Algorithm Design and Analysis



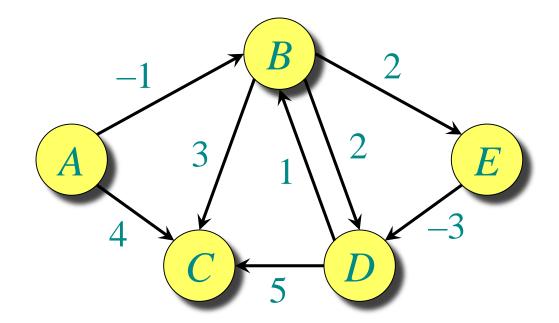
LECTURES 16 Dynamic Programming

- Shortest Paths: Bellman-Ford
- Detecting negative cycles
 Network Flow
 Duality of Max Flow and Min Cut

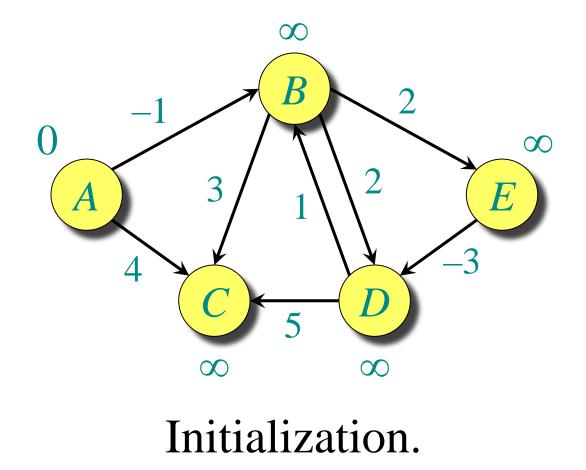
Sofya Raskhodnikova

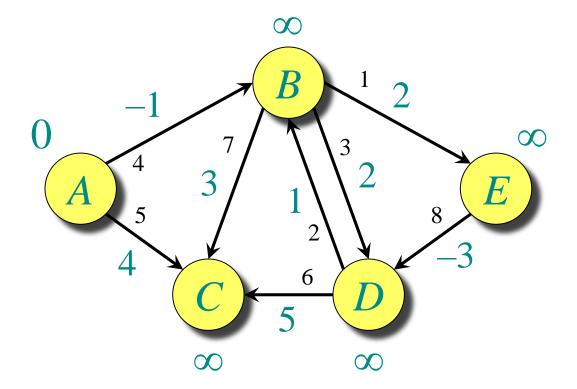
Belman-Ford: Efficient Implementation

```
Bellman-Ford-Shortest-Path(G, s, t) {
   foreach node v \in V {
       M[v] \leftarrow \infty
       successor[v] \leftarrow \phi
   }
   M[t] = 0
   for i = 1 to n-1 {
       foreach node w \in V {
       if (M[w] has been updated in previous iteration) {
          foreach node v such that (v, w) \in E {
              if (M[v] > M[w] + c_{vw}) {
                  M[v] \leftarrow M[w] + c_{vw}
                  successor[v] \leftarrow w
              }
       If no M[w] value changed in iteration i, stop.
   }
}
```

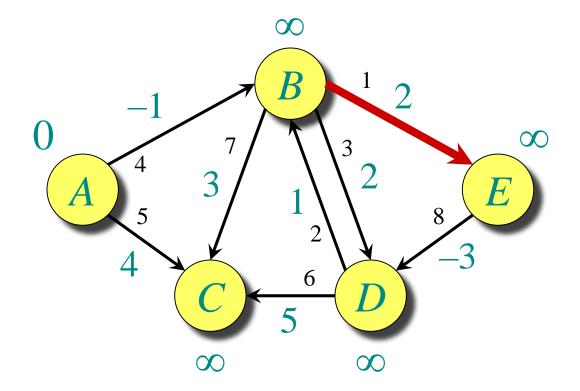


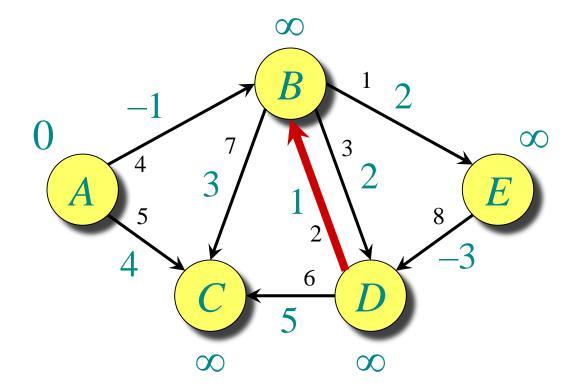
The demonstration is for a sligtly different version of the algorithm (see CLRS) that computes distances from the sourse node rather than distances to the destination node.

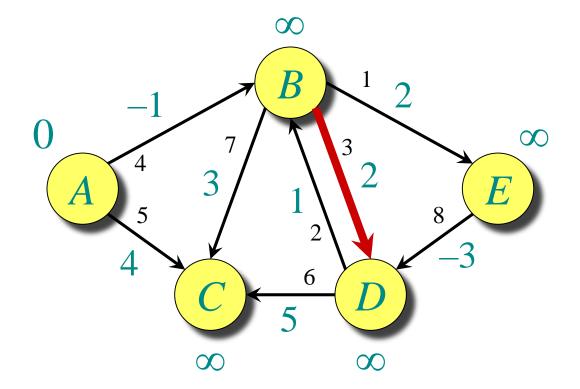


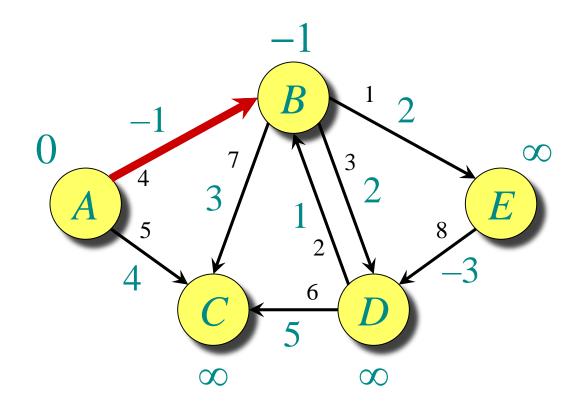


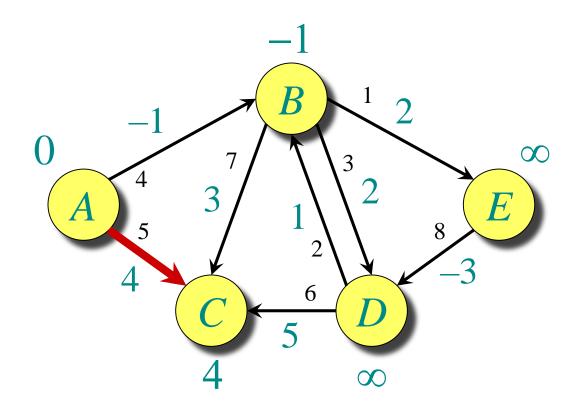
Order of edge relaxation.

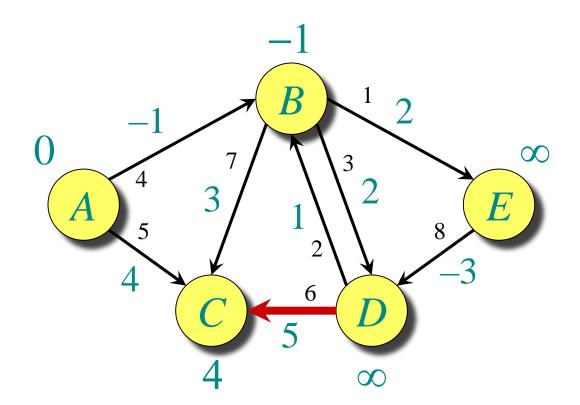


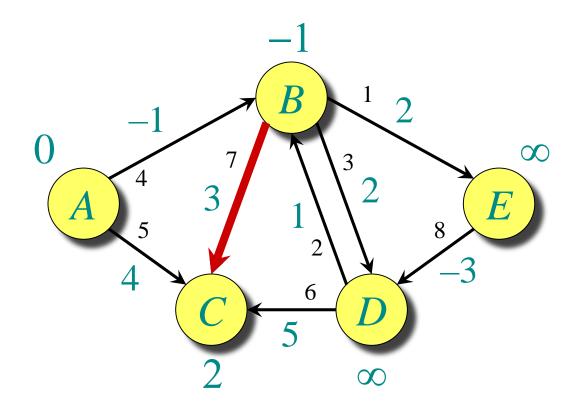


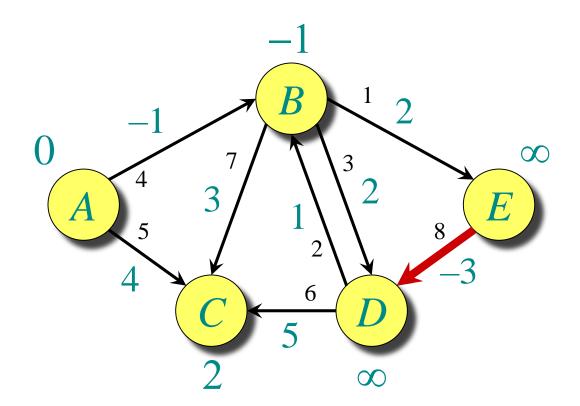


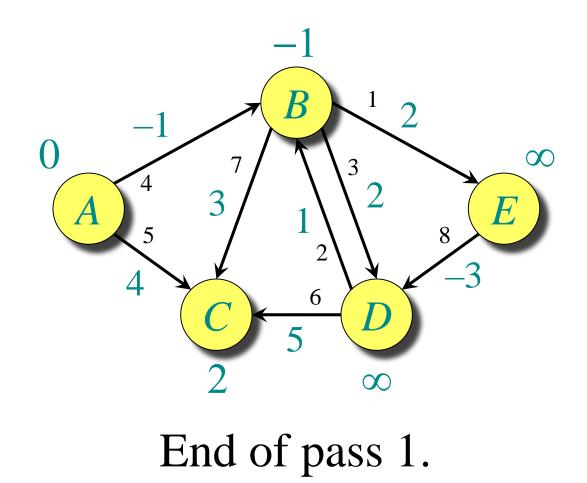


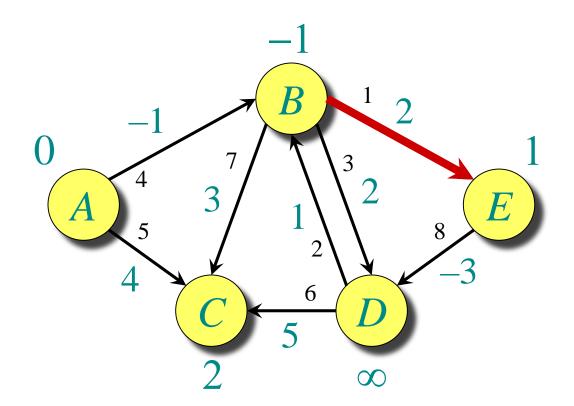


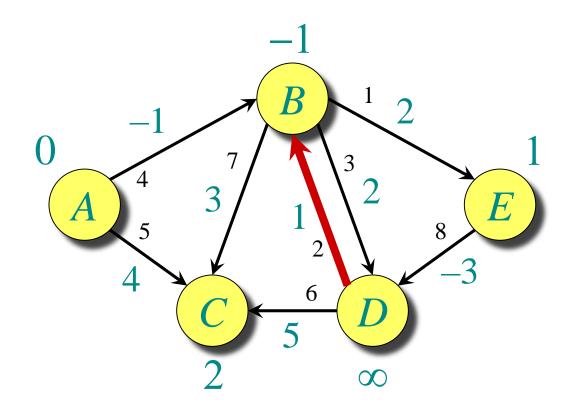


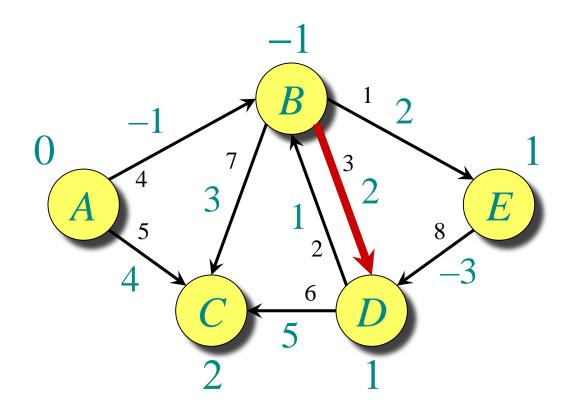


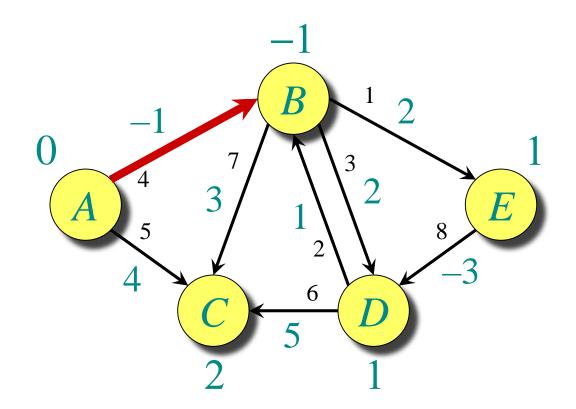


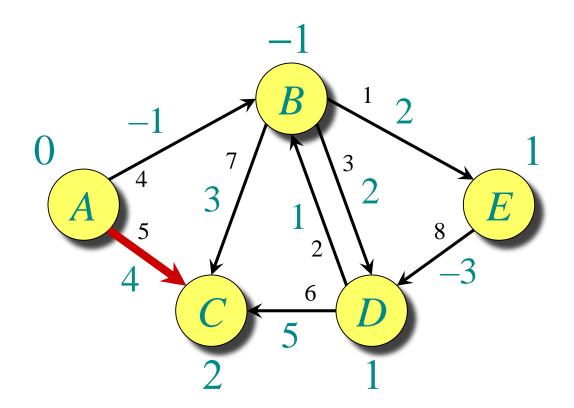


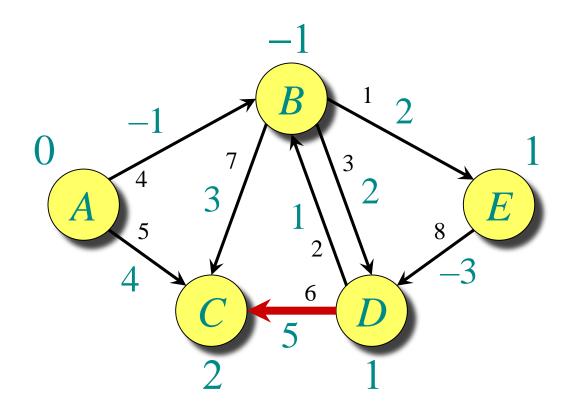


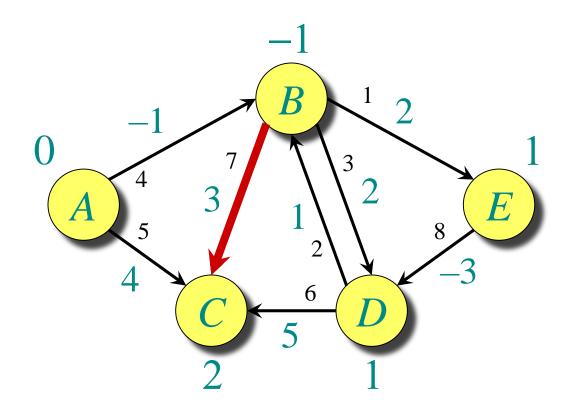


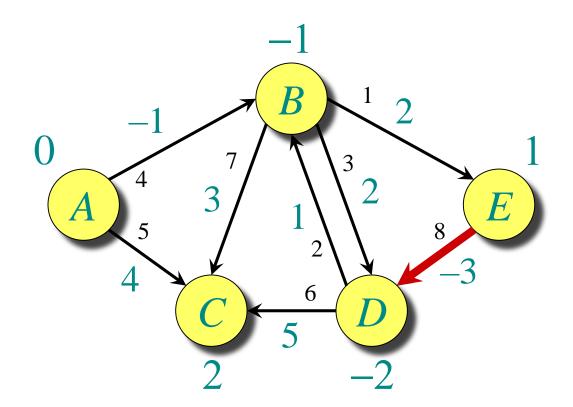


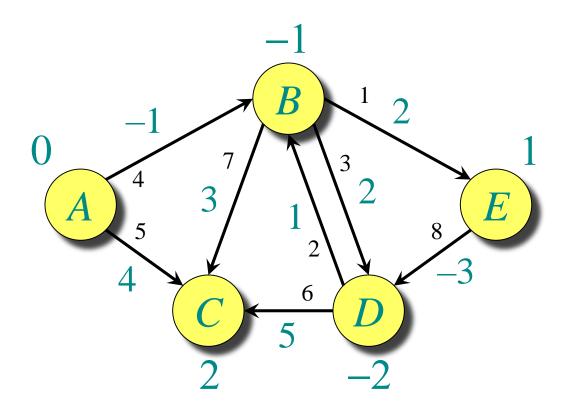












End of pass 2 (and 3 and 4).

10/19/2016

S. Raskhodnikova; based on slides by E. Demaine, C. Leiserson, A. Smith, K. Wayne L16.23

Distance Vector Protocol

Distance Vector Protocol

Communication network.

- Nodes \approx routers.
- Edges \approx direct communication link.
- Cost of edge ≈ delay on link. ← naturally nonnegative, but Bellman-Ford used anyway!

Dijkstra's algorithm. Requires global information of network.

Bellman-Ford. Uses only local knowledge of neighboring nodes.

Synchronization. We don't expect routers to run in lockstep. The order in which each foreach loop executes is not important. Moreover, algorithm still converges even if updates are asynchronous.

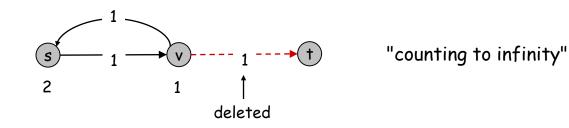
Distance Vector Protocol

Distance vector protocol.

- Each router maintains a vector of shortest path lengths to every other node (distances) and the first hop on each path (directions).
- Algorithm: each router performs n separate computations, one for each potential destination node.
- "Routing by rumor."

Ex. RIP, Xerox XNS RIP, Novell's IPX RIP, Cisco's IGRP, DEC's DNA Phase IV, AppleTalk's RTMP.

Caveat. Edge costs may change during algorithm (or fail completely).



Path Vector Protocols

Link state routing.

not just the distance and first hop

- Each router also stores the entire path.
- Based on Dijkstra's algorithm.
- Avoids "counting-to-infinity" problem and related difficulties.
- Requires significantly more storage.

Ex. Border Gateway Protocol (BGP), Open Shortest Path First (OSPF).

Detecting negative cycles in a graph

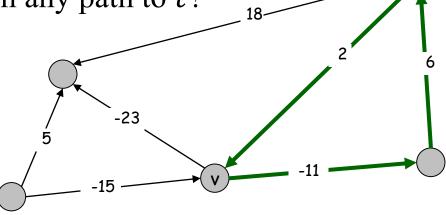
Detecting Negative Cycles

Bellman-Ford is guaranteed to work if there are no negative-cost cycles.

How can we tell if a negative-cost cycle exists?

- We could pick a destination vertex *t* and check whether cost estimates in Bellman-Ford converge
- What is wrong with it?

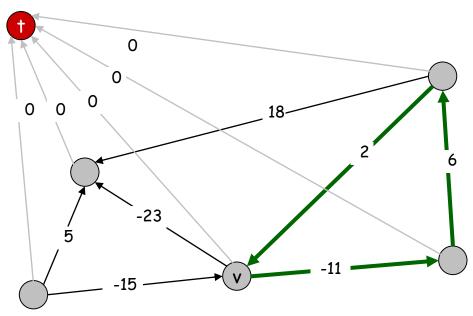
- What if the cycle isn't on any path to t?



Detecting Negative Cycles

Theorem. Can detect a negative cost cycle in O(mn) time.

- Add new node *t* and connect all nodes to *t* with 0-cost edge.
- Check if OPT(n, v) = OPT(n 1, v) for all nodes v.
 - if yes, then no negative cycles
 - if no, then extract cycle from shortest path from v to t



Detecting Negative Cycles

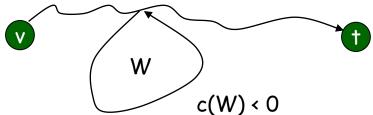
Lemma. If OPT(n, v) = OPT(n - 1, v) for all v, then no negative cycles are connected to t.

Proof. If OPT(n, v) = OPT(n - 1, v) for all v, then distance estimates won't change again even with many executions of the for loop. So there are no negative cost cycles on any path from v to t, for all v.

Lemma. If OPT(n, v) < OPT(n - 1, v) for some node v, then some path from v to t contains a cycle W of negative cost.

Proof. (by contradiction)

- Since OPT(n, v) < OPT(n 1, v), current path P from v to t has n edges.
- By pigeonhole principle, P must contain a directed cycle W.
- Deleting W yields a v-t path with $< n \text{ edges} \Rightarrow W$ has negative cost.

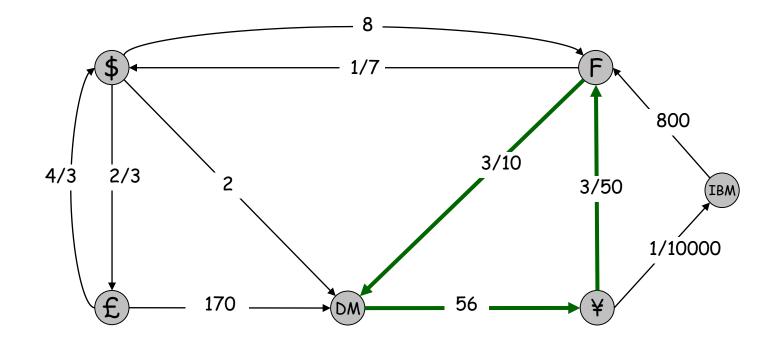


S. Raskhodnikova; based on slides by E. Demaine, C. Leiserson, A. Smith, K. Wayne L16.31

Detecting Negative Cycles: Application

Currency conversion. Given n currencies and exchange rates between pairs of currencies, is there an arbitrage opportunity?

Remark. Fastest algorithm very valuable! Question. What should we use as edge costs?



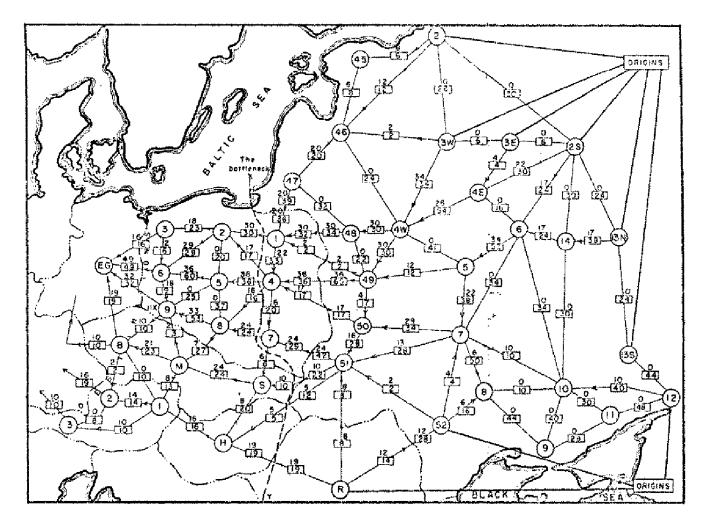
Detecting Negative Cycles: Summary

Bellman-Ford. O(mn) time, O(m + n) space.

- Run Bellman-Ford for n iterations (instead of n-1).
- Upon termination, Bellman-Ford successor variables trace a negative cycle if one exists.
- See p. 304 for improved version and early termination rule.

Network Flow and Linear Programming

Soviet Rail Network, 1955



Reference: On the history of the transportation and maximum flow problems. Alexander Schrijver in Math Programming, 91: 3, 2002.

Maximum Flow and Minimum Cut

Max flow and min cut.

- Two very rich algorithmic problems.
- Cornerstone problems in combinatorial optimization.
- Beautiful mathematical duality.

Nontrivial applications / reductions.

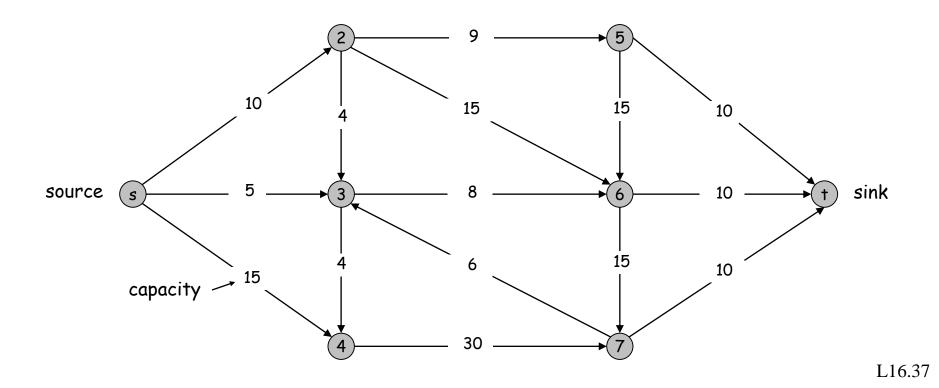
- Data mining.
- Open-pit mining.
- Project selection.
- Airline scheduling.
- Bipartite matching.
- Baseball elimination.
- Image segmentation.
- Network connectivity.

- Network reliability.
- Distributed computing.
- Egalitarian stable matching.
- Security of statistical data.
- Network intrusion detection.
- Multi-camera scene reconstruction.
- Many many more . . .

Minimum Cut Problem

Flow network.

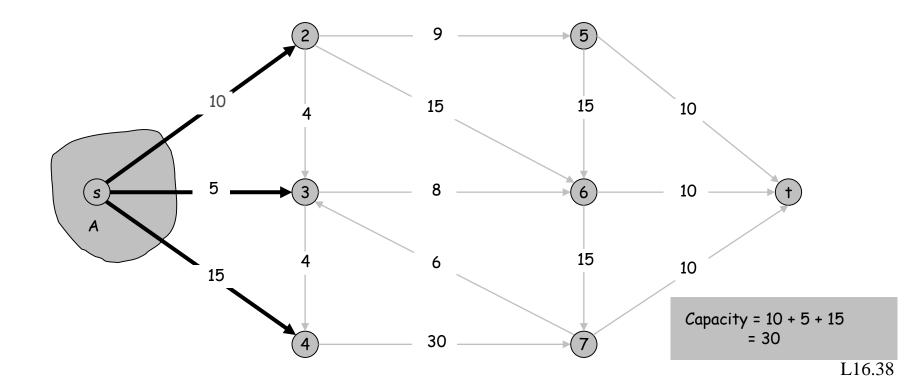
- Abstraction for material flowing through the edges.
- G = (V, E) = directed graph, no parallel edges.
- Two distinguished nodes: s = source, t = sink.
- c(e) = capacity of edge e.



Cuts

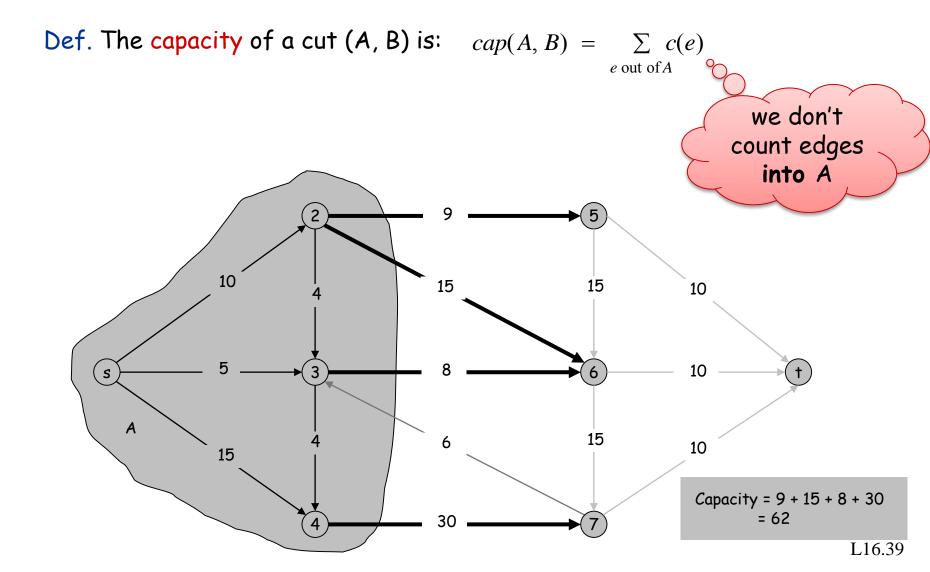
Def. An s-t cut is a partition (A, B) of V with $s \in A$ and $t \in B$.

Def. The capacity of a cut (A, B) is: $cap(A, B) = \sum_{e \text{ out of } A} c(e)$



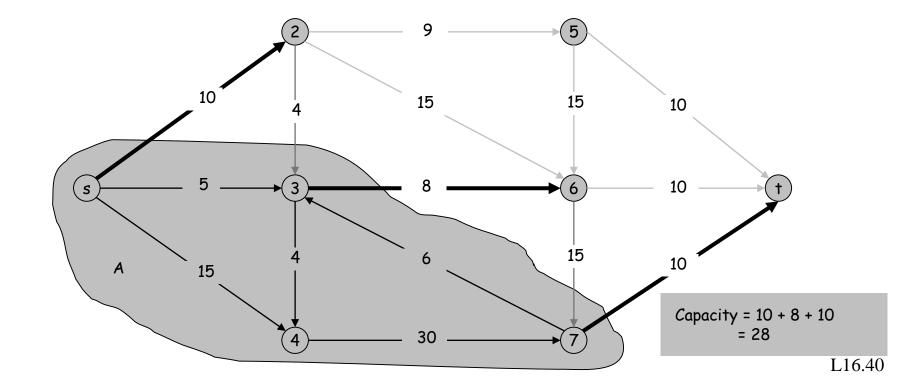
Cuts

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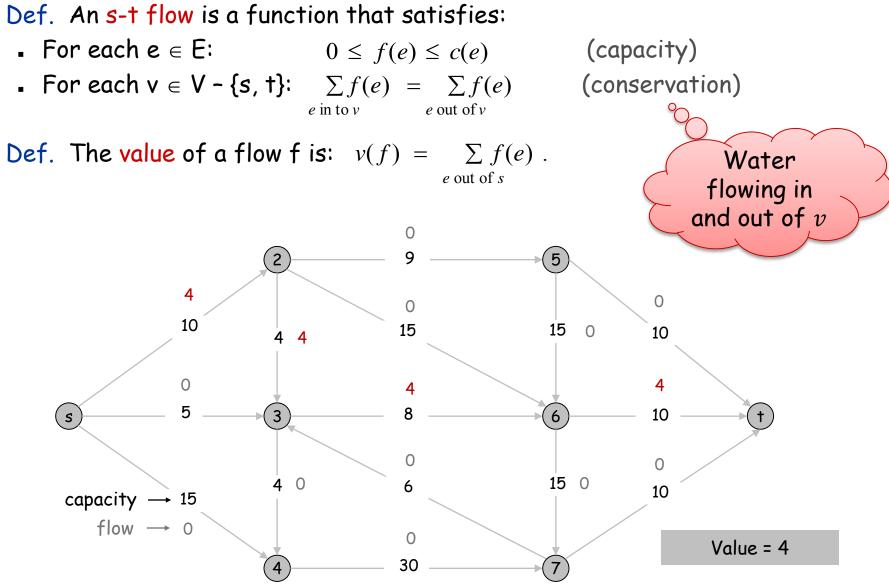


Minimum Cut Problem

Min s-t cut problem. Find an s-t cut of minimum capacity.



Flows



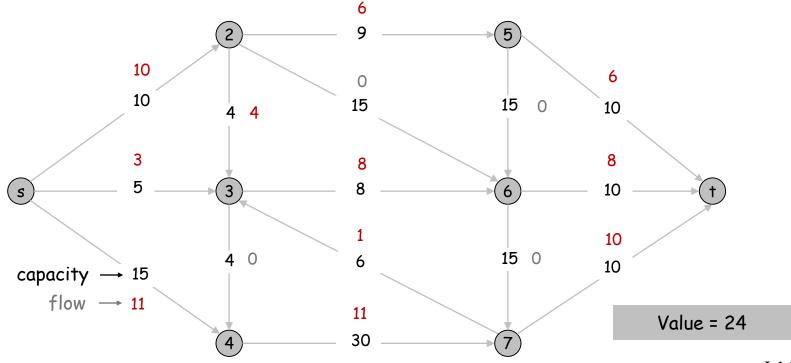
Flows

Def. An s-t flow is a function that satisfies:

- For each $e \in E$: $0 \le f(e) \le c(e)$
- For each $v \in V \{s, t\}$: $\sum_{e \text{ in to } v} f(e) = \sum_{e \text{ out of } v} f(e)$

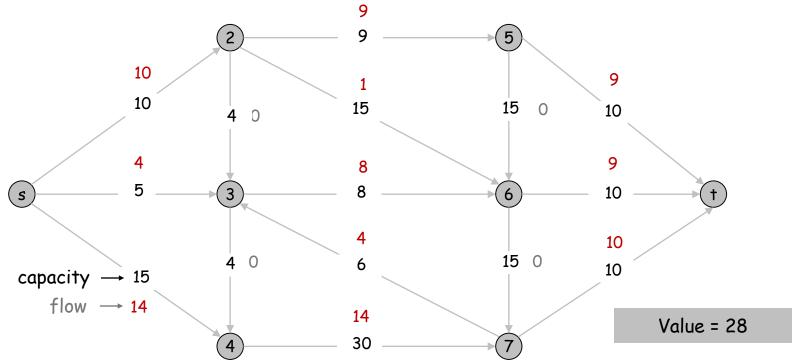
(capacity) (conservation)

Def. The value of a flow f is: $v(f) = \sum_{e \text{ out of } s} f(e)$.



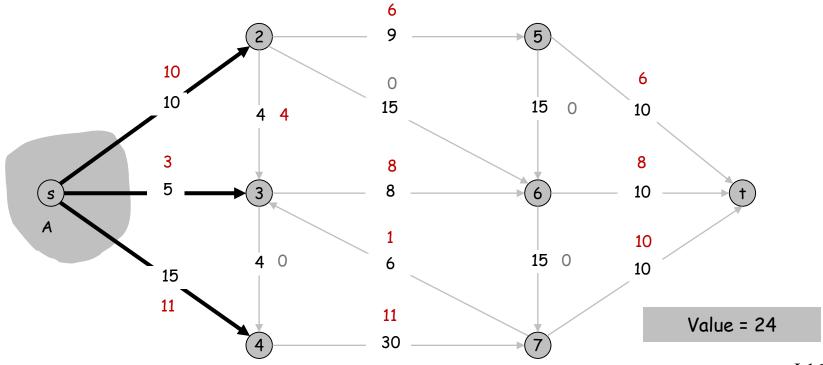
Maximum Flow Problem

Max flow problem. Find s-t flow of maximum value.



Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then the net flow sent across the cut is equal to the amount leaving s.

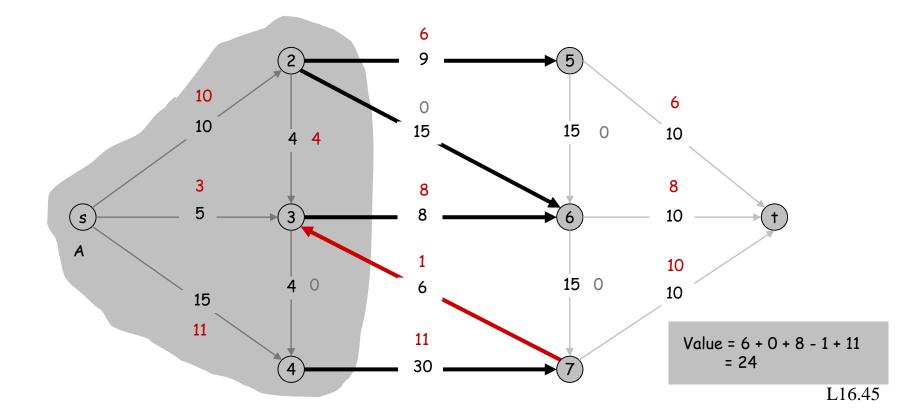
 $\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$



L16.44

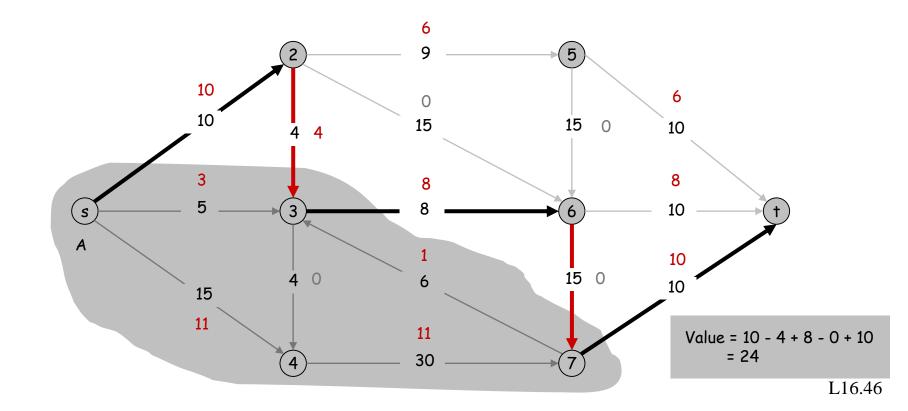
Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then the net flow sent across the cut is equal to the amount leaving s.

 $\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$



Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then the net flow sent across the cut is equal to the amount leaving s.

 $\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f)$



Flow value lemma. Let f be any flow, and let (A, B) be any s-t cut. Then

 $\sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e) = v(f).$

Proof.
$$v(f) = \sum_{e \text{ out of } s} f(e)$$

by flow conservation, all terms
$$\longrightarrow = \sum_{v \in A} \left(\sum_{e \text{ out of } v} f(e) - \sum_{e \text{ in to } v} f(e) \right)$$

$$= \sum_{e \text{ out of } A} f(e) - \sum_{e \text{ in to } A} f(e).$$

Question

Two problems

- Min Cut
- Max Flow

.How do they relate?

Weak duality. Let f be any flow, and let (A, B) be any s-t cut. Then the value of the flow is at most the capacity of the cut. **Big Optimization Idea #1:** Look for structural Cut capacity = $30 \implies$ Flow value ≤ 30 constraints, e.g. max flow \leq min-cut 9 5 10 15 15 10 5 8 10 6 + S A 15 6 10 15 Capacity = 30 30 L16.49

Weak duality. Let f be any flow. Then, for any s-t cut (A, B), $v(f) \leq \text{cap}(A, B).$

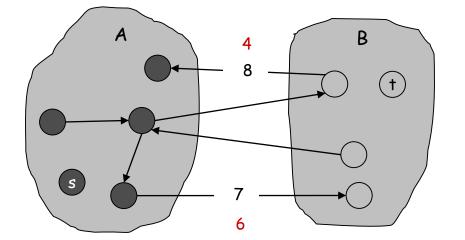
Proof.

$$v(f) = \sum_{\substack{e \text{ out of } A}} f(e) - \sum_{\substack{e \text{ in to } A}} f(e)$$

$$\leq \sum_{\substack{e \text{ out of } A}} f(e)$$

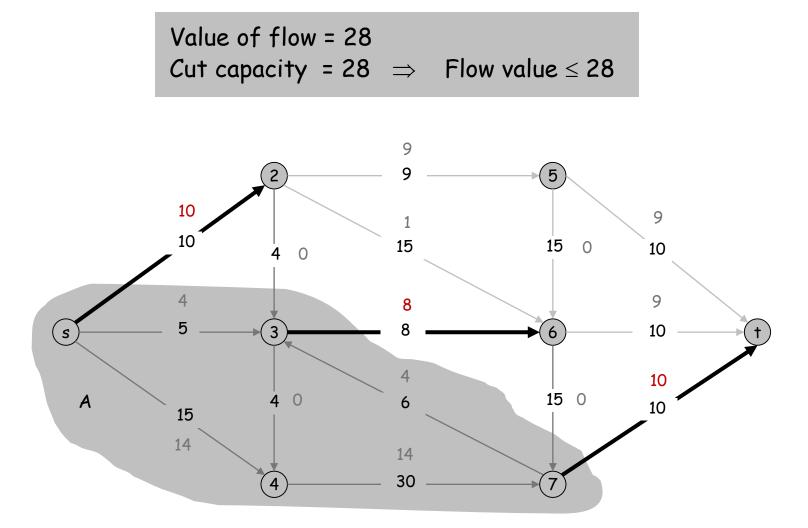
$$\leq \sum_{\substack{e \text{ out of } A}} c(e)$$

$$= \operatorname{cap}(A, B) \quad \bullet$$



Certificate of Optimality

Corollary. Let f be any flow, and let (A, B) be any cut. If v(f) = cap(A, B), then f is a max flow and (A, B) is a min cut.



Review Questions

True/False

Let G be an arbitrary flow network, with a source s, and sink t, and a positive integer capacity c_e on every edge e.

1) If f is a maximum s-t flow in G, then f saturates every edge out of s with flow (i.e., for all edges e out of s, we have $f(e) = c_e$).

2) Let (A,B) be a minimum s-t cut with respect to these capacities . If we add 1 to every capacity, then (A,B) is still a minimum s-t cut with respect to the new capacities.