **simulate** a multi-tape TM with a single-tape TM

Need a runtime analysis of this construction

**Moral of the story (part 2):** Time complexity doesn't depend too much on the TM model (as long as it's deterministic, sequential)

# Simulating Multiple Tapes

## Implementation-Level Description

Simulating  
 $k$  tape TM

On input  $w = w_1 w_2 \dots w_n$

1. Format tape into  $\# w_1 w_2 \dots w_n \# \square \# \square \# \dots \#$   $O(n + k)$

2. For each move of  $M$ : Outer loop: executed  $\leq t(n)$  times

Scan left-to-right, finding current symbols

Scan left-to-right, writing new symbols,

Scan left-to-right, moving each tape head

}  $O(k \cdot t(n))$   
time

If a tape head goes off the right end, insert blank

If a tape head goes off left end, move back right

}  $O(1)$

# How *much* does the model matter?

**Theorem:** Let  $t(n) \geq n$  be a function. Every multi-tape TM running in time  $t(n)$  has an equivalent single-tape TM running in time  $O(t(n)^2)$

**Proof:** Time analysis of simulation

- Time to initialize (i.e., format tape):  $O(n + k)$
- Time to simulate one step of multi-tape TM:  $O(t(n)^k)$

Reason:  $\leq t(n)$  cells in use if runtime of multi-tape TM is  $t(n)$

- Number of steps to simulate:  $t(n)$

=> Total time:  $O(n+k) + O(k \cdot t(n)) = O(t(n)^2)$  [for constant  $k$ ]





# Extended Church-Turing Thesis

Every “reasonable”<sup>\*</sup> model of computation can be simulated by a basic, single-tape TM with only a **polynomial** slowdown.

E.g., doubly infinite TMs, multi-tape TMs, RAM TMs

Does **not** include nondeterministic TMs (not reasonable)

**Possible counterexamples?** Randomized computation, parallel computation, DNA computing, quantum computation  
(*more believable: \* deterministic, sequential*)

# Complexity Class P

# Complexity class P

**Definition:** P is the class of languages decidable in polynomial time on a basic single-tape (deterministic) TM

$$P = \bigcup_{k=1}^{\infty} \text{TIME}(n^k)$$

$$= \text{TIME}(n) \cup \text{TIME}(n^2) \cup \text{TIME}(n^3) \cup \dots$$



- Class doesn't change if we substitute in another reasonable deterministic model (Extended Church-Turing)
- **Cobham-Edmonds Thesis:** <sup>"Roughly"</sup> Captures class of problems that are feasible to solve on computers

# Examples of languages in P

- $PATH = \{\langle G, s, t \rangle \mid G \text{ is a directed graph with a directed path from } s \text{ to } t\}$
- $A_{DFA} = \{\langle D, w \rangle \mid D \text{ is a DFA that accepts input } w\}$
- $RELPRIME = \{\langle x, y \rangle \mid x \text{ and } y \text{ are relatively prime}\}$
- $PRIMES = \{\langle x \rangle \mid x \text{ is prime}\}$

2006 Gödel Prize citation



The 2006 Gödel Prize for outstanding articles in theoretical computer science is awarded to Manindra Agrawal, Neeraj Kayal, and Nitin Saxena for their paper "PRIMES is in P."

In August 2002 one of the most ancient computational problems was finally solved....

- Every context-free language (section tomorrow)

Dynamic  
Programming