

BU CS 332 – Theory of Computation

Lecture 24:

- More NP-completeness
- Space complexity (?)

Reading:

Sipser Ch 7.4-7.5,
8.1-8.2

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Polynomial-time reducibility

Definition:

A function $f: \Sigma^* \rightarrow \Sigma^*$ is **polynomial-time computable** if there is a **polynomial-time** TM M which, given as input any $w \in \Sigma^*$, halts with only $f(w)$ on its tape.

Definition:

Language A is **polynomial-time reducible** to language B , written

$$A \leq_p B$$

if there is a **polynomial-time** computable function $f: \Sigma^* \rightarrow \Sigma^*$ such that for all strings $w \in \Sigma^*$, we have $w \in A \iff f(w) \in B$

NP-completeness

“The hardest languages in NP”

Definition: A language B is NP-complete if

- 1) $B \in \text{NP}$, and
- 2) **Every** language $A \in \text{NP}$ is poly-time reducible to B , i.e., $A \leq_p B$ (“ B is NP-hard”)

The usual way to prove NP-completeness

Theorem:

If

1) $C \in \text{NP}$, and

2) There is an NP-complete language B such that

$$B \leq_p C$$

then C is NP-complete.

Some general reduction strategies

- Reduction by simple equivalence

Ex. $IND - SET \leq_p VERTEX - COVER$

$VERTEX - COVER \leq_p IND - SET$

- Reduction from special case to general case

Ex. $VERTEX - COVER \leq_p SET - COVER$

$3SAT \leq_p SAT$

- “Gadget” reductions

Ex. $SAT \leq_p 3SAT$

$3SAT \leq_p IND - SET$

3SAT (3-CNF Satisfiability)



Definitions:

- A **literal** either a variable or its negation $x_5, \overline{x_7}$
- A **clause** is a disjunction (OR) of literals **Ex.** $x_5 \vee \overline{x_7} \vee x_2$
- A **3-CNF** is a conjunction (AND) of clauses where each clause contains exactly 3 literals

Ex. $C_1 \wedge C_2 \wedge \dots \wedge C_m =$

$$(x_5 \vee \overline{x_7} \vee x_2) \wedge (\overline{x_3} \vee x_4 \vee x_1) \wedge \dots \wedge (x_1 \vee x_1 \vee x_1)$$

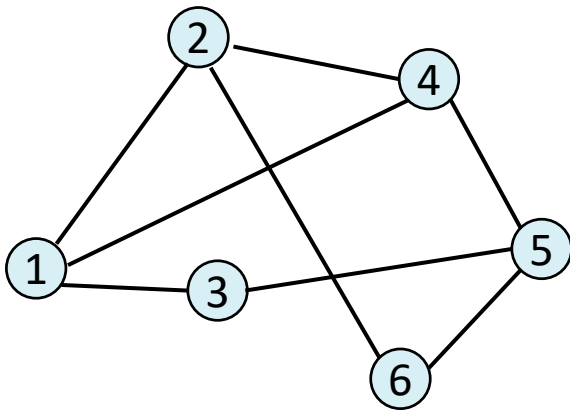
$$3SAT = \{\langle \varphi \rangle \mid \varphi \text{ is a satisfiable 3-CNF}\}$$

Last time: 3SAT is NP-complete

Independent Set

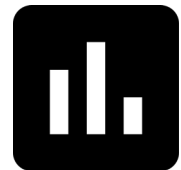
An **independent set** in an undirected graph G is a set of vertices that includes at most one endpoint of every edge.

$IND - SET = \{\langle G, k \rangle \mid G \text{ is an undirected graph containing an independent set with } \geq k \text{ vertices}\}$



Which of the following are independent sets in this graph?

- a) {1}
- b) {1, 5}
- c) {2, 3, 6}
- d) {3, 4, 6}



Independent Set is NP-complete

- 1) $IND - SET \in NP$
- 2) Reduce $3SAT \leq_p IND - SET$

Proof of 1) The following gives a poly-time verifier for $IND - SET$

Certificate: Vertices v_1, \dots, v_k

Verifier:

- “On input $\langle G, k; v_1, \dots, v_k \rangle$, where G is a graph, k is a natural number,
1. Check that v_1, \dots, v_k are distinct vertices in G
 2. Check that there are no edges between the v_i 's.”

Independent Set is NP-complete

- 1) $IND - SET \in NP$
- 2) Reduce $3SAT \leq_p IND - SET$

Proof of 2) The following TM computes a poly-time reduction.

“On input $\langle \varphi \rangle$, where φ is a 3CNF formula,

1. Construct graph G from φ
 - G contains 3 vertices for each clause, one for each literal.
 - Connect 3 literals in a clause in a triangle.
 - Connect every literal to each of its negations.
2. Output $\langle G, k \rangle$, where k is the number of clauses in φ .”

Example of the reduction

$$\varphi = (\overline{x_1} \vee x_2 \vee x_3) \wedge (x_1 \vee \overline{x_2} \vee x_3) \wedge (\overline{x_1} \vee x_2 \vee x_3)$$

Proof of correctness for reduction

Let $k = \#$ clauses and $l = \#$ literals in φ

Correctness: φ is satisfiable iff G has an independent set of size k

\Rightarrow Given a satisfying assignment, select one true literal from each triangle. This is an independent set of size k

\Leftarrow Let S be an independent set in G of size k

- S must contain exactly one vertex in each triangle
- Set these literals to true, and set all other variables arbitrarily
- Truth assignment is consistent and all clauses are satisfied

Runtime: $O(k + l^2)$ which is polynomial in input size

Some general reduction strategies

- Reduction by simple equivalence

$$\text{Ex. } \boxed{\begin{array}{l} \text{IND} - \text{SET} \leq_p \text{VERTEX} - \text{COVER} \\ \text{VERTEX} - \text{COVER} \leq_p \text{IND} - \text{SET} \end{array}}$$

- Reduction from special case to general case

$$\text{Ex. } \begin{array}{l} \text{VERTEX} - \text{COVER} \leq_p \text{SET} - \text{COVER} \\ 3\text{SAT} \leq_p \text{SAT} \end{array}$$

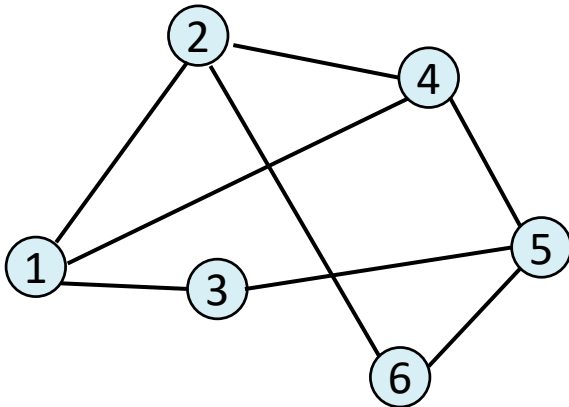
- “Gadget” reductions

$$\text{Ex. } \begin{array}{l} \text{SAT} \leq_p 3\text{SAT} \\ 3\text{SAT} \leq_p \text{IND} - \text{SET} \end{array}$$

Vertex Cover

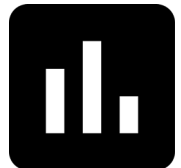
Given an undirected graph G , a **vertex cover** in G is a subset of nodes which includes at **least** one endpoint of every edge.

$VERTEX - COVER = \{ \langle G, k \rangle \mid G \text{ is an undirected graph which has a vertex cover with } \leq k \text{ vertices} \}$



Which of the following are vertex covers in this graph?

- a) {1}
- b) {1, 6}
- c) {1, 2, 5}
- d) {1, 2, 5, 6}

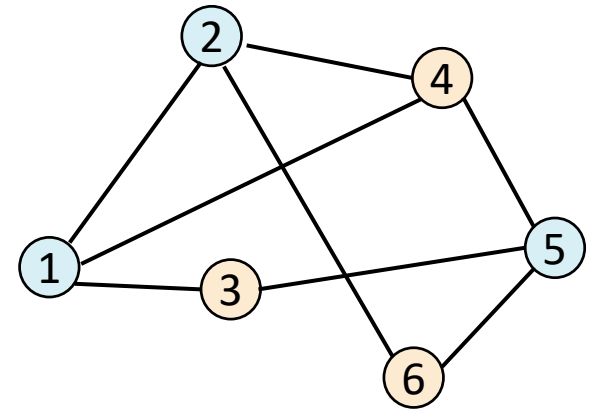


Independent Set and Vertex Cover

Claim. S is an independent set iff $V \setminus S$ is a vertex cover.

\Rightarrow Let S be any independent set.

- Consider an arbitrary edge (u, v) .
- S is independent $\Rightarrow u \notin S$ or $v \notin S \Rightarrow u \in V \setminus S$ or $v \in V \setminus S$.
- Thus, $V \setminus S$ covers (u, v) .



\Leftarrow Let $V \setminus S$ be any vertex cover.

- Consider two nodes $u \in S$ and $v \in S$.
- Then $(u, v) \notin E$ since $V \setminus S$ is a vertex cover.
- Thus, no two nodes in S are joined by an edge $\Rightarrow S$ is an independent set.

INDEPENDENT SET reduces to VERTEX COVER

Theorem. $\text{IND-SET} \leq_p \text{VERTEX-COVER}$.



What do we need to do to prove this theorem?

- a) Construct a poly-time nondet. TM deciding IND-SET
- b) Construct a poly-time deterministic TM deciding IND-SET
- c) Construct a poly-time nondet. TM mapping instances of IND-SET to instances of VERTEX-COVER
- d) Construct a poly-time deterministic TM mapping instances of IND-SET to instances of VERTEX-COVER
- e) Construct a poly-time nondet. TM mapping instances of VERTEX-COVER to instances of IND-SET
- f) Construct a poly-time deterministic TM mapping instances of VERTEX-COVER to instances of IND-SET

INDEPENDENT SET reduces to VERTEX COVER

Theorem. $\text{IND-SET} \leq_p \text{VERTEX-COVER}$.

Proof. The following TM computes the reduction.

“On input $\langle G, k \rangle$, where G is an undirected graph and k is an integer,

1. Output $\langle G, n - k \rangle$, where n is the number of nodes in G .”

Correctness:

- G has an independent set of size at least k iff it has a vertex cover of size at most $n - k$.

Runtime:

- Reduction runs in linear time.

VERTEX COVER reduces to INDEPENDENT SET

Theorem. VERTEX-COVER \leq_p IND-SET

Proof. The following TM computes the reduction.

“On input $\langle G, k \rangle$, where G is an undirected graph and k is an integer,

1. Output $\langle G, n - k \rangle$, where n is the number of nodes in G .”

Correctness:

- G has a vertex cover of size at most k iff it has an independent set of size at least $n - k$.

Runtime:

- Reduction runs in linear time.

A Brief Tour of Space (Complexity)

Space analysis

Space complexity of a TM (algorithm) = maximum number of tape cells it uses on a worst-case input

Formally: Let $f : \mathbb{N} \rightarrow \mathbb{N}$. A TM M runs in space $f(n)$ if on every input $w \in \Sigma^*$, M halts on w using at most $f(n)$ cells

For nondeterministic machines: Let $f : \mathbb{N} \rightarrow \mathbb{N}$. An NTM N runs in space $f(n)$ if on every input $w \in \Sigma^*$, N halts on w using at most $f(n)$ cells on every computational branch

Space complexity classes

Let $f : \mathbb{N} \rightarrow \mathbb{N}$

A language $A \in \text{SPACE}(f(n))$ if there exists a basic single-tape (deterministic) TM M that

- 1) Decides A , and
- 2) Runs in space $O(f(n))$

A language $A \in \text{NSPACE}(f(n))$ if there exists a single-tape **nondeterministic** TM N that

- 1) Decides A , and
- 2) Runs in space $O(f(n))$

Space vs. Time

$$\begin{aligned} \text{TIME}(f(n)) &\subseteq \text{NTIME}(f(n)) \\ &\subseteq \text{SPACE}(f(n)) \subseteq \text{NSPACE}(f(n)) \end{aligned}$$

How about the opposite direction? Can low-space algorithms be simulated by low-time algorithms?

Theorem: A TM running in space $f(n)$ also runs in time $2^{O(f(n))}$

Savitch's Theorem: Deterministic vs. Nondeterministic Space

Theorem: Let f be a function with $f(n) \geq \log n$. Then $\text{NSPACE}(f(n)) \subseteq \text{SPACE}\left((f(n))^2\right)$.

Complexity class PSPACE

Definition: PSPACE is the class of languages decidable in polynomial space on a basic single-tape (deterministic) TM

$$\text{PSPACE} = \bigcup_{k=1}^{\infty} \text{SPACE}(n^k)$$

Definition: NPSPACE is the class of languages decidable in polynomial space on a single-tape (nondeterministic) TM

$$\text{NPSPACE} = \bigcup_{k=1}^{\infty} \text{NSPACE}(n^k)$$

Relationships between complexity classes

1. $P \subseteq NP \subseteq PSPACE \subseteq EXP$

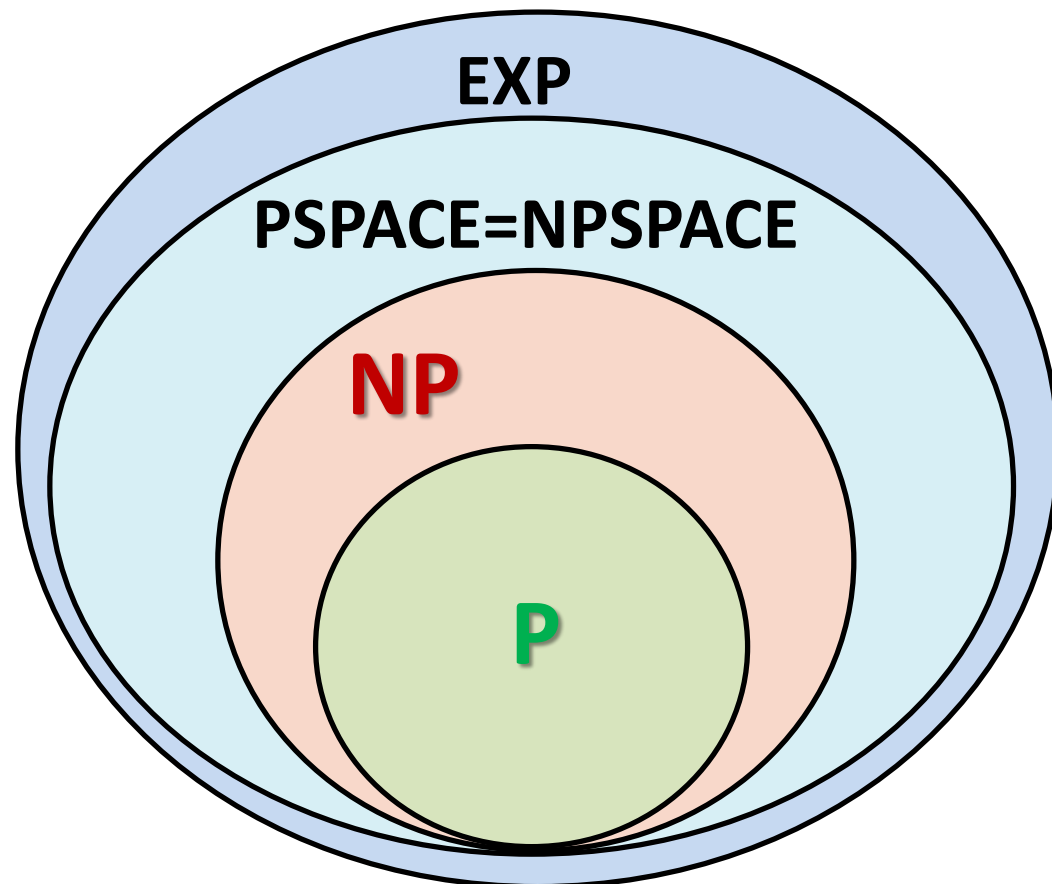
since $SPACE(f(n)) \subseteq TIME(2^{O(f(n))})$

2. $P \neq EXP$

(via time hierarchy)

Which containments
in (1) are proper?

Unknown!



Course Evaluations

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