

BU CS 332 – Theory of Computation

Lecture 23:

- Savitch's Theorem
- PSPACE-Completeness
- Unconditional Hardness
- Course Evaluations

Reading:

Sipser Ch 8.1-8.3, 9.1

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Space analysis

Space complexity of a TM (algorithm) = maximum number of tape cell it uses on a worst-case input

Formally: Let $f : \mathbb{N} \rightarrow \mathbb{N}$. A TM M runs in space $f(n)$ if on every input $w \in \Sigma^*$, M halts on w using at most $f(n)$ cells

For nondeterministic machines: Let $f : \mathbb{N} \rightarrow \mathbb{N}$. An NTM N runs in space $f(n)$ if on every input $w \in \Sigma^*$, N halts on w using at most $f(n)$ cells on every computational branch

Space complexity classes

Let $f : \mathbb{N} \rightarrow \mathbb{N}$

A language $A \in \text{SPACE}(f(n))$ if there exists a basic single-tape (deterministic) TM M that

- 1) Decides A , and
- 2) Runs in space $O(f(n))$

A language $A \in \text{NSPACE}(f(n))$ if there exists a single-tape **nondeterministic** TM N that

- 1) Decides A , and
- 2) Runs in space $O(f(n))$

Savitch's Theorem

Savitch's Theorem: Deterministic vs. Nondeterministic Space

Theorem: Let f be a function with $f(n) \geq n$. Then $NSPACE(f(n)) \subseteq SPACE\left(\left(f(n)\right)^2\right)$.

Proof idea:

- Let N be an NTM deciding f in space $f(n)$
- We construct a TM M deciding f in space $O\left(\left(f(n)\right)^2\right)$
- Actually solve a more general problem:
 - Given configurations c_1, c_2 of N and natural number t , decide whether N can go from c_1 to c_2 in $\leq t$ steps on some nondeterministic path.
 - Design procedure $CANYIELD(c_1, c_2, t)$

Savitch's Theorem

Theorem: Let f be a function with $f(n) \geq n$. Then $NSPACE(f(n)) \subseteq SPACE\left((f(n))^2\right)$.

Proof idea:

- Let N be an NTM deciding f in space $f(n)$

$M =$ “On input w :

1. Output the result of $CANYIELD(c_1, c_2, 2^{df(n)})$ ”

where $CANYIELD(c_1, c_2, t)$ decides whether N can go from configuration c_1 to c_2 in $\leq t$ steps on some nondeterministic path

Savitch's Theorem

CANYIELD(c_1, c_2, t) decides whether N can go from configuration c_1 to c_2 in $\leq t$ steps on some nondeterministic path:

CANYIELD(c_1, c_2, t) =

1. If $t = 1$, **accept** if $c_1 = c_2$ or c_1 yields c_2 in one transition.
Else, **reject**.
2. If $t > 1$, then for each config c_{mid} of N with $\leq f(n)$ cells:
 3. Run CANYIELD($\langle c_1, c_{mid}, t/2 \rangle$).
 4. Run CANYIELD($\langle c_{mid}, c_2, t/2 \rangle$).
 5. If both runs accept, **accept**.
 6. **Reject**.

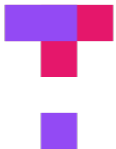
Complexity class PSPACE

Definition: PSPACE is the class of languages decidable in polynomial space on a basic single-tape (deterministic) TM

$$\text{PSPACE} = \bigcup_{k=1}^{\infty} \text{SPACE}(n^k)$$

Definition: NPSPACE is the class of languages decidable in polynomial space on a single-tape (nondeterministic) TM

$$\text{NPSPACE} = \bigcup_{k=1}^{\infty} \text{NSPACE}(n^k)$$



Relationships between complexity classes

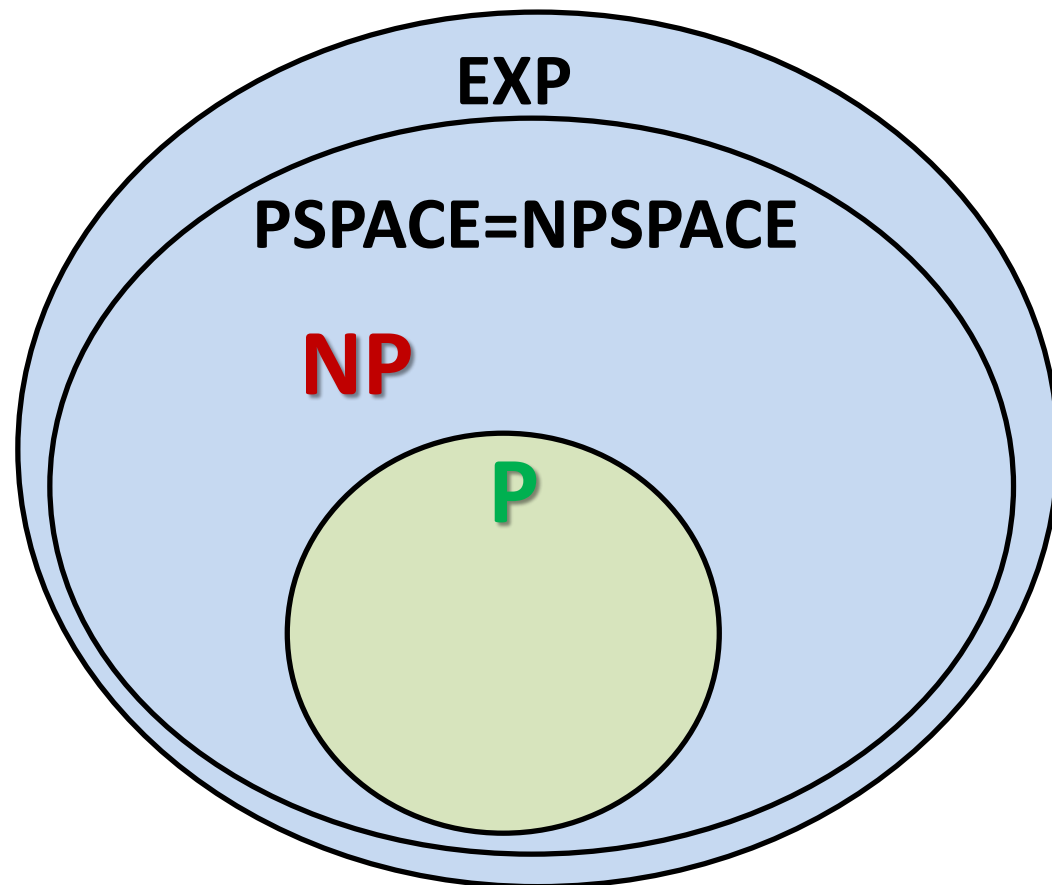
1. $P \subseteq NP \subseteq PSPACE \subseteq EXP$

since $SPACE(f(n)) \subseteq TIME(2^{O(f(n))})$

2. $P \neq EXP$ (Monday)

Which containments
in (1) are proper?

Unknown!



PSPACE-Completeness

What happens in a world where $P \neq PSPACE$?

Even more believable than $P \neq NP$, but still(!) very far from proving it

Question: What would $P \neq PSPACE$ allow us to conclude about problems we care about?

PSPACE-completeness: Find the “hardest” problems in PSPACE
Find $L \in PSPACE$ such that $L \in P$ iff $P = PSPACE$

Reminder: NP-completeness

Definition: A language B is NP-complete if

- 1) $B \in \text{NP}$, and
- 2) **Every** language $A \in \text{NP}$ is poly-time reducible to B , i.e., $A \leq_p B$ (“ B is NP-hard”)

PSPACE-completeness

Definition: A language B is **PSPACE**-complete if

1) $B \in \text{PSPACE}$, and

2) **Every** language $A \in \text{PSPACE}$ is poly-time reducible to B , i.e., $A \leq_p B$ (“ B is **PSPACE**-hard”)

A PSPACE-complete problem: TQBF

“Is a fully quantified logical formula true?”

- **Boolean variable:** Variable that can take on the value true/false (encoded as 0/1)
- **Boolean operations:** \wedge (AND), \vee (OR), \neg (NOT)
- **Boolean formula:** Expression made of Boolean variables and operations. **Ex:** $(x_1 \vee \overline{x_2}) \wedge x_3$
- **Fully quantified Boolean formula:** Boolean formula with all variables quantified (\forall, \exists) **Ex:** $\forall x_1 \exists x_3 \forall x_2 (x_1 \vee \overline{x_2}) \wedge x_3$
- Every fully quantified Boolean formula is either true or false
- **TQBF** = $\{\langle \varphi \rangle \mid \varphi \text{ is a true fully quantified formula}\}$

Theorem: TQBF is PSPACE-complete

Need to prove two things...



1) $TQBF \in PSPACE$

2) Every problem in PSPACE is poly-time reducible to $TQBF$ ($TQBF$ is PSPACE-hard)

1) TQBF is in PSPACE

T = “On input $\langle \varphi \rangle$,

where φ is a fully quantified Boolean formula:

1. If φ has no quantifiers, it has only constants (and no variables). Evaluate φ .

If true, **accept**; else, **reject**.

2. If φ is of the form $\exists x \psi$, recursively call T on ψ with $x = 0$ and then on ψ with $x = 1$.

If **either** call accepts, **accept**; else, **reject**.

3. If φ is of the form $\forall x \psi$, recursively call T on ψ with $x = 0$ and then on ψ with $x = 1$.

If **both** calls accept, **accept**; else, **reject**.”

- If n is the input length, T uses space $O(n)$.

2) TQBF is PSPACE-hard

Theorem: Every language $A \in \text{PSPACE}$ is poly-time reducible to $TQBF$

Proof idea:

Let $A \in \text{PSPACE}$ be decided by a poly-space deterministic TM M . Using proof of Cook-Levin Theorem,

M accepts input $w \iff$ formula $\varphi_{M,w}$ is true

Using idea of Savitch's Theorem, replace $\varphi_{M,w}$ with a quantified formula of poly-size that can be computed in poly-time

Unconditional Hardness

Hardness results so far

- If $P \neq NP$, then $3SAT \notin P$
- If $P \neq PSPACE$, then $TQBF \notin P$



Question: Are there decidable languages that we can show are not in P ?

Diagonalization redux

TM M						
M_1						
M_2						
M_3						
M_4						
\vdots						

Diagonalization redux

TM M	$M(\langle M_1 \rangle)$?	$M(\langle M_2 \rangle)$?	$M(\langle M_3 \rangle)$?	$M(\langle M_4 \rangle)$?		$D(\langle D \rangle)$?
M_1	Y	N	Y	Y	...	
M_2	N	N	Y	Y		
M_3	Y	Y	Y	N		
M_4	N	N	Y	N		
\vdots					\ddots	
D						

$\overline{SA_{TM}} = \{\langle M \rangle \mid M \text{ is a TM that does **not** accept input } \langle M \rangle\}$

$\overline{SA_{TM,EXP}} = \{\langle M \rangle \mid M \text{ is a TM that does **not** accept input } \langle M \rangle$
within } 2^{|\langle M \rangle|} \text{ steps}\}

An explicit undecidable language

- **Theorem:** $L = \overline{SA_{TM,EXP}} = \{\langle M \rangle \mid M \text{ is a TM that does not accept input } \langle M \rangle \text{ within } 2^{|\langle M \rangle|} \text{ steps}\}$

is in EXP, but not in P

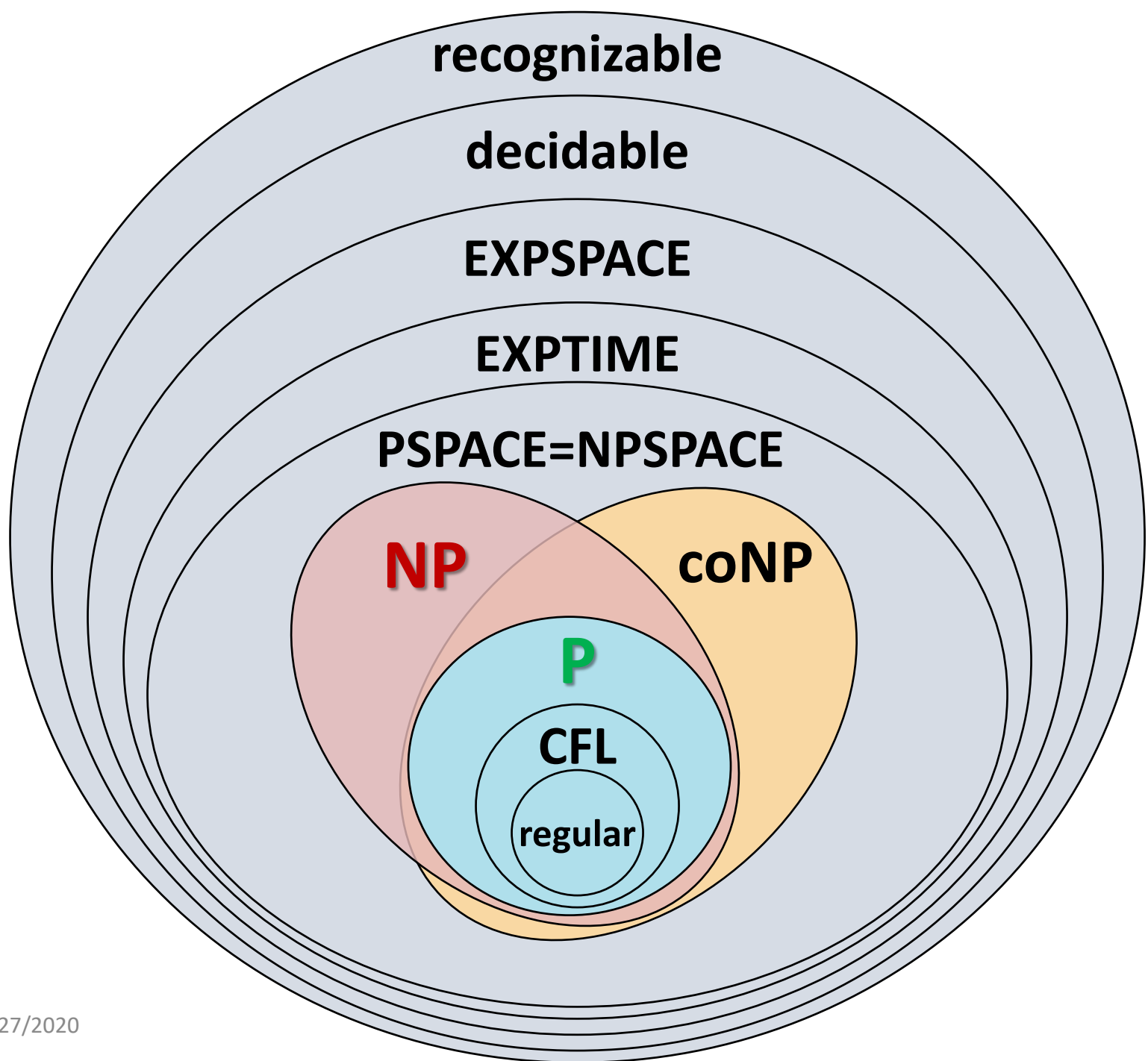
Proof:

- In EXP: Simulate M on input $\langle M \rangle$ for $2^{|\langle M \rangle|}$ steps and flip its decision
- Not in P: Suppose for contradiction that D decides L in time n^k

Time and space hierarchy theorems

- For any* function $f(n) \geq n \log n$, a language exists that is decidable in $f(n)$ time, but not in $o\left(\frac{f(n)}{\log f(n)}\right)$ time.
- For any* function $f(n) \geq n \log n$, a language exists that is decidable in $f(n)$ space, but not in $o(f(n))$ space.

*time constructible and space constructible, respectively



Course evaluations

<https://bu.campuslabs.com/courseeval>