

Random Walks as a Stable Analogue of Eigenvectors (with Applications to Nearly-Linear-Time Graph Partitioning)

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Based on joint works with Michael Mahoney (Stanford), Sushant Sachdeva (Yale) and Nisheeth Vishnoi (MSR India).

Why Spectral Algorithms for Graph Problems ...

... in practice?

- Simple to **implement**
- Can exploit **very efficient** linear algebra routines
- Perform **well in practice** for many problems

... in theory?

- Connections between **spectral and combinatorial** objects
- Connections to Markov Chains and Probability Theory
- Intuitive geometric viewpoint

RECENT ADVANCES:

Fast algorithms for fundamental combinatorial problems
rely on spectral and optimization ideas

Spectral Algorithms for Graph Partitioning

Spectral algorithms are **widely used** in many graph-partitioning applications: clustering, image segmentation, community-detection, etc.

CLASSICAL VIEW:

- Based on **Cheeger's Inequality**
- Eigenvectors **sweep-cuts** reveal sparse cuts in the graph

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NEW TREND:

- **Random walk vectors** replace eigenvectors:
 - Fast Algorithms for Graph Partitioning
 - Local Graph Partitioning
 - Real Network Analysis
- Different random walks: **PageRank**, **Heat-Kernel**, etc.

Why Random Walks? A Practitioner's View

Advantages of Random Walks:

1) Quick approximation to eigenvector in massive graphs

A = adjacency matrix

D = diagonal degree matrix

$W = AD^{-1}$ = natural random walk matrix $L = D - A$ = Laplacian matrix

Second Eigenvector of the Laplacian can be computed by iterating W :

For random y_0 s.t. $y_0^T D^{-1} \mathbf{1} = 0$, compute

$$D^{-1} W^t y_0$$

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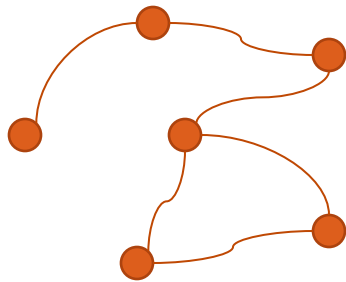
Heuristic: For massive graphs, pick t as large as computationally affordable.

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Advantages of Random Walks:

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- 2) Statistical robustness

Real-world graphs are **noisy**



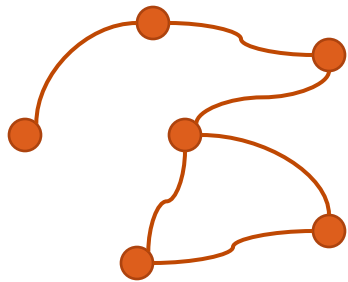
**GROUND TRUTH
GRAPH**

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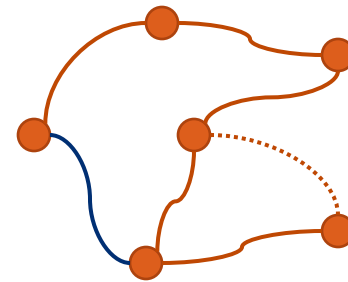
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**GROUND-TRUTH
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**NOISY
MEASUREMENT**



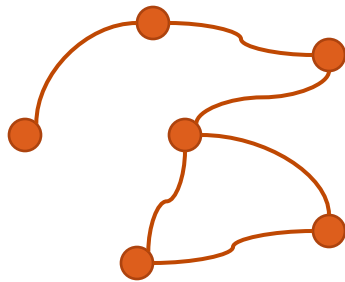
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GOAL: estimate eigenvector of ground-truth graph.

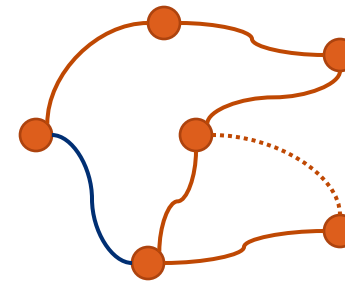
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**GROUND-TRUTH
GRAPH**



INPUT GRAPH

GOAL: estimate eigenvector of ground-truth graph.

OBSERVATION: eigenvector of input graph can have **very large variance**, as it can be **very sensitive to noise**

RANDOM-WALK VECTORS provide better, **more stable estimates**.

This Talk

QUESTION:

Why random-walk vectors in the design of fast algorithms?

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GOALS OF THIS TALK:

- Show **optimization perspective** on why random walks arise
- Application to nearly-linear-time **balanced graph partitioning**

Random Walks as Regularized Eigenvectors

What is Regularization?

Regularization is a fundamental technique in **optimization**

OPTIMIZATION
PROBLEM



WELL-BEHAVED
OPTIMIZATION
PROBLEM

- Stable optimum
- Unique optimal solution
- Smoothness conditions

...

What is Regularization?

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WELL-BEHAVED
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$$\min_{x \in H} L(x)$$

$$\min_{x \in H} L(x) + \lambda \cdot F(x)$$

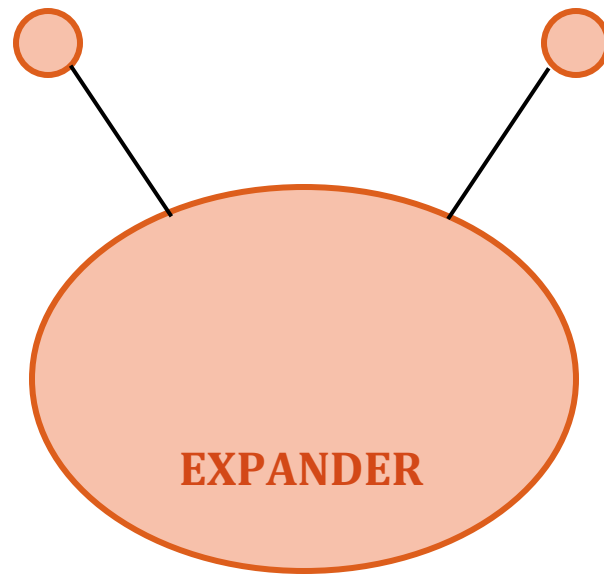
Parameter $\lambda > 0$

Regularizer F

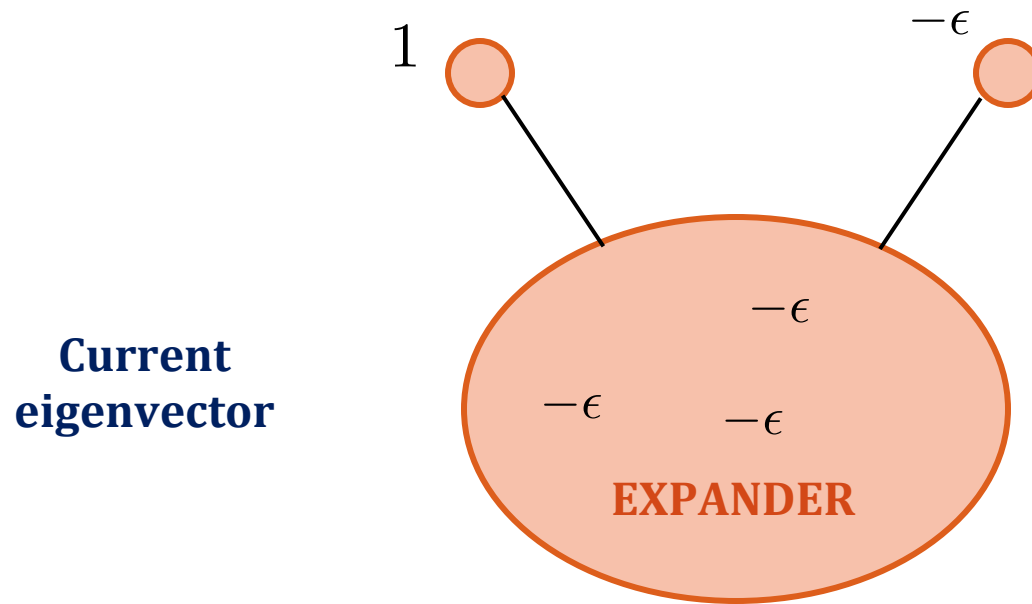
Benefits of Regularization in Learning and Statistics:

- Increases stability
- Decreases sensitivity to random noise
- Prevents overfitting

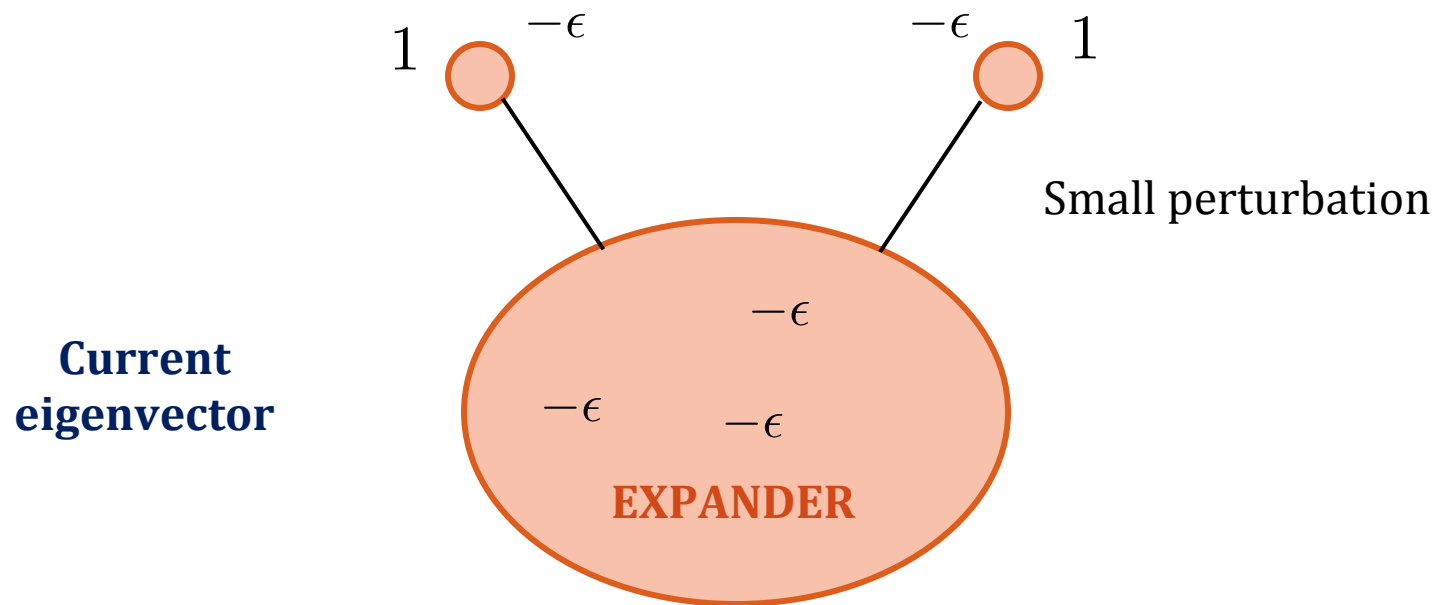
Instability of Eigenvector



Instability of Eigenvector



Instability of Eigenvector



Eigenvector Changes Completely!

The Laplacian Eigenvalue Problem

Quadratic Formulation

$$\frac{1}{d} \min x^T L x$$

$$\text{s.t. } \|x\|_2 = 1$$

$$x^T \mathbf{1} = 0$$

For simplicity, take G to be d -regular.

The Laplacian Eigenvalue Problem

Quadratic Formulation

$$\begin{aligned} & \frac{1}{d} \min x^T L x \\ & \text{s.t. } \|x\|_2 = 1 \\ & \quad x^T \mathbf{1} = 0 \end{aligned}$$



SDP Formulation

$$\begin{aligned} & \frac{1}{d} \min L \bullet X \\ & \text{s.t. } I \bullet X = 1 \\ & \quad \mathbf{1}\mathbf{1}^T \bullet X = 0 \\ & \quad X \succeq 0 \end{aligned}$$

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Programs have **same optimum**. Take optimal solution

$$X^* = x^* (x^*)^T$$

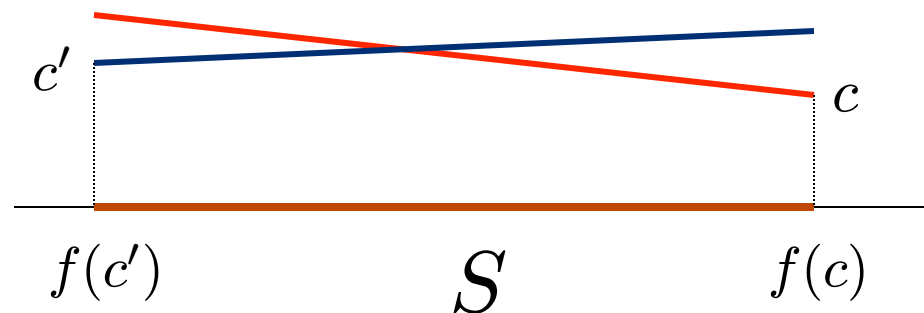
Instability of Linear Optimization

Consider a convex set $S \subset \mathbb{R}^n$ and a linear optimization problem:

$$f(c) = \arg \min_{x \in S} c^T x$$

The optimal solution $f(c)$ may be very unstable under perturbation of c :

$$\|c' - c\| \leq \delta \quad \text{and} \quad \|f(c') - f(c)\| \gg \delta$$



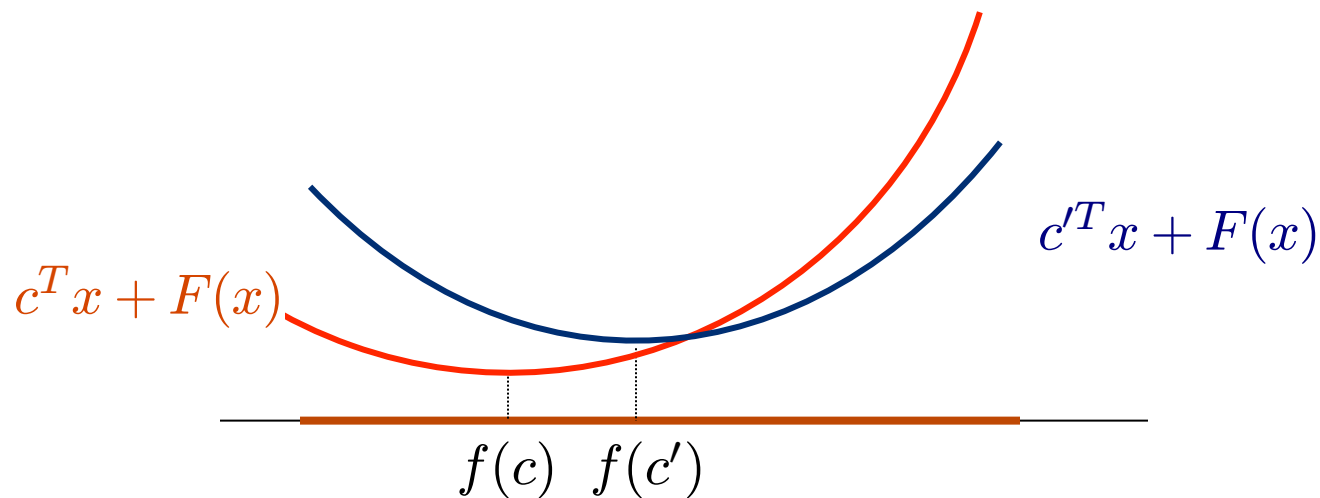
Regularization Helps Stability

Consider a convex $S \subset \mathbb{R}^n$ and a **regularized** linear optimization problem

$$f(c) = \arg \min_{x \in S} c^T x + F(x)$$

where F is σ -strongly convex.

Then: $\|c' - c\| \leq \delta$ implies $\|f(c) - f(c')\| \leq \frac{\delta}{\sigma}$



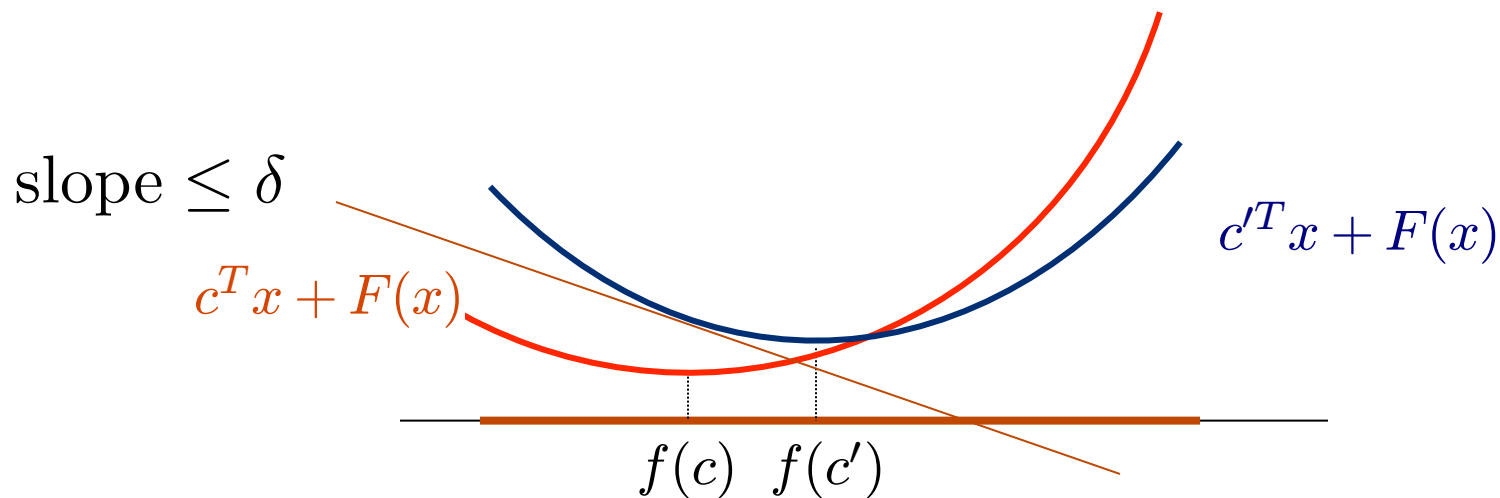
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Regularized Spectral Optimization

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$$\begin{aligned} & \frac{1}{d} \min \quad L \bullet X \\ \text{s.t.} \quad & I \bullet X = 1 \\ & \mathbf{1}\mathbf{1}^T \bullet X = 0 \\ & X \succeq 0 \end{aligned} \quad \left. \vphantom{\begin{aligned} & \frac{1}{d} \min \\ \text{s.t.} \end{aligned}} \right\} \text{Density Matrix}$$

Eigenvector decomposition of X :

$$X = \sum p_i v_i v_i^T \quad \left\{ \begin{array}{l} \forall i, p_i \geq 0, \\ \sum p_i = 1, \\ \forall i, v_i^T \mathbf{1} = 0. \end{array} \right.$$

Eigenvalues of X define **probability distribution**

Regularized Spectral Optimization

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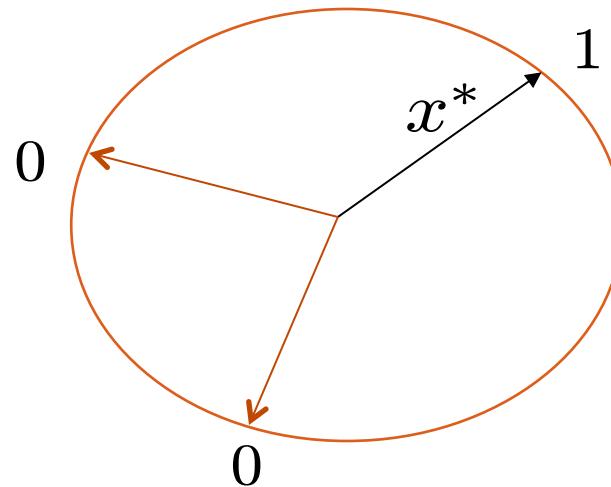
$$\frac{1}{d} \min L \bullet X$$

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Eigenvalues of X define **probability distribution**

$$X^* = x^* (x^*)^T$$

TRIVIAL DISTRIBUTION



Regularized Spectral Optimization

$$\frac{1}{d} \min \quad L \bullet X + \boxed{\eta \cdot F(X)} \quad \begin{array}{l} \text{Regularizer } F \\ \text{Parameter } \eta \end{array}$$

$$\text{s.t.} \quad I \bullet X = 1$$

$$11^T \bullet X = 0$$

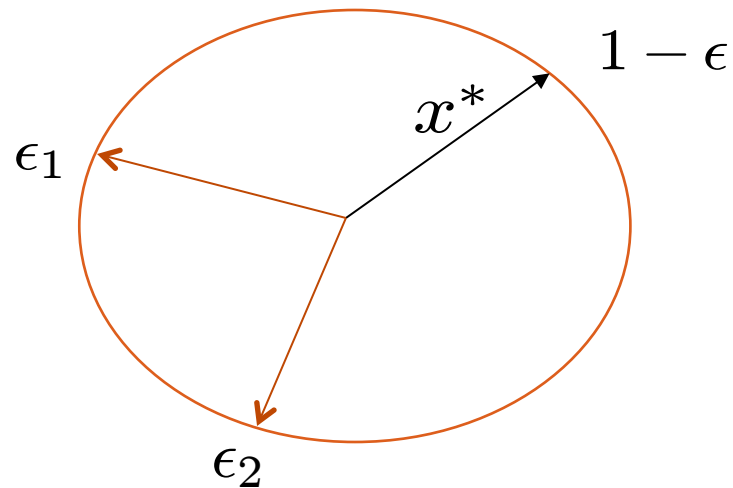
$$X \succeq 0$$

The regularizer F forces the distribution of eigenvalues of X to be **non-trivial**

$$X^* = x^*(x^*)^T$$

REGULARIZATION

$$X^* = \sum p_i v_i v_i^T$$



Regularizers

Regularizers are **SDP-versions** of common regularizers

- von Neumann Entropy

$$F_H(X) = \text{Tr}(X \log X) = \sum p_i \log p_i$$

- p-Norm, $p > 1$

$$F_p(X) = \frac{1}{p} \|X\|_p^p = \frac{1}{p} \text{Tr}(X^p) = \frac{1}{p} \sum p_i^p$$

- And more, e.g. log-determinant.

Our Main Result

Regularized SDP

$$\frac{1}{d} \min L \bullet X + \eta \cdot F(X)$$

$$\text{s.t.} \quad I \bullet X = 1$$

$$J \bullet X = 0$$

$$X \succeq 0$$

RESULT:

Explicit correspondence between regularizers and random walks

REGULARIZER

OPTIMAL SOLUTION OF REGULARIZED PROGRAM

$$F = F_H \xrightarrow{\text{Entropy}} X^* \propto H_G^t \quad \text{where } t \text{ depends on } \eta$$

$$F = F_p \xrightarrow{p\text{-Norm}} X^* \propto (qI + (1 - q)W)^{\frac{1}{p-1}} \quad \text{where } q \text{ depends on } \eta$$

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$$\begin{aligned}
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HEAT-KERNEL

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LAZY RANDOM WALK where q depends on η

Background: Heat-Kernel Random Walk

For simplicity, take G to be **d-regular**.

- The Heat-Kernel Random Walk is a **Continuous-Time Markov Chain** over V , modeling the **diffusion of heat** along the edges of G .

- Transitions take place in **continuous time** t , with an **exponential distribution**.

$$\frac{\partial p(t)}{\partial t} = -L \frac{p(t)}{d}$$

$$p(t) = e^{-\frac{t}{d}L} p(0)$$

- The Heat Kernel can be interpreted as **Poisson distribution** over number of steps of the natural random walk $W=AD^{-1}$:

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Notation

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Heat Kernel Walk: Stability Analysis

Consider a convex set $S \subset \mathbb{R}^n$ and a **regularized** linear optimization problem

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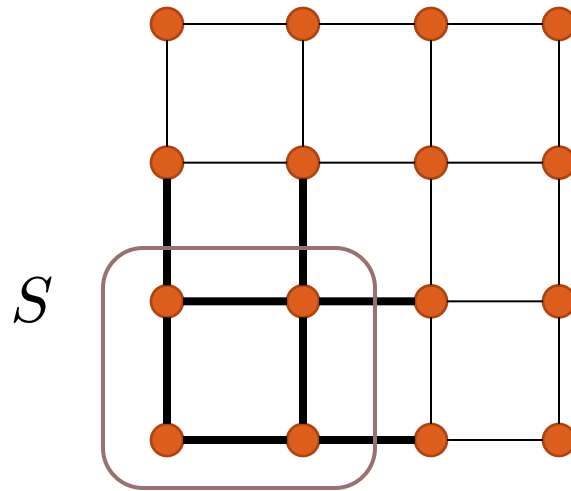
Analogous statement for Heat Kernel:

$$\|G' - G\|_{\infty} \leq \delta \quad \text{implies} \quad \left\| \frac{H_{G'}^{\tau}}{I \bullet H_{G'}^{\tau}} - \frac{H_G^{\tau}}{I \bullet H_G^{\tau}} \right\|_1 \leq \tau \cdot \delta$$

Applications to Graph Partitioning: Nearly-Linear-Time Balanced Cut

Partitioning Graphs - Conductance

Undirected unweighted $G = (V, E)$, $|V| = n$, $|E| = m$



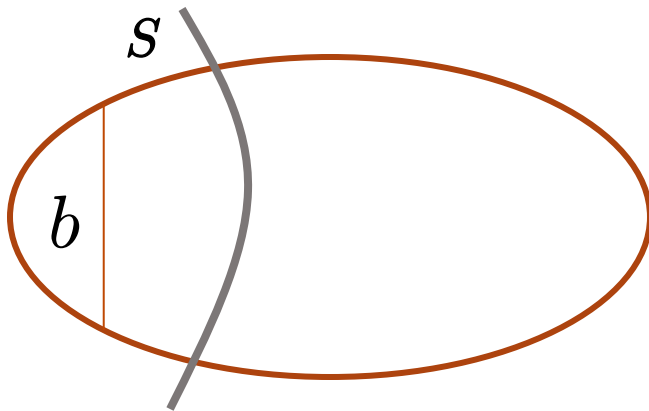
Conductance of $S \subseteq V$

$$\phi(S) = \frac{|E(S, \bar{S})|}{\min\{\text{vol}(S), \text{vol}(\bar{S})\}}$$

Partitioning Graphs – Balanced Cut

NP-HARD DECISION PROBLEM

Does G have a b -balanced cut of conductance $< \gamma$?



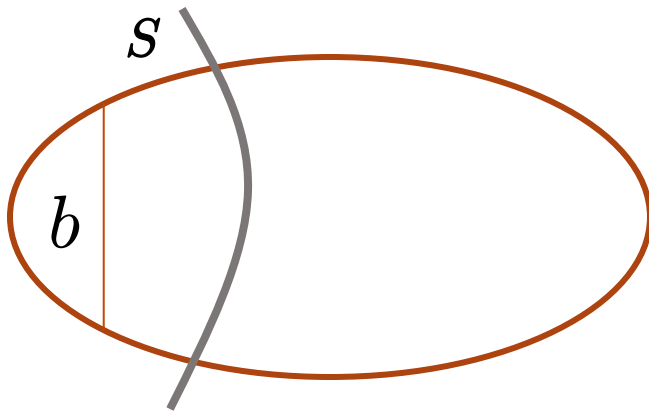
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$$\phi(S) < \gamma$$

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- Important primitive for many **recursive** algorithms.
- Applications to **clustering** and **graph decomposition**.

Spectral Approximation Algorithms

Does G have a b -balanced cut of conductance $< \gamma$?

Algorithm	Method	Distinguishes $\geq \gamma$ and	Running Time
Recursive Eigenvector	Spectral	$O(\sqrt{\gamma})$	$\tilde{O}(mn)$
[Spielman, Teng '04]	Local Random Walks	$O\left(\sqrt{\gamma \log^3 n}\right)$	$\tilde{O}\left(\frac{m}{\gamma^2}\right)$
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[Orecchia, Sachdeva, Vishnoi '12]	Random Walks	$O(\sqrt{\gamma})$	$\tilde{O}(m)$

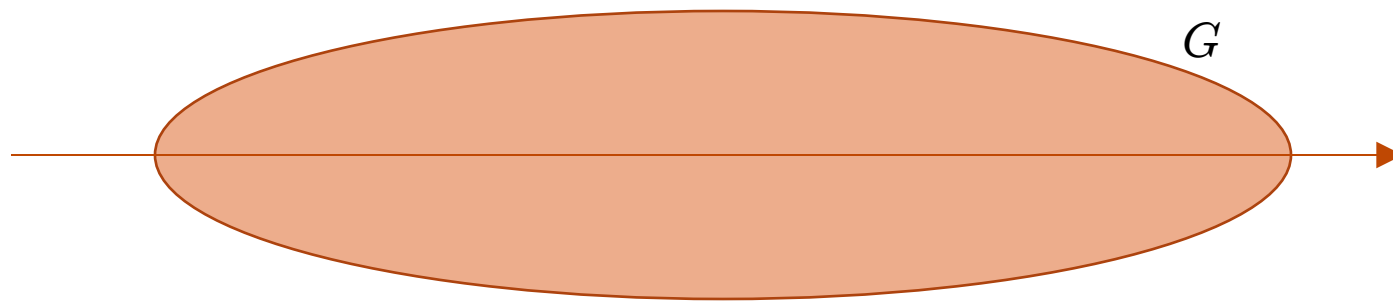
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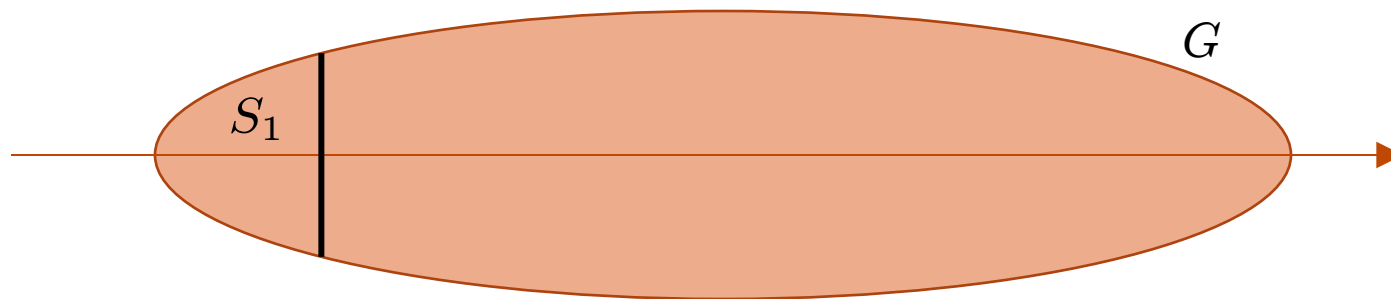


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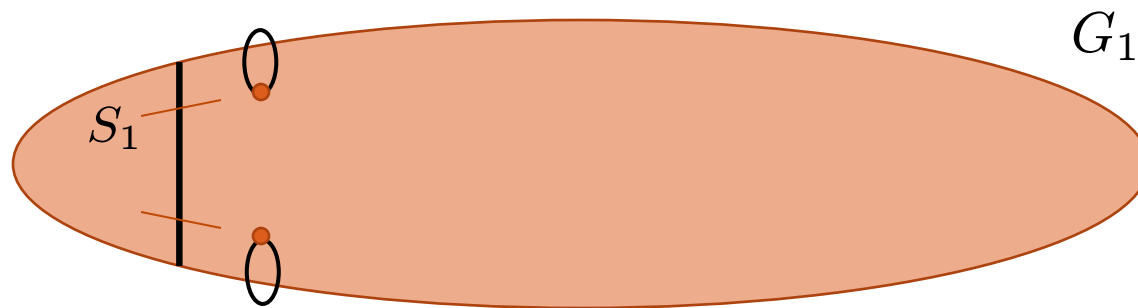
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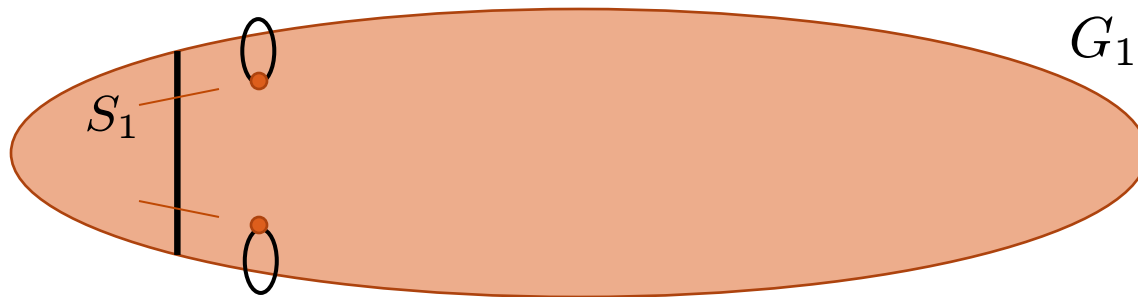
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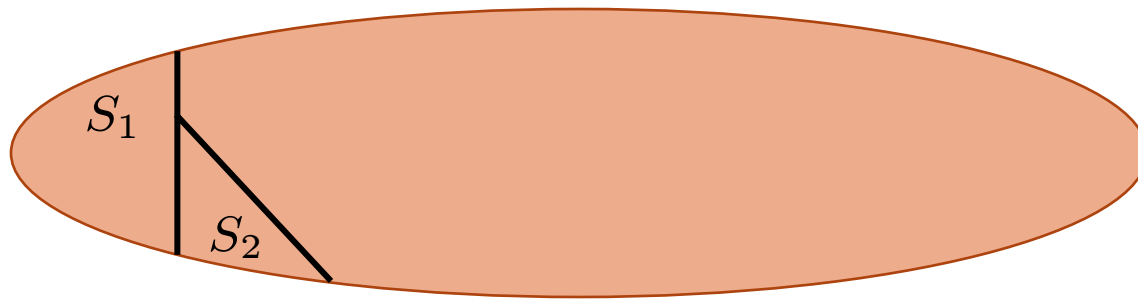
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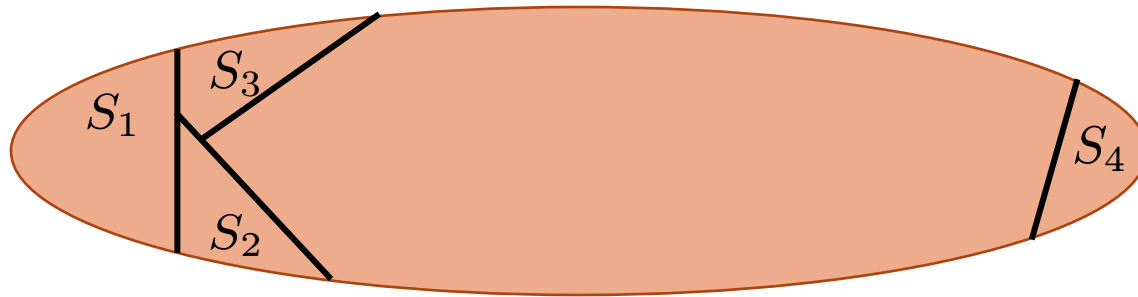
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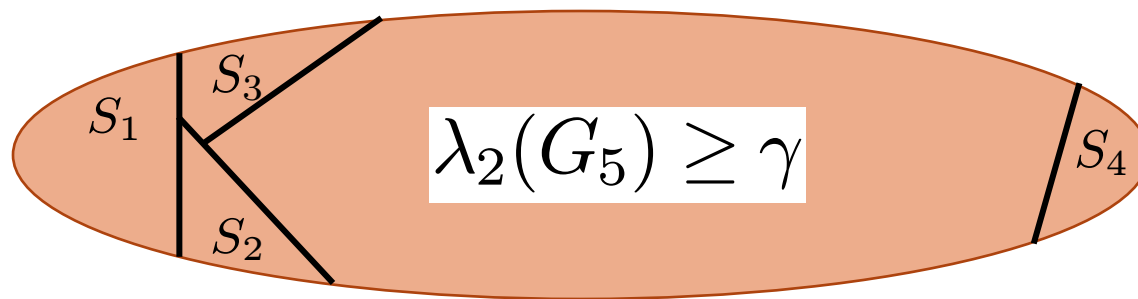
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LARGE INDUCED EXPANDER = **NO-CERTIFICATE**

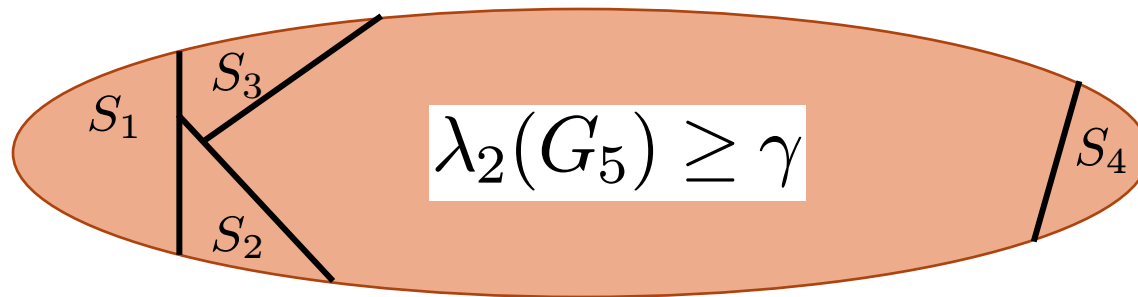
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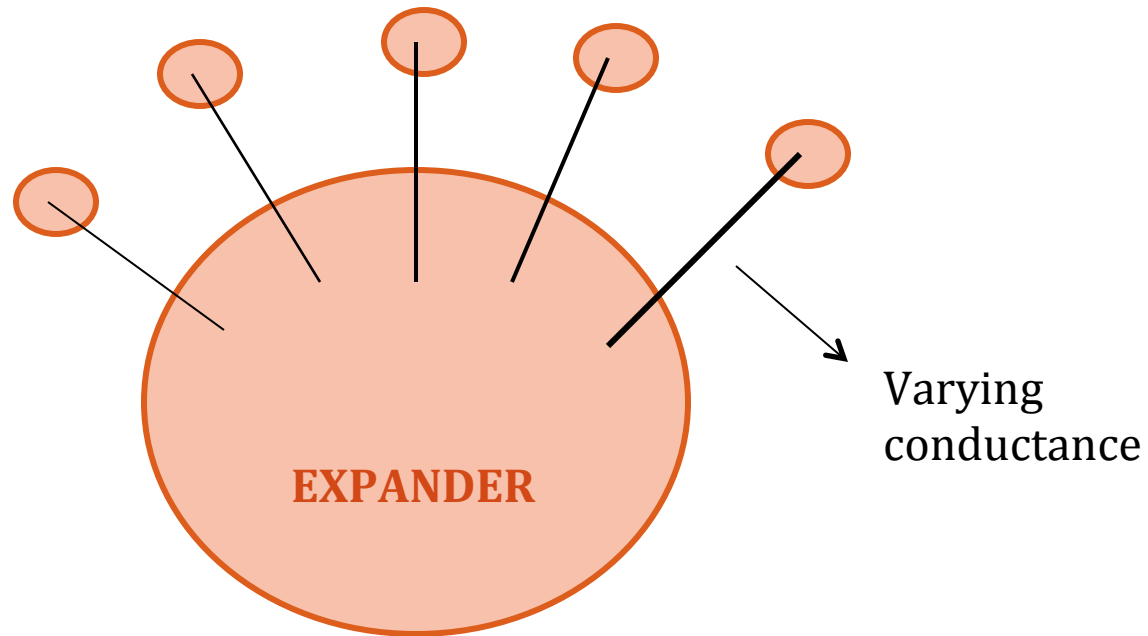
$$\phi(S_1) \leq O(\sqrt{\gamma})$$

- If S_1 is $(b/2)$ -balanced. **Output S_1** . Otherwise, consider the graph G_1 induced by G on $V - S_1$ with self-loops replacing the edges going to S_1 .
- Recurse on G_1 .



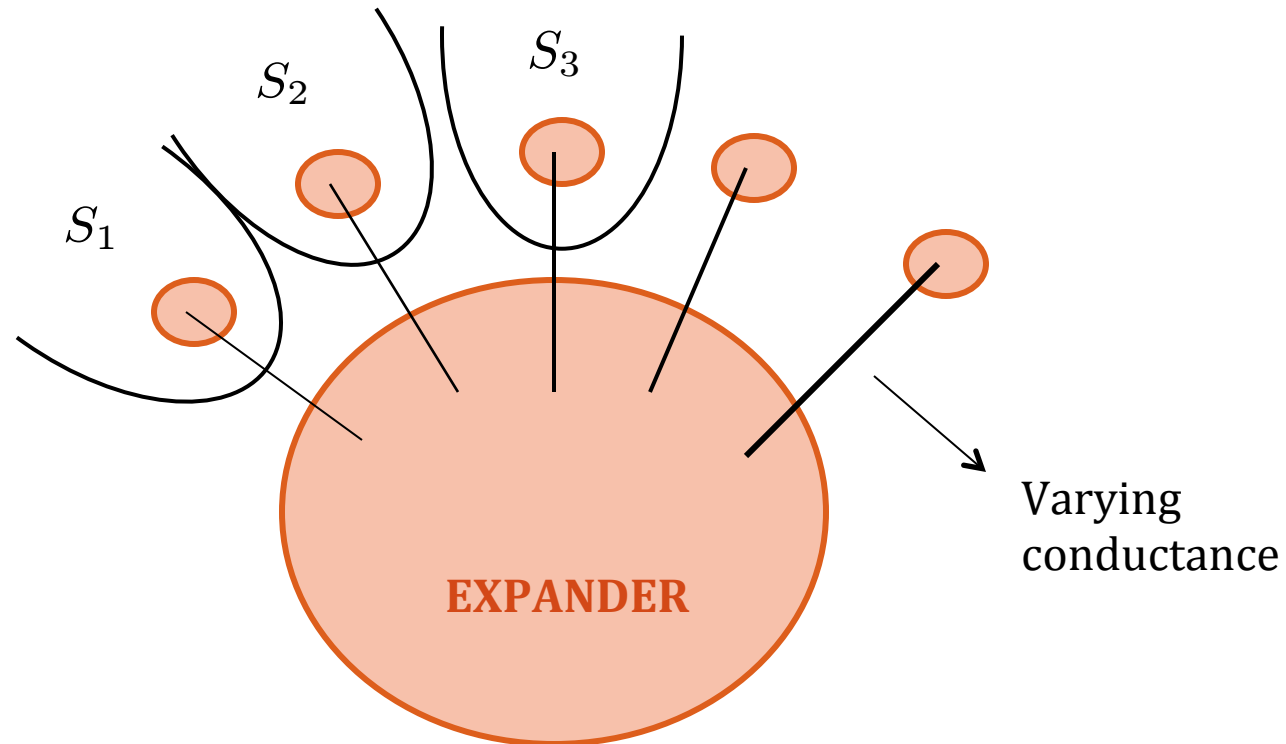
RUNNING TIME: $\tilde{O}(m)$ per iteration, $O(n)$ iterations. Total: $\tilde{O}(mn)$

Recursive Eigenvector: The Worst Case



$\Omega(n)$ nearly-disconnected components

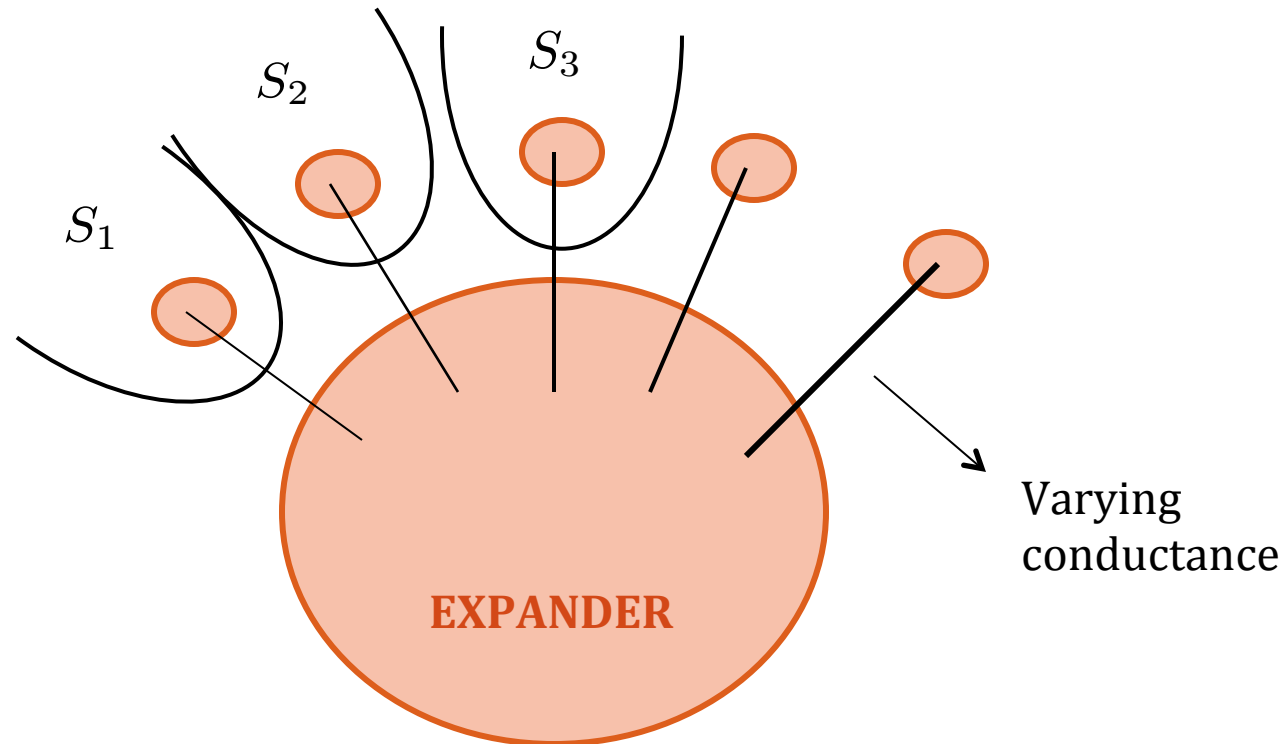
Recursive Eigenvector: The Worst Case



NB: Recursive Eigenvector **eliminates one component per iteration.**

$\Omega(n)$ iterations are necessary. Each iteration requires $\Omega(m)$ time.

Recursive Eigenvector: The Worst Case

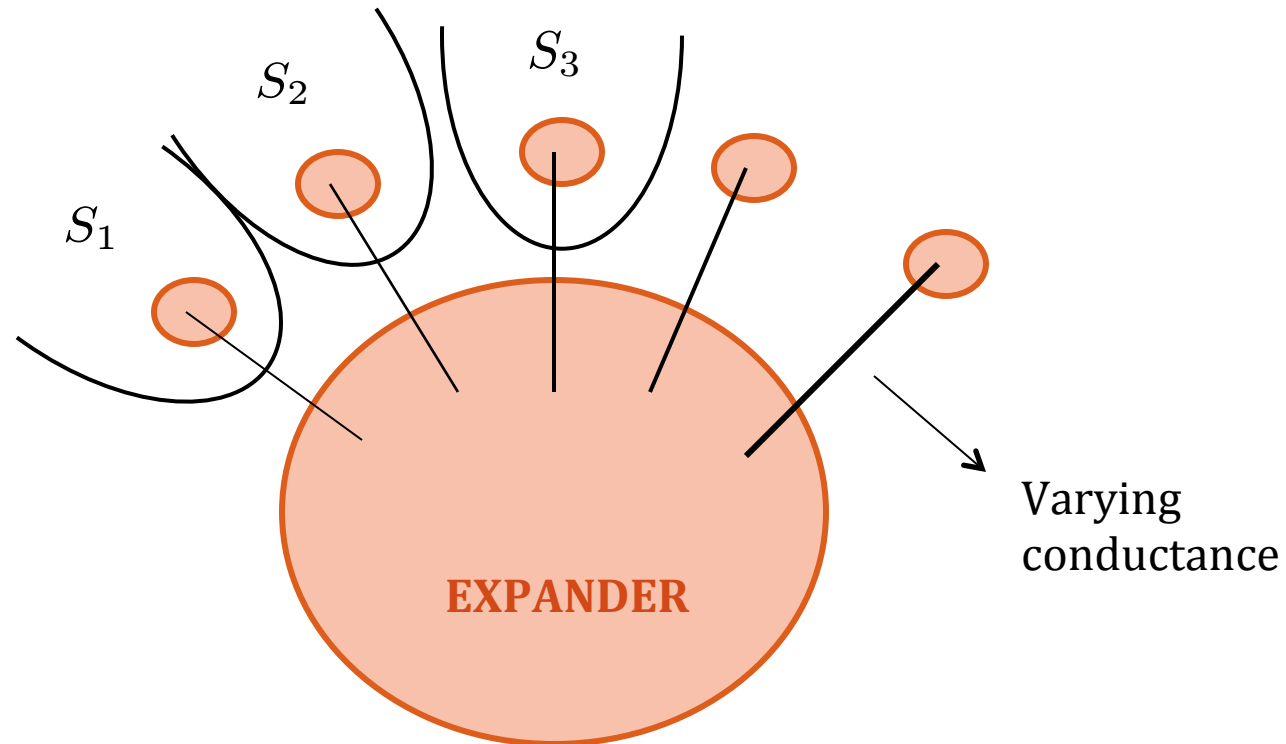


NB: Recursive Eigenvector **eliminates one component per iteration.**

$\Omega(n)$ iterations are necessary. Each iteration requires $\Omega(mn)$ time.

GOAL: Eliminate unbalanced low-conductance cuts faster.

Recursive Eigenvector: The Worst Case



STABILITY VIEW:

- Ideally, we would like to enforce progress: $\lambda_2(G_{t+1}) \gg \lambda_2(G_t)$
- **Eigenvector** may change completely at every iteration. Impossible to enforce any non-trivial relation between $\lambda_2(G_{t+1})$ and $\lambda_2(G_t)$

Our Algorithm: Contributions

Algorithm	Method	Distinguishes $\geq \gamma$ and	Time
Recursive Eigenvector	Eigenvector	$O(\sqrt{\gamma})$	$\tilde{O}(mn)$
OUR ALGORITHM	Random Walks	$O(\sqrt{\gamma})$	$\tilde{O}(m)$

MAIN FEATURES:

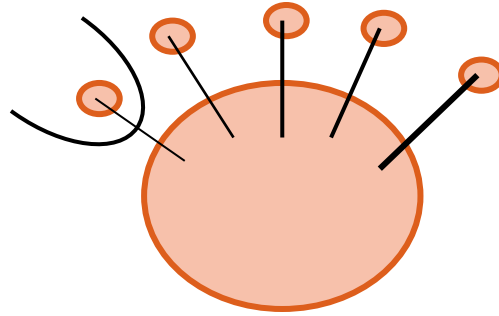
- Compute $O(\log n)$ global heat-kernel random-walk vectors at each iteration
- Unbalanced cuts are removed in $O(\log n)$ iterations
- Method to compute heat-kernel vectors in nearly-linear time

TECHNICAL COMPONENTS:

- 1) New iterative algorithm with a simple random walk interpretation
- 2) Novel analysis of Lanczos methods for computing heat-kernel vectors

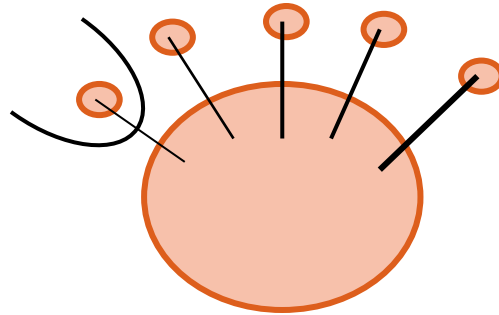
Eliminating Unbalanced Cuts

- The **graph eigenvector** may be correlated with **only one** sparse unbalanced cut.

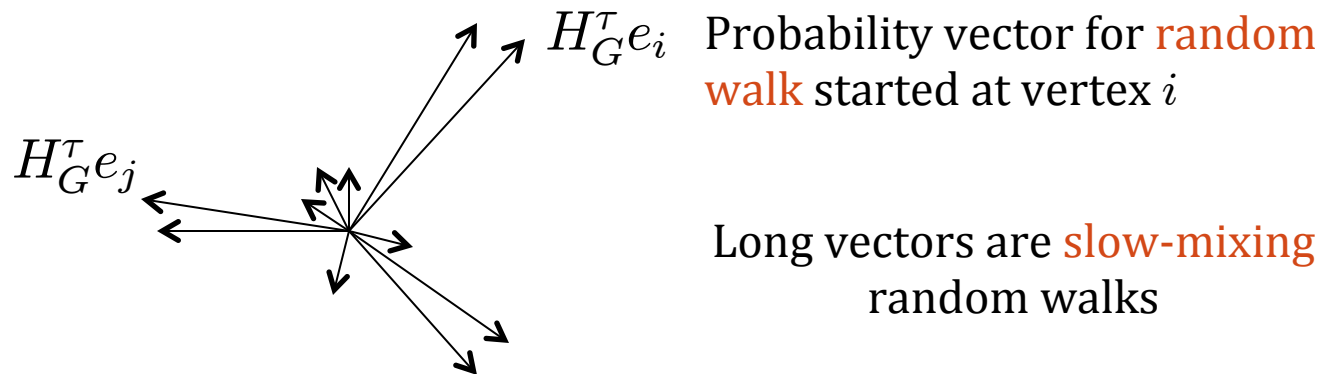


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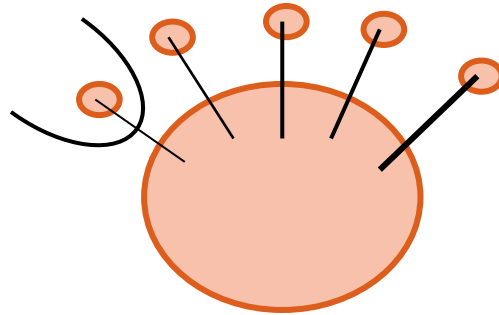


- Consider the Heat-Kernel random walk-matrix H_G^τ for $\tau = \log n / \gamma$.

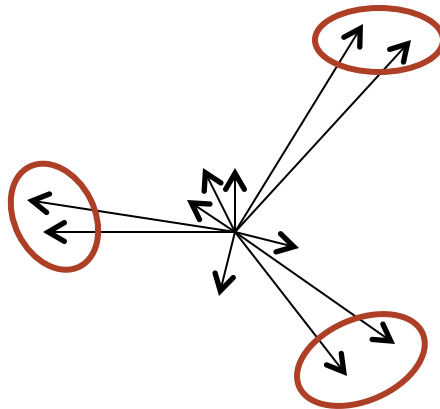


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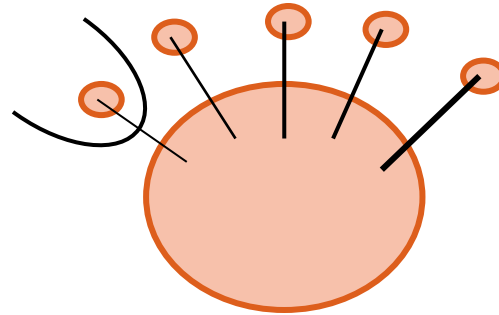


Unbalanced cuts of
conductance $< \sqrt{\gamma}$

Eliminating Unbalanced Cuts

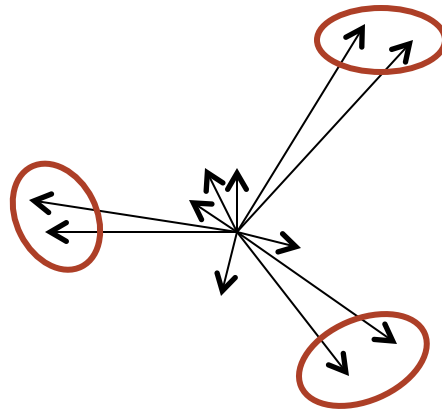
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**SINGLE VECTOR
SINGLE CUT**



- Consider the Heat-Kernel random walk-matrix H_G^τ for $\tau = \log n / \gamma$.

**VECTOR
EMBEDDING
MULTIPLE CUTS**

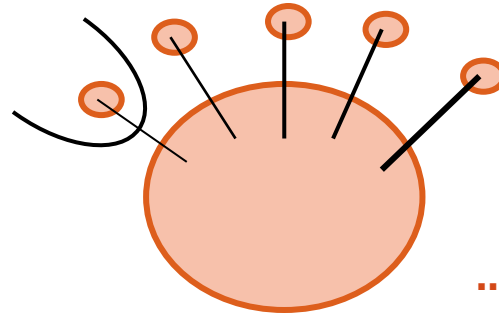


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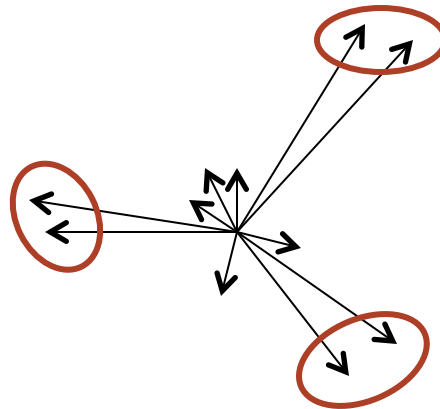


AFTER CUT REMOVAL ...

... eigenvector can change completely

- Consider the Heat-Kernel random walk-matrix H_G^τ for $\tau = \log n / \gamma$.

**VECTOR
EMBEDDING
MULTIPLE CUTS**



... vectors do not change a lot

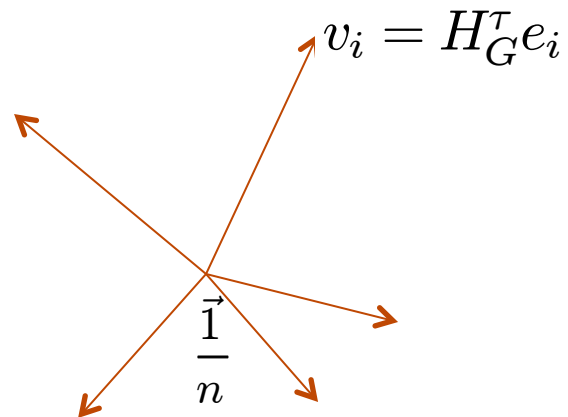
Our Algorithm for Balanced Cut

IDEA BEHIND OUR ALGORITHM:

Replace eigenvector in recursive eigenvector algorithm with

Heat-Kernel random walk H_G^τ for $\tau = \log n/\gamma$

Consider the embedding $\{v_i\}$ given by H_G^τ :



Our Algorithm for Balanced Cut

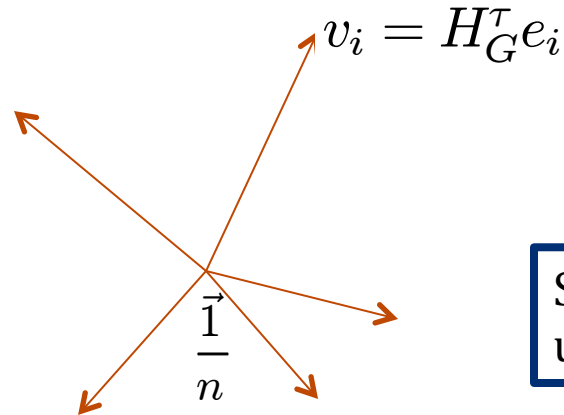
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Stationary distribution is
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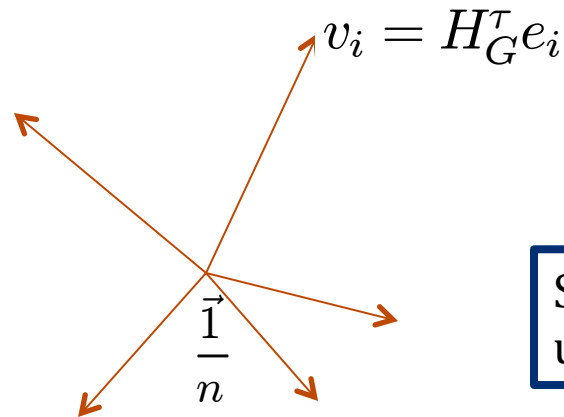
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Stationary distribution is uniform as G is regular

MIXING:

Define the total deviation from stationary for a set $S \subseteq V$ for walk

$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|v_i - \vec{1}/n\|^2$$

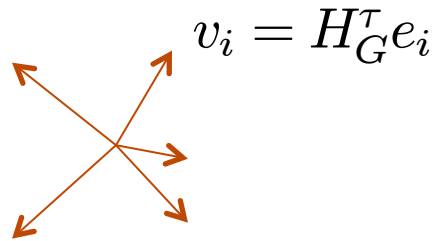
FUNDAMENTAL QUANTITY TO UNDERSTAND CUTS IN G

Our Algorithm: Case Analysis

Recall:

$$\tau = \log n / \gamma \quad \Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$

CASE 1: Random walks have **mixed**



ALL VECTORS ARE SHORT

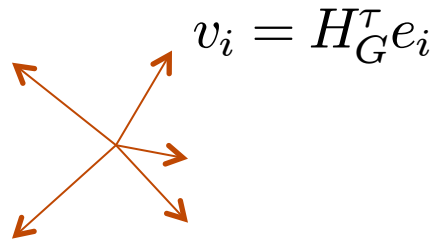
$$\Psi(H_G^\tau, V) \leq \frac{1}{\text{poly}(n)}$$

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$$\tau = \log n / \gamma \quad \Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$

CASE 1: Random walks have **mixed**



ALL VECTORS ARE SHORT

$$\Psi(H_G^\tau, V) \leq \frac{1}{\text{poly}(n)}$$



By definition of τ

$$\lambda_2 \geq \Omega(\gamma)$$

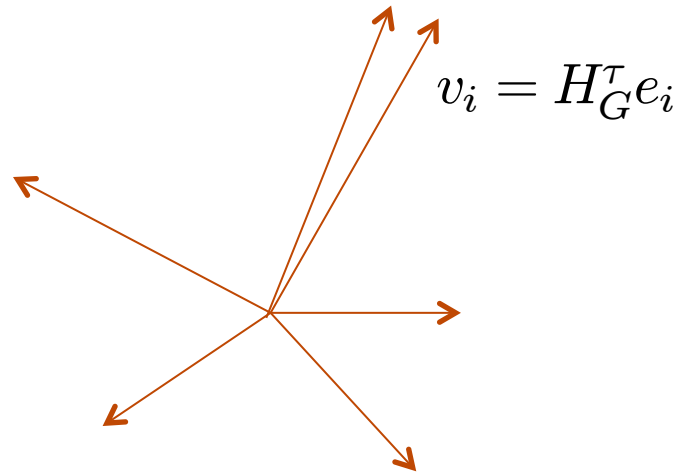


$$\phi_G \geq \Omega(\gamma)$$

Our Algorithm

$$\tau = \log n / \gamma$$

$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$



CASE 2: Random walks have **not mixed**

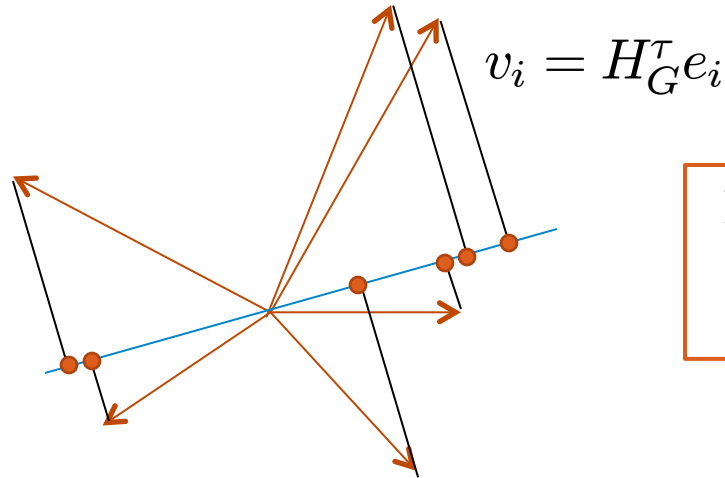
$$\Psi(H_G^\tau, V) > \frac{1}{\text{poly}(n)}$$

We can either find an $\Omega(b)$ -**balanced cut** with conductance $O(\sqrt{\gamma})$

Our Algorithm

$$\tau = \log n / \gamma$$

$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$



RANDOM PROJECTION
+
SWEEP CUT

CASE 2: Random walks have **not mixed**

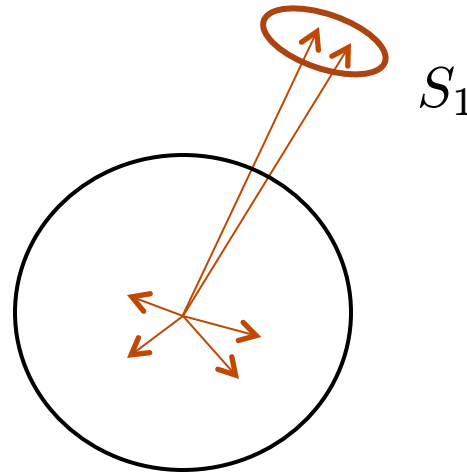
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BALL
ROUNDING

CASE 2: Random walks have **not mixed**

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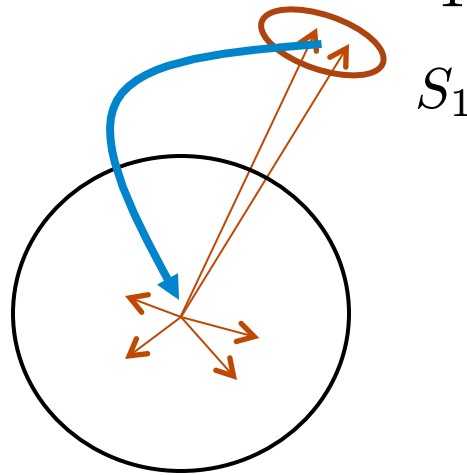
OR a ball cut yields S_1 such that $\phi(S_1) \leq O(\sqrt{\gamma})$ and

$$\Psi(H_G^\tau, S_1) \geq \frac{1}{2} \Psi(H_G^\tau, V).$$

Our Algorithm: Iteration

$$\tau = \log n / \gamma$$

$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \bar{\mathbf{1}}/n\|^2$$



CASE 2: We found an **unbalanced cut** S_1 with $\phi(S_1) \leq O(\sqrt{\gamma})$ and

$$\Psi(H_G^\tau, S_1) \geq \frac{1}{2} \Psi(H_G^\tau, V).$$

Modify $G = G^{(1)}$ by **adding edges** across (S_1, \bar{S}_1) to construct $G^{(2)}$.

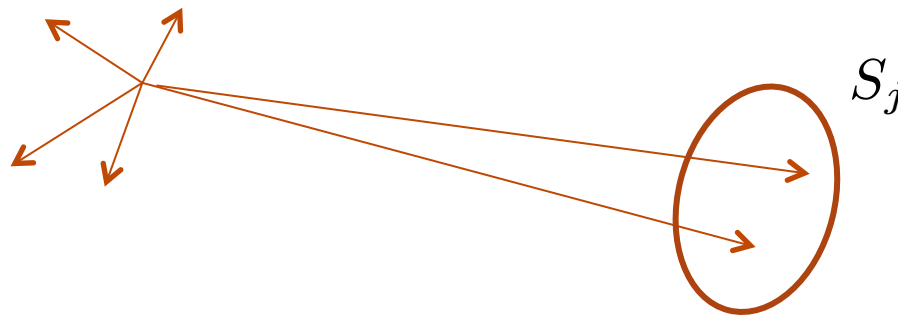
Analogous to **removing unbalanced cut** S_1
in Recursive Eigenvector algorithm

Our Algorithm: Modifying G

CASE 2: We found an **unbalanced cut** S_1 with $\phi(S_1) \leq O(\sqrt{\gamma})$ and

$$\Psi(H_G^T, S_1) \geq \frac{1}{2}\Psi(H_G^T, V).$$

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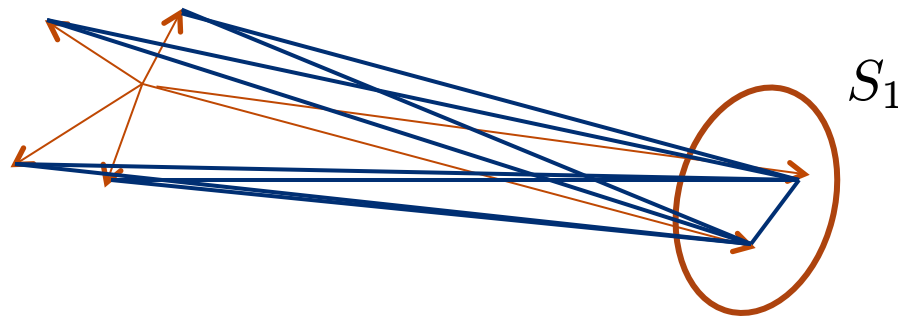


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Modify $G = G^{(1)}$ by **adding edges** across (S_1, \bar{S}_1) to construct $G^{(2)}$.



$$G^{(t+1)} = G^{(t)} + \gamma \sum_{i \in S_t} \text{Star}_i$$

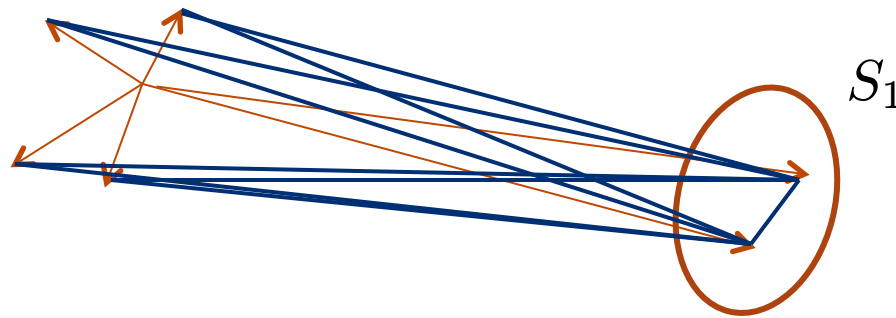
where Star_i is the **star graph** rooted at vertex i .

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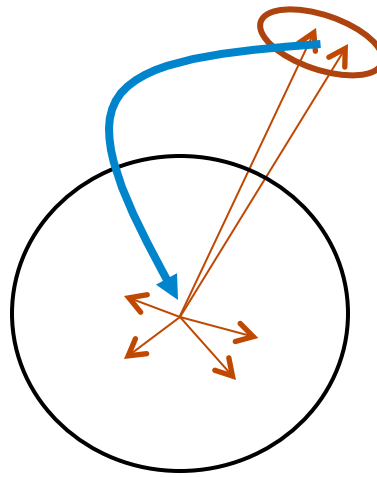
$$G^{(t+1)} = G^{(t)} + \gamma \sum_{i \in S_t} \text{Star}_i$$

where Star_i is the **star graph** rooted at vertex i .

The random walk can now **escape** S_1 more easily.

Our Algorithm: Iteration

$$\tau = \log n / \gamma$$



$$\Psi(H_G^\tau, S) = \sum_{i \in S} \|H_G^\tau e_i - \vec{1}/n\|^2$$

CASE 2: We found an **unbalanced cut** S_1 with $\phi(S_1) \leq O(\sqrt{\gamma})$ and

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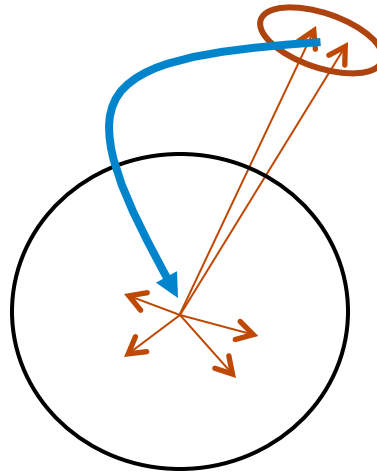
Modify $G = G^{(1)}$ by **adding edges** across (S_1, \bar{S}_1) to construct $G^{(2)}$.

POTENTIAL REDUCTION:

$$\Psi(H_{G^{(t+1)}}^\tau, V) \leq \Psi(H_{G^{(t)}}^\tau, V) - \frac{1}{2} \Psi(H_{G^{(t)}}^\tau, S_t) \leq \frac{3}{4} \Psi(H_{G^{(t)}}^\tau, V)$$

Our Algorithm: Iteration

$$\tau = \log n / \gamma$$



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CRUCIAL APPLICATION OF STABILITY OF RANDOM WALK

Summary and Potential Analysis

IN SUMMARY:

At every step t of the recursion, we either

1. Produce a $\Omega(b)$ -balanced cut of the required conductance, OR

Potential Reduction

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At every step t of the recursion, we either

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$$\Psi(H_{G^{(t)}}^T, V) \leq \frac{1}{\text{poly}(n)}, \text{ OR}$$

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3. Find an **unbalanced cut** S_t of the required conductance, such that for the graph $G^{(t+1)}$, modified to have **increased edges** from S_t ,

$$\Psi(H_{G^{(t+1)}}^\tau, V) \leq \frac{3}{4} \Psi(H_{G^{(t)}}^\tau, V)$$

Potential Reduction

IN SUMMARY:

At every step $t-1$ of the recursion, we either

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2. Find that

$$\Psi(H_{G^{(t)}}^\tau, V) \leq \frac{1}{\text{poly}(n)}, \text{ OR}$$

3. Find an **unbalanced cut** S_t of the required conductance, such that for the process $P^{(t+1)}$, modified to have **increased transitions** from S_t ,

$$\Psi(H_{G^{(t+1)}}^\tau, V) \leq \frac{3}{4} \Psi(H_{G^{(t)}}^\tau, V)$$

After $T=O(\log n)$ iterations, if no balanced cut is found:

$$\Psi(H_{G^{(T)}}^\tau, V) \leq \frac{1}{\text{poly}(n)}$$

From this guarantee, using the definition of $G^{(T)}$, we derive an **SDP-certificate** that no **b-balanced cut** of conductance $O(\gamma)$ exists in G .

NB: Only $O(\log n)$ iterations to remove unbalanced cuts.

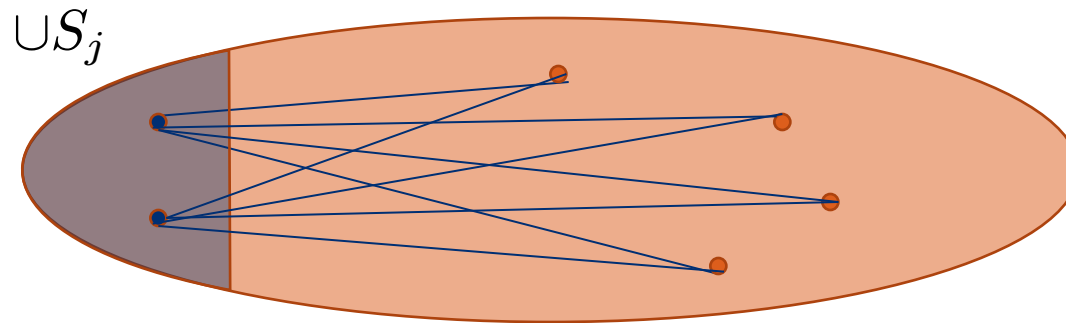
Heat-Kernel and Certificates

- If no balanced cut of conductance is found, our potential analysis yields:

$$\Psi(H_{G^{(T)}}^T, V) \leq \frac{1}{\text{poly}(n)} \longrightarrow L + \gamma \sum_{j=1}^{T-1} \sum_{i \in S_j} L(\text{Star}_i) \succeq \gamma L(K_V)$$

Modified graph has $\lambda_2 \geq \gamma$

CLAIM: This is a certificate that no balanced cut of conductance $< \gamma$ existed in G .



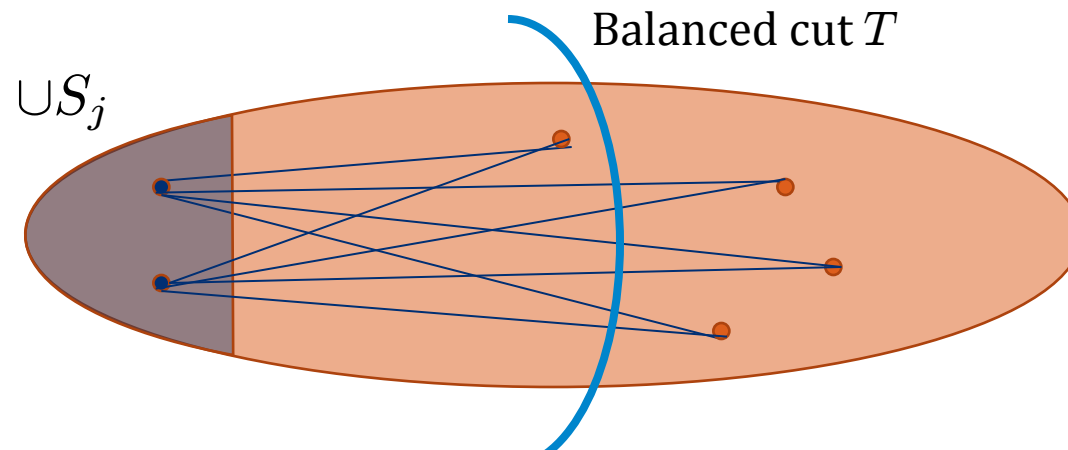
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$$\phi(T) \geq \gamma - \gamma \frac{|U S_j|}{|T|}$$

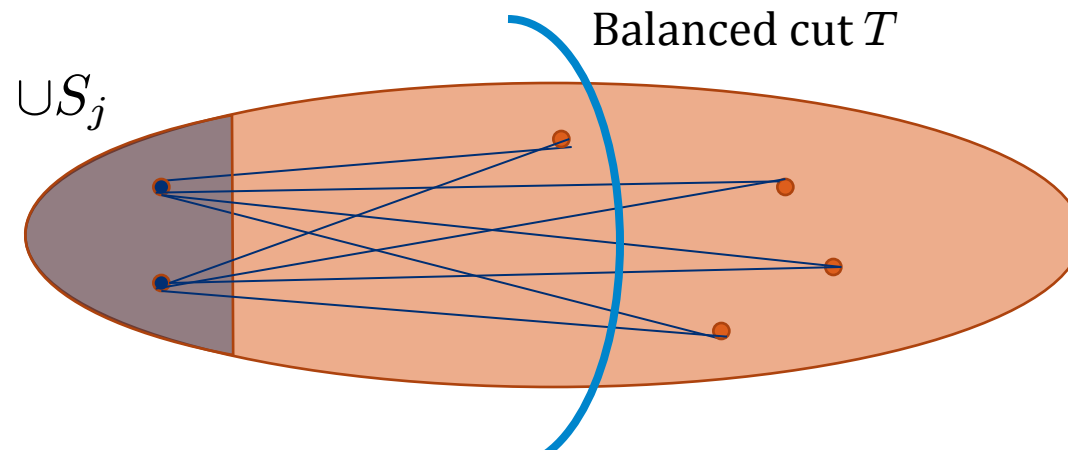
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Modified graph has $\lambda_2 \geq \gamma$

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$$\phi(T) \geq \gamma - \gamma \frac{|US_j|}{|T|} \geq \gamma - \gamma \frac{b/2}{b} \geq \gamma/2$$

Comparison with Recursive Eigenvector

RECURSIVE EIGENVECTOR:

We can **only bound** number of iterations by **volume** of graph removed.
 $\Omega(n)$ iterations possible.

OUR ALGORITHM:

Use **variance of random walk** as potential.
Only $O(\log n)$ iterations necessary.

$$\Psi(P, V) = \sum_{i \in V} \underbrace{\|Pe_i - \vec{1}/n\|^2}_{\text{STABLE SPECTRAL NOTION OF POTENTIAL}}$$

STABLE SPECTRAL NOTION OF POTENTIAL

Running Time

- Our Algorithm runs in $O(\log n)$ iterations.
- In one iteration, we perform some **simple computation** (projection, sweep cut) on the vector embedding $H_{G^{(t)}}^\tau$. This takes time $\tilde{O}(md)$, where d is the **dimension of the embedding**.
- Can use **Johnson-Lindenstrauss** to obtain $d = O(\log n)$.
- Hence, we only need to compute $O(\log^2 n)$ **matrix-vector products**

$$H_{G^{(t)}}^\tau u$$

- We show how to perform one such product in time $\tilde{O}(m)$ for all τ .
- **OBSTACLE:**
 τ , the mean number of steps in the Heat-Kernel random walk, is $\Omega(n^2)$ for path.

Conclusion

NOVEL ALGORITHMIC CONTRIBUTIONS

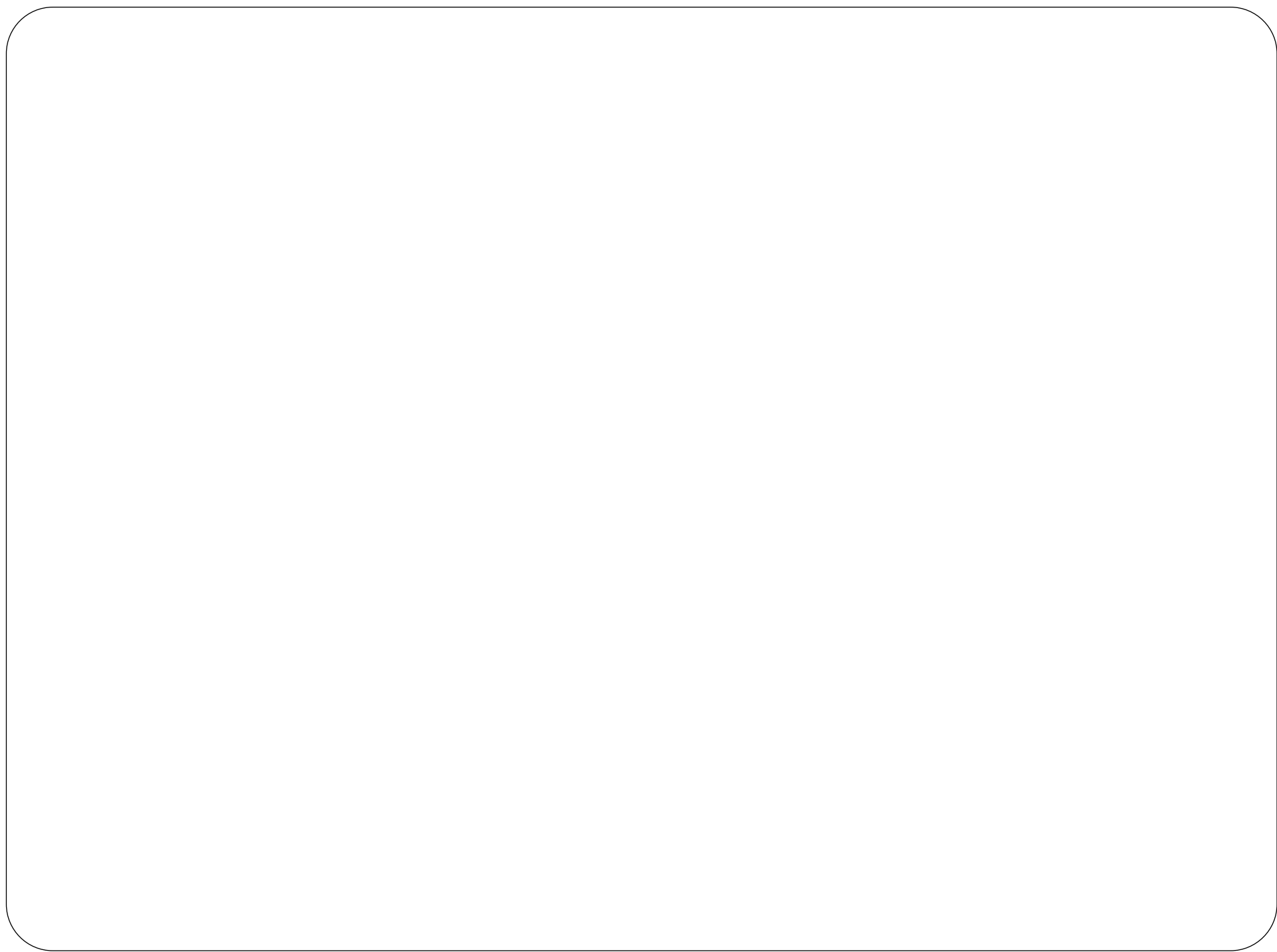
- Balanced-Cut Algorithm using Random Walks in time $\tilde{O}(m)$

MAIN IDEA

Random walks provide a very useful
stable analogue of the graph eigenvector
via regularization

OPEN QUESTION

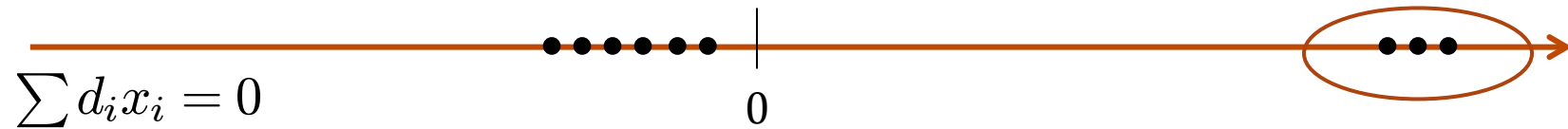
More applications of this idea?
Applications beyond design of fast algorithms?



A Different Interpretation

THEOREM:

Suppose eigenvector x yields an **unbalanced cut** S of low conductance and **no balanced cut** of the required conductance. S



Then,

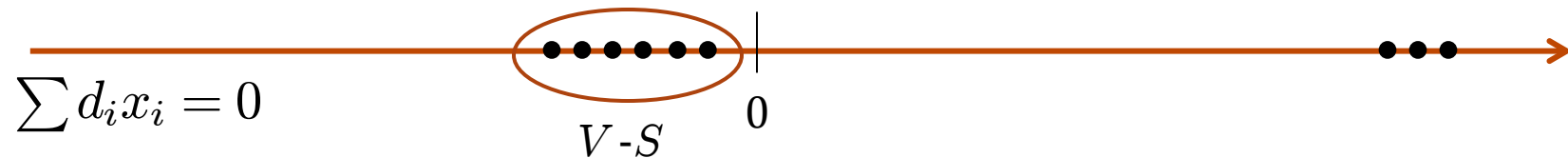
$$\sum_{i \in S} d_i x_i^2 \geq \frac{1}{2} \sum_{i \in V} d_i x_i^2.$$

In words, S contains **most of the variance** of the eigenvector.

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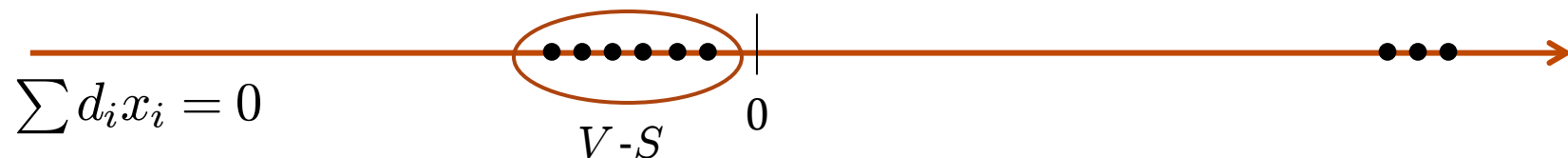
In words, S contains **most of the variance** of the eigenvector.

QUESTION: Does this mean the graph induced by G on $V-S$ is **much closer** to have conductance at least γ ?

A Different Interpretation

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QUESTION: Does this mean the graph induced by G on $V-S$ is **much closer** to have conductance at least γ ?

ANSWER: NO. x may contain little or no information about G on $V-S$.

Next eigenvector may be only **infinitesimally larger**.

CONCLUSION: To make significant progress, we need an analogue of the eigenvector that captures sparse

Theorems for Our Algorithm

THEOREM 1: (WALKS HAVE NOT MIXED)

$$\Psi(P^{(t)}, V) > \frac{1}{\text{poly}(n)} \longrightarrow \text{Can find cut of conductance } O(\sqrt{\gamma})$$

Theorems for Our Algorithm

THEOREM 1: (WALKS HAVE NOT MIXED)

$$\Psi(P^{(t)}, V) > \frac{1}{\text{poly}(n)} \longrightarrow \text{Can find cut of conductance } O(\sqrt{\gamma})$$

Proof: Recall that

$$P^{(t)} = e^{-\tau Q^{(t)}} \quad \tau = \log n / \gamma \quad \Psi(P, V) = \sum_{i \in V} \|Pe_i - \vec{1}/n\|^2$$

Use the definition of τ . The spectrum of $P^{(t)}$ implies that

$$\underbrace{\sum_{ij \in E} \|P^{(t)}e_i - P^{(t)}e_j\|^2}_{\text{EDGE LENGTH}} \cdot O(\gamma) \cdot \underbrace{\Psi(P^{(t)}, V)}_{\text{TOTAL VARIANCE}}$$

Theorems for Our Algorithm

THEOREM 1: (WALKS HAVE NOT MIXED)

$$\Psi(P^{(t)}, V) > \frac{1}{\text{poly}(n)} \longrightarrow \text{Can find cut of conductance } O(\sqrt{\gamma})$$

Proof: Recall that

$$P^{(t)} = e^{-\tau Q^{(t)}} \quad \tau = \log n / \gamma \quad \Psi(P, V) = \sum_{i \in V} \|P e_i - \vec{1}/n\|^2$$

Use the definition of τ . The spectrum of $P^{(t)}$ implies that

$$\underbrace{\sum_{ij \in E} \|P^{(t)} e_i - P^{(t)} e_j\|^2}_{\text{EDGE LENGTH}} \cdot \underbrace{O(\gamma) \cdot \Psi(P^{(t)}, V)}_{\text{TOTAL VARIANCE}}$$

Hence, by a random projection of the embedding $\{P e_i\}$, followed by a sweep cut, we can recover the required cut.

SDP ROUNDING TECHNIQUE

Theorems for Our Algorithm

THEOREM 2: (WALKS HAVE MIXED)

$$\Psi(P^{(t)}, V) \cdot \frac{1}{\text{poly}(n)} \longrightarrow \text{No } \Omega(b)\text{-balanced cut of conductance } O(\gamma)$$

Theorems for Our Algorithm

THEOREM 2: (WALKS HAVE MIXED)

$$\Psi(P^{(t)}, V) \cdot \frac{1}{\text{poly}(n)} \longrightarrow \text{No } \Omega(b)\text{-balanced cut of conductance } O(\gamma)$$

Proof: Consider $S = \cup S_i$. Notice that S is unbalanced.

Assumption is equivalent to

$$L(K_V) \bullet e^{-\tau L - O(\log n)} \sum_{i \in S} L(S_i) \cdot \frac{1}{\text{poly}(n)}.$$

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By taking logs,

$$L + O(\gamma) \sum_{i \in S} L(S_i) \succeq \Omega(\gamma) L(K_V). \quad \text{SDP DUAL CERTIFICATE}$$

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$$L + O(\gamma) \sum_{i \in S} L(S_i) \succeq \Omega(\gamma) L(K_V). \quad \text{SDP DUAL CERTIFICATE}$$

This is a certificate that no $\Omega(1)$ -balanced cut of conductance $O(\gamma)$ exists, as evaluating the quadratic form for a vector representing a balanced cut U yields

$$\phi(U) \geq \Omega(\gamma) - \frac{\text{vol}(S)}{\text{vol}(U)} O(\gamma) \geq \Omega(\gamma)$$

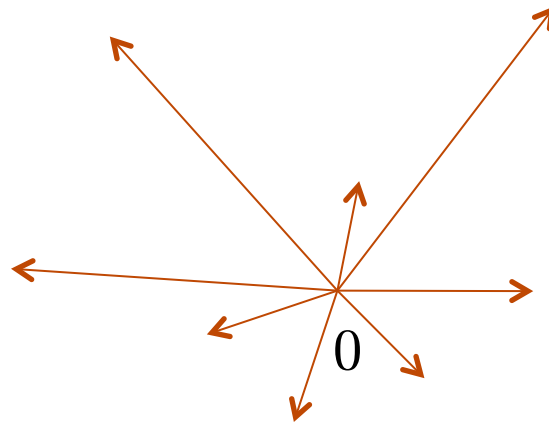
as long as S is sufficiently unbalanced.

SDP Interpretation

$$\mathbb{E}_{\{i,j\} \in E_G} \|v_i - v_j\|^2 \cdot \gamma, \quad \text{SHORT EDGES}$$

$$\mathbb{E}_{\{i,j\} \in V \times V} \|v_i - v_j\|^2 = \frac{1}{2m}, \quad \text{FIXED VARIANCE}$$

$$\forall i \in V \quad \mathbb{E}_{j \in V} \|v_i - v_j\|^2 \cdot \frac{1}{b} \cdot \frac{1}{2m}. \quad \text{LENGTH OF STAR EDGES}$$



SDP Interpretation

$$\mathbb{E}_{\{i,j\} \in E_G} \|v_i - v_j\|^2 \leq \gamma,$$

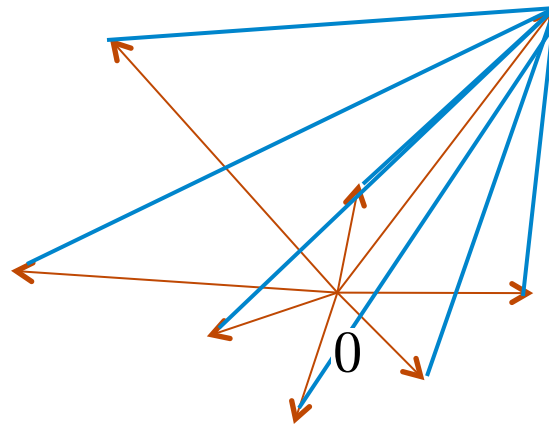
SHORT EDGES

$$\mathbb{E}_{\{i,j\} \in V \times V} \|v_i - v_j\|^2 = \frac{1}{2m},$$

FIXED VARIANCE

$$\forall i \in V \quad \mathbb{E}_{j \in V} \|v_i - v_j\|^2 = \frac{1}{b} \cdot \frac{1}{2m}.$$

**LENGTH OF
STAR
EDGES**



SHORT RADIUS

Background: Heat-Kernel Random Walk

For simplicity, take G to be **d-regular**.

- The Heat-Kernel Random Walk is a **Continuous-Time Markov Chain** over V , modeling the **diffusion of heat** along the edges of G .

- Transitions take place in **continuous time** t , with an **exponential distribution**.

$$\frac{\partial p(t)}{\partial t} = -L \frac{p(t)}{d}$$

$$p(t) = e^{-\frac{t}{d}L} p(0) =: \boxed{H_G^t} p(0)$$

Notation

- The Heat Kernel can be interpreted as **Poisson distribution** over number of steps of the natural random walk $W \sim \Delta D^{-1}$.

$$e^{-\frac{t}{d}L} = e^{-t} \sum_{k=1}^{\infty} \frac{t^k}{k!} W^k$$

- In practice, can replace **Heat-Kernel** with **natural random walk** W^t