

# BU CS 332 – Theory of Computation



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## Lecture 10:

- Turing Machines
- TM Variants and Closure Properties

Reading:

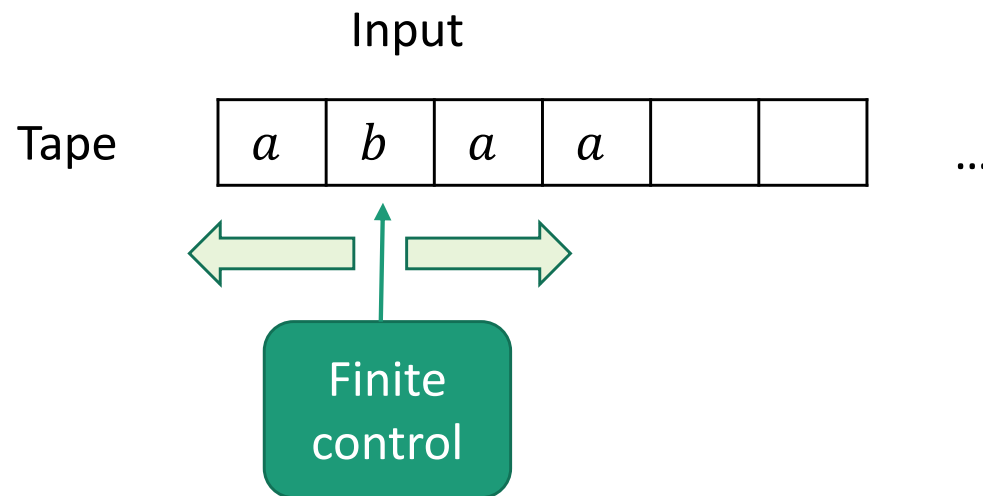
Sipser Ch 3.1-3.3

M W Y due  
Friday 3/1  
11:59 PM

Mark Bun

February 28, 2024

# The Basic Turing Machine (TM)



- Input is written on an infinitely long tape
- Head can both read and write, and move in both directions
- Computation halts as soon as control reaches “accept” or “reject” state

# Three Levels of Abstraction

## High-Level Description

An algorithm (like CS 330)

## Implementation-Level Description

Describe (in English) the instructions for a TM

- How to move the head
- What to write on the tape

## Low-Level Description

State diagram or formal specification

# Example

Determine if a string  $w \in \{0\}^*$  is in the language

$$A = \{0^{2^n} \mid n \geq 0\}$$

## High-Level Description

Repeat the following forever:

- If there is exactly one 0 in  $w$ , **accept**
- If there is an odd ( $> 1$ ) number of 0s in  $w$ , **reject**
- Delete half of the 0s in  $w$

# Example

Determine if a string  $w \in \{0\}^*$  is in the language

$$A = \{0^{2^n} \mid n \geq 0\}$$

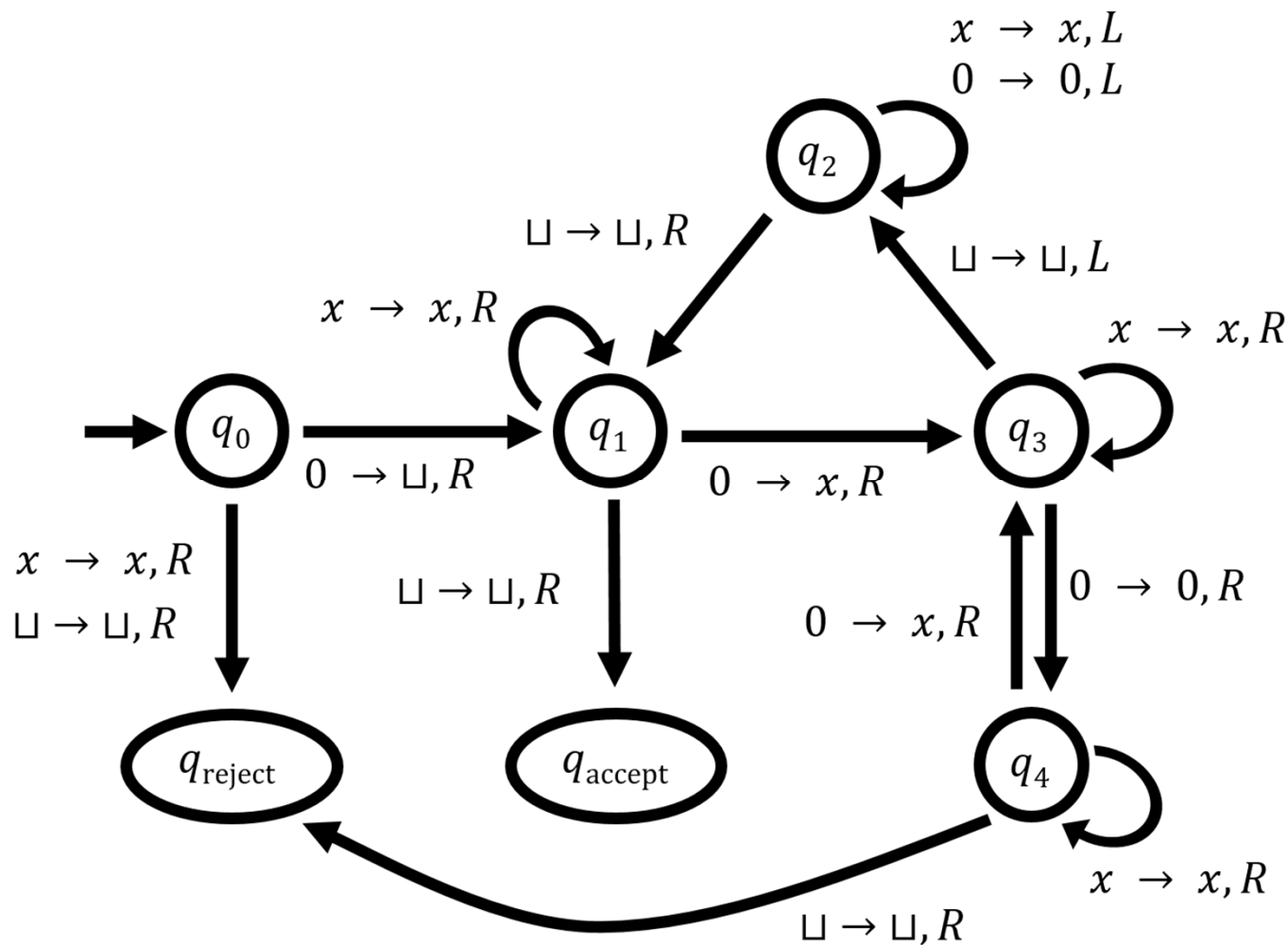
## Implementation-Level Description

1. While moving the tape head left-to-right:
  - a) Cross off every other 0 (i.e., replace it with symbol x)
  - b) If there is exactly one 0 when we reach the right end of the tape, **accept**
  - c) If there is an odd ( $> 1$ ) number of 0s when we reach the right end of the tape, **reject**
2. Return the head to the left end of the tape
3. Go back to step 1

# Example

Determine if a string  $w \in A = \{0^{2^n} \mid n \geq 0\}$

## Low-Level Description



# Formal Definition of a TM

A TM is a 7-tuple  $M = (Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}}, q_{\text{reject}})$

- $Q$  is a finite set of states
- $\Sigma$  is the input alphabet (does **not** include  $\sqcup$ )
- $\Gamma$  is the tape alphabet (contains  $\sqcup$  and  $\Sigma$ ) <sup>eg.  $x \in \Gamma$</sup>
- $\delta$  is the transition function

...more on this later

- $q_0 \in Q$  is the start state
- $q_{\text{accept}} \in Q$  is the accept state
- $q_{\text{reject}} \in Q$  is the reject state ( $q_{\text{reject}} \neq q_{\text{accept}}$ )

# TM Transition Function

$$\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$$

Handwritten annotations with arrows pointing to the symbols in the equation above:  
-  $Q$  (input): current state  
-  $\Gamma$  (input): current symbol  
-  $Q$  (output): next state  
-  $\Gamma$  (output): next symbol  
-  $\{L, R\}$  (output): movement instruction

$L$  means “move left” and  $R$  means “move right”

$\delta(p, a) = (q, b, R)$  means:

- Replace  $a$  with  $b$  in current cell
- Transition from state  $p$  to state  $q$
- Move tape head right

$\delta(p, a) = (q, b, L)$  means:

- Replace  $a$  with  $b$  in current cell
- Transition from state  $p$  to state  $q$
- Move tape head left UNLESS we are at left end of tape, in which case don't move

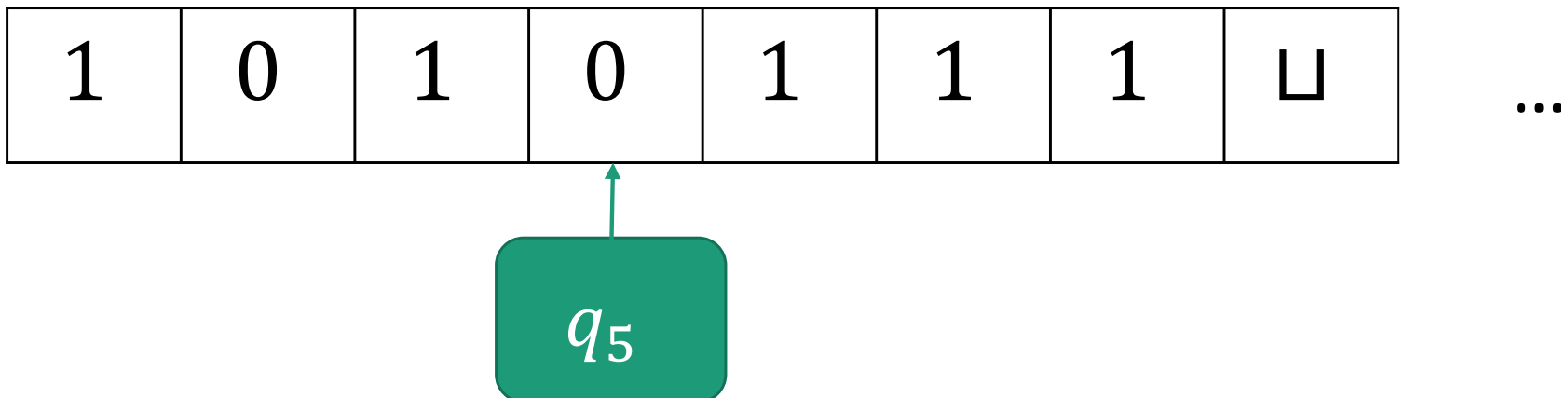


# Configuration of a TM: Formally

A **configuration** is a string  $uqv$  where  $q \in Q$  and  $u, v \in \Gamma^*$

- Tape contents =  $uv$  (followed by infinitely many blanks  $\sqcup$ )
- Current state =  $q$
- Tape head on first symbol of  $v$

Example:  $101q_50111$



# How a TM Computes

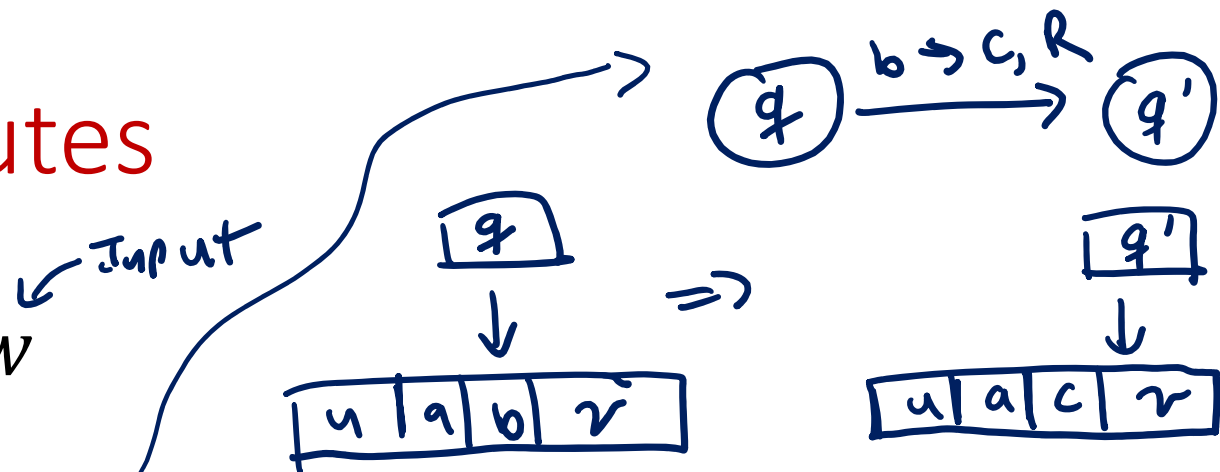
Start configuration:  $q_0 w$

One step of computation:

- If  $\delta(q, b) = (q', c, R)$ , then  $u a q b v$  yields  $u a c q' v$
- If  $\delta(q, b) = (q', c, L)$ , then  $u a q b v$  yields  $u q' a c v$
- If  $\delta(q, b) = (q', c, L)$ , then  $q b v$  yields  $q' c v$

Accepting configuration:  $q = q_{\text{accept}}$

Rejecting configuration:  $q = q_{\text{reject}}$



# How a TM Computes

$M$  **accepts** input  $w$  if there exists a sequence of configurations  $C_1, \dots, C_k$  such that:

- $C_1 = q_0 w$
- $C_i$  yields  $C_{i+1}$  for every  $i$  Can get from config  $C_i$  to  $C_{i+1}$  in one step of computation
- $C_k$  is an accepting configuration

$L(M)$  = the set of all strings  $w$  which  $M$  accepts

$A$  is **Turing-recognizable** if  $A = L(M)$  for some TM  $M$ :

- $w \in A \implies M$  halts on  $w$  in state  $q_{\text{accept}}$
- $w \notin A \implies M$  halts on  $w$  in state  $q_{\text{reject}}$  OR  
 $M$  runs forever on  $w$

eg.  
TM  $B$ :  
On input  $w$ :  
Enter an infinite loop  
 $L(B) = \emptyset$

# Recognizers vs. Deciders

$L(M)$  = the set of all strings  $w$  which  $M$  accepts

$A$  is **Turing-recognizable** if  $A = L(M)$  for some TM  $M$ :

- $w \in A \implies M$  halts on  $w$  in state  $q_{\text{accept}}$
- $w \notin A \implies M$  halts on  $w$  in state  $q_{\text{reject}}$  OR  
(  $M$  runs forever on  $w$  )

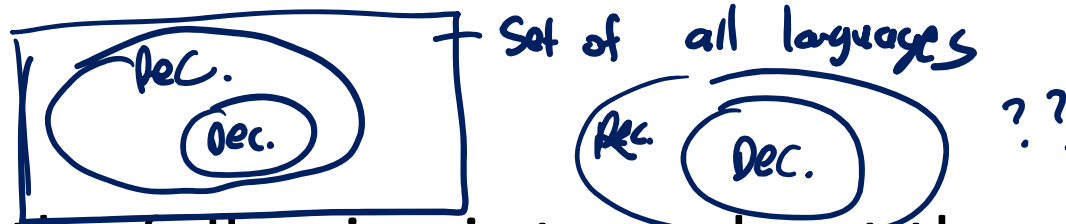
*$A$  is Turing decidable  $\implies A$  is Turing recognizable*

$A$  is **(Turing-)decidable** if  $A = L(M)$  for some TM  $M$

which halts on every input

- $w \in A \implies M$  halts on  $w$  in state  $q_{\text{accept}}$
- $w \notin A \implies M$  halts on  $w$  in state  $q_{\text{reject}}$

# Recognizers vs. Deciders



Which of the following is true about the relationship between decidable and recognizable languages?

*A decidable  $\Rightarrow$  A recognizable*

*{ decidable langs. }  $\subseteq$  { recognizable langs }*

- a) The decidable languages are a subset of the recognizable languages
- b) The recognizable languages are a subset of the decidable languages
- c) They are incomparable: There might be decidable languages which are not recognizable and vice versa

# Example: Arithmetic on a TM

The following TM decides  $MULT = \{a^i b^j c^k \mid i \times j = k\}$ :

On input string  $w$ : *High-level*

1. Check  $w$  is formatted correctly
2. For each  $a$  appearing in  $w$ :
3.     For each  $b$  appearing in  $w$ :
4.         Attempt to cross off a  $c$ . If none exist, **reject**.
5. If all  $c$ 's are crossed off, **accept**. Else, **reject**.

# Example: Arithmetic on a TM

Ex. ~~a a bbb ccc ccc~~  
~~a a bbb ccc ccc~~  
~~a a bbb ccc ccc~~

The following TM decides  $MULT = \{a^i b^j c^k \mid i \times j = k\}$ :

On input string  $w$ : *Implementation-level*

1. Scan the input from left to right to determine whether it is a member of  $L(a^* b^* c^*)$  *Follows from fact that regular languages are recognized by DFAs.*
2. Return head to left end of tape
3. Cross off an  $a$  if one exists. Scan right until a  $b$  occurs. Shuttle between  $b$ 's and  $c$ 's crossing off one of each until all  $b$ 's are gone. **Reject** if all  $c$ 's are gone but some  $b$ 's remain.
4. Restore crossed off  $b$ 's. If any  $a$ 's remain, repeat step 3.
5. If all  $c$ 's are crossed off, **accept**. Else, **reject**.

# Back to Hilbert's Tenth Problem

**Computational Problem:** Given a Diophantine equation, does it have a solution over the integers?

$$L = \left\{ p(x_1, \dots, x_n) \mid p \text{ is an integer polynomial and } \exists z_1, \dots, z_n \in \mathbb{Z}^n \text{ s.t. } p(z_1, \dots, z_n) = 0 \right\}$$

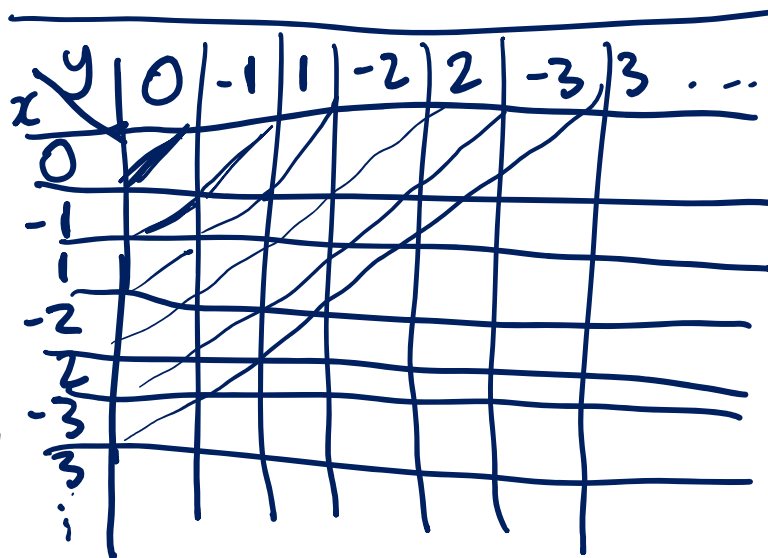
- $L$  is Turing-recognizable

Special case:  $p(x, y)$

TM  $M$ :

On input  $p(x, y)$ :

- Try evaluating  $p(x, y)$  on inputs in order specified by  $\rightarrow$
- If any evaluate to 0, accept.



Eval.

- 1)  $p(0, 0)$
- 2)  $p(-1, 0)$
- 3)  $p(-1, -1)$
- 4)  $p(1, 1)$
- ...

$M$  recognizes  $L$ . Accepts all  $p \in L$ , loops forever on all  $p \notin L$ .

- $L$  is **not** decidable (1949-70)





# TM Variants

# How Robust is the TM Model?

Does changing the model result in different languages being recognizable / decidable?

So far we've seen...



- We can require that NFAs have a single accept state
- Adding nondeterminism does not change the languages recognized by finite automata

Other modifications possible too: E.g., allowing DFAs to have multiple passes over their input does not increase their power

Turing machines have an **astounding** level of robustness

# TMs are equivalent to...

- TMs with “stay put”
- TMs with 2-way infinite tapes
- Multi-tape TMs
- Nondeterministic TMs
- Random access TMs
- Enumerators
- Finite automata with access to an unbounded queue
- Primitive recursive functions *≈ lambda calculus*
- Cellular automata
- ...

# Equivalent TM models



- TMs that are allowed to “stay put” instead of moving left or right

$$\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, \underline{S}\} \text{ Stay put}$$

TMs with stay put are at least as powerful as basic TMs

(Every basic TM is a TM with stay put that never stays put)

How would you show that TMs with stay put are no more powerful than basic TMs?

- a) Convert any basic TM into an equivalent TM with stay put
- b) Convert any TM with stay put into an equivalent basic TM
- c) Construct a language that is recognizable by a TM with stay put, but not by any basic TM
- d) Construct a language that is recognizable by a basic TM, but not by any TM with stay put

# Equivalent TM models

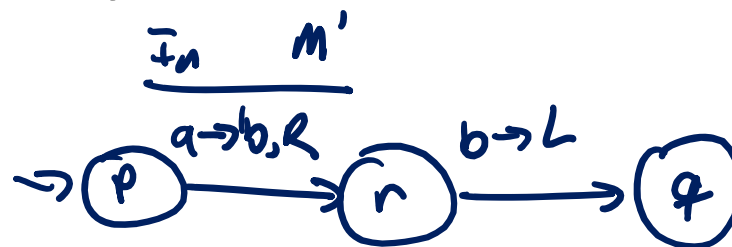
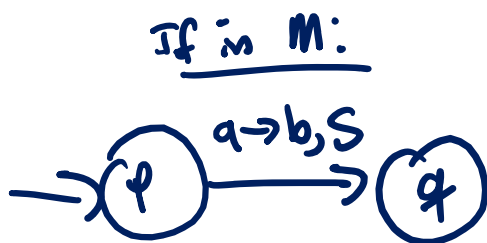
- TMs that are allowed to “stay put” instead of moving left or right

$$\delta : Q \times \Gamma \rightarrow Q \times \Gamma \times \{L, R, S\}$$

**Proof** that TMs with stay put are no more powerful:

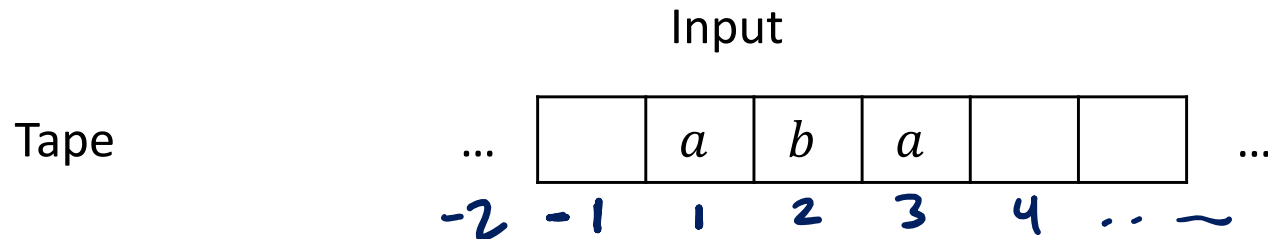
**Simulation:** Our goal is to convert any TM  $M$  with stay put into an equivalent basic TM  $M'$

How? Replace every stay put instruction in  $M$  with a move right instruction, followed by a move left instruction in  $M'$



# Equivalent TM models

- TMs with a 2-way infinite tape, unbounded left to right



**Proof** that TMs with 2-way infinite tapes are no more powerful:

**Simulation:** Convert any TM  $M$  with 2-way infinite tape into a 1-way infinite TM  $M'$  with a “two-track tape”



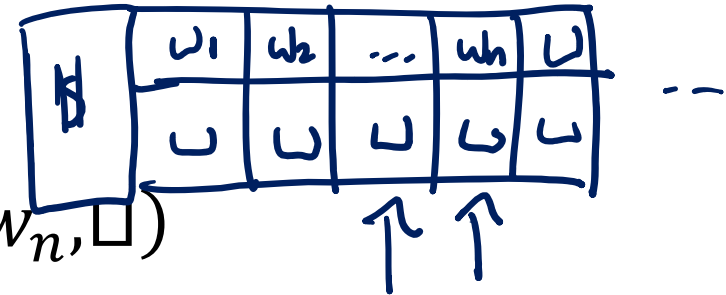
# Implementation-Level Simulation

Given 2-way TM  $\underline{M}$  construct a basic TM  $\underline{M'}$  as follows.

TM  $\underline{M'}$  = "On input  $w = w_1 w_2 \dots w_n$ :

1. Format 2-track tape with contents

$\$, (w_1, \sqcup), (w_2, \sqcup), \dots, (w_n, \sqcup)$



2. To simulate one move of  $\underline{M}$ :

a) If working on upper track, read/write to the first position of cell under tape head, and move in the same direction as  $\underline{M}$

b) If working on lower track, read/write to second position of cell under tape head, and move in the opposite direction as  $\underline{M}$

c) If move results in hitting \$, switch to the other track. ”

# Formalizing the Simulation

Given 2-way TM  $M = (Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}}, q_{\text{reject}})$ , construct  $M' = (Q', \Sigma, \Gamma', \delta', q'_0, q'_{\text{accept}}, q'_{\text{reject}})$

upper track  
lower track

**New tape alphabet:**  $\Gamma' = (\Gamma \times \Gamma) \cup \{\$\}$

**New state set:**  $Q' = Q \times \{+, -\}$

$(q, +)$  means “in state  $q$  and working on upper track”

$(q, -)$  means “in state  $q$  and working on lower track”

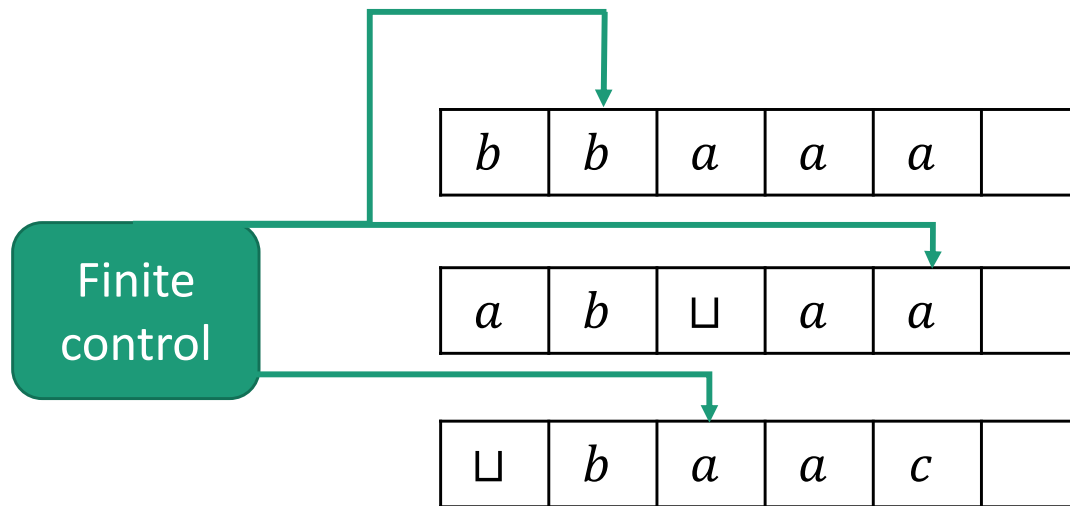
**New transitions:**

If  $\delta(p, a_-) = (q, b, L)$ , let  $\delta'((p, -), (a_-, a_+)) = ((q, -), (b, a_+), R)$

Also need new transitions for moving right, lower track, hitting \$,  
initializing input into 2-track format



# Multi-Tape TMs



Fixed number of tapes  $k$

( $k$  can't depend on input or change during computation)

Transition function  $\delta : Q \times \Gamma^k \rightarrow Q \times \Gamma^k \times \{L, R, S\}^k$

$\downarrow$  current state       $\uparrow$   $k$  symbols read       $\uparrow$  new state       $\uparrow$   $k$  symbols written       $\uparrow$   $k$  directions

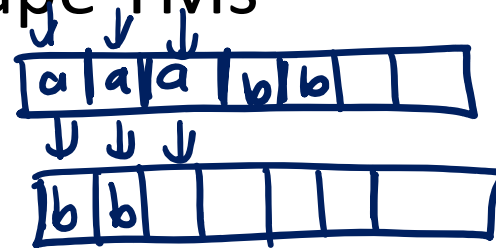
# Why are Multi-Tape TMs Helpful?

To show a language is Turing-recognizable or decidable, it's enough to construct a multi-tape TM

Often easier to construct multi-tape TMs

Ex. Decider for  $\{a^i b^j \mid i > j\}$

On input  $w$ :



- 1) Check in one left-to-right pass that  $w \in L(a^* b^*)$
- 2) Copy all b's to tape 2
- 3) Check one character at a time that every b has a matching a
- 4) Check at least one a left over.